Important separators and parameterized algorithms

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WORKER 2013

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April 9, 2013

Overview

Main message: Small separators in graphs have interesting extremal properties that can be exploited in combinatorial and algorithmic results.

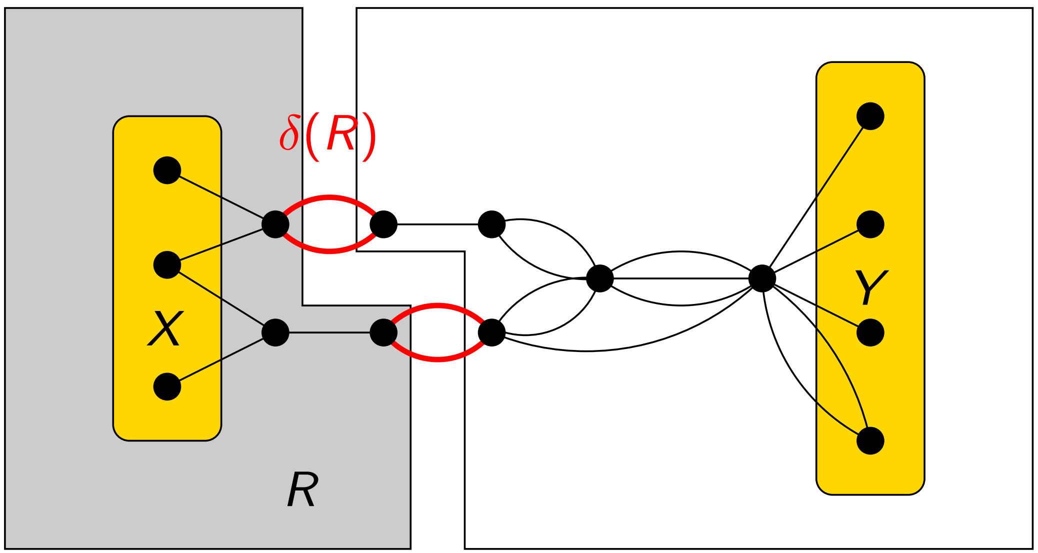
- Bounding the number of “important” separators.
- Edge/vertex versions, directed/undirected versions.
- Algorithmic applications: FPT algorithm for MULTIWAY CUT and DIRECTED FEEDBACK VERTEX SET.

Important separators

Definition: $\delta(R)$ is the set of edges with exactly one endpoint in R.

Definition: A set S of edges is an (X, Y)**-separator** if there is no $X - Y$ path in $G \setminus S$ and no proper subset of S breaks every $X - Y$ path.

Observation: Every (X, Y)-separator S can be expressed as $S = \delta(R)$ for some $X \subseteq R$ and $R \cap Y = \emptyset$.



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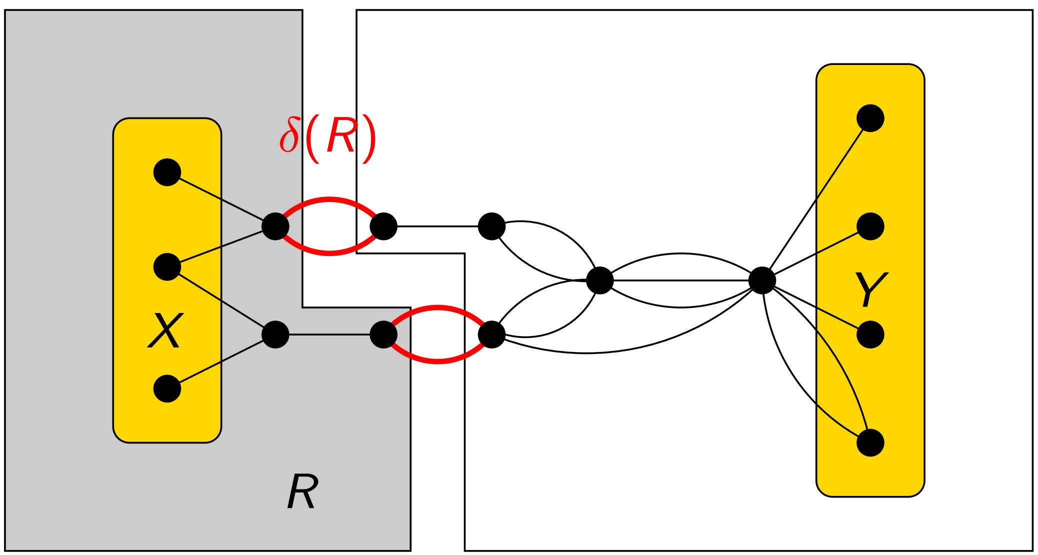
Definition: An (X, Y)-separator $\delta(R)$ is **important** if there is no (X, Y)-separator $\delta(R')$ with $R \subset R'$ and $|\delta(R')| \leq |\delta(R)|$.

Note: Can be checked in polynomial time if a separator is important.



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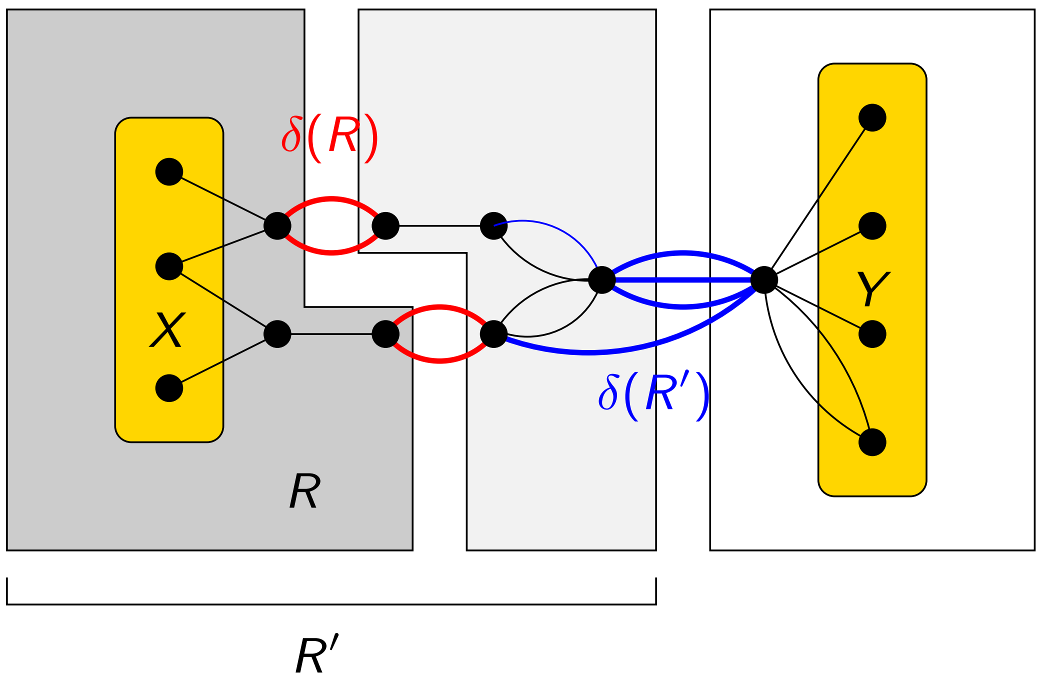

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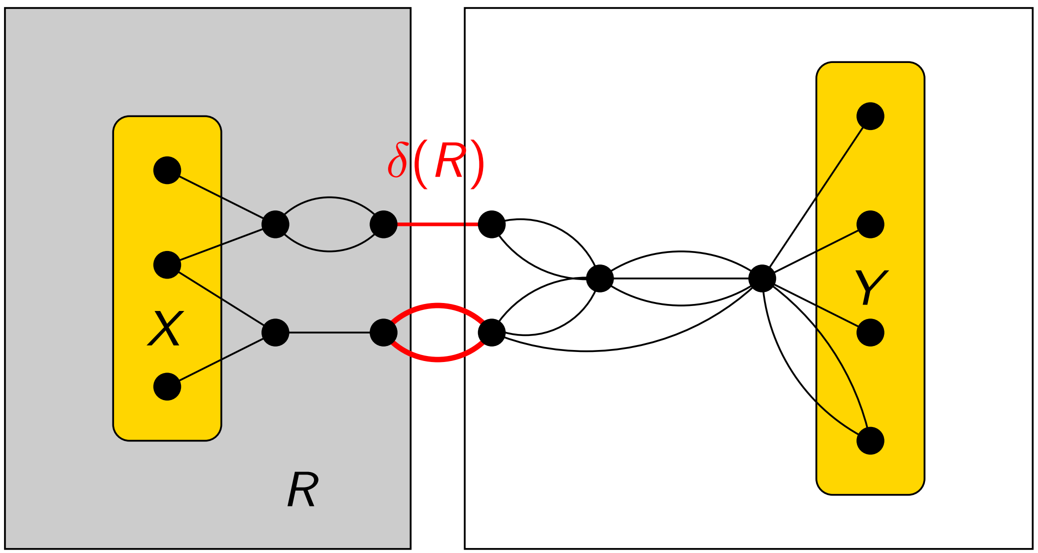
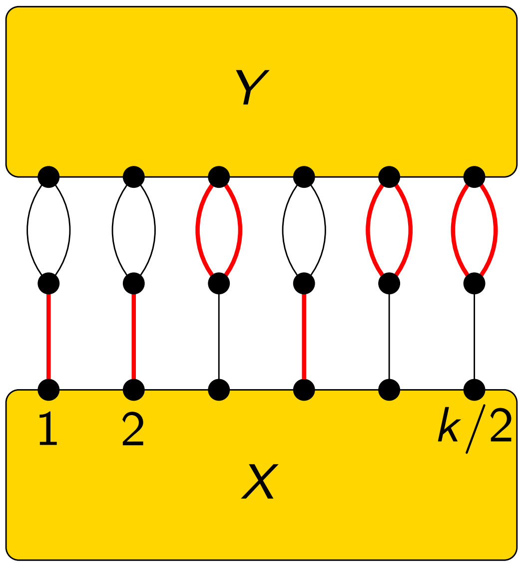


Important separators

The number of important separators can be exponentially large.

Example:



This graph has exactly $2^{k/2}$ important (X, Y)-separators of size at most k.

Theorem: There are at most 4^k important (X, Y)-separators of size at most k.
(Proof is implicit in [Chen, Liu, Lu 2007], worse bound in [M. 2004].)

Submodularity

Fact: The function δ is **submodular:** for arbitrary sets A, B,

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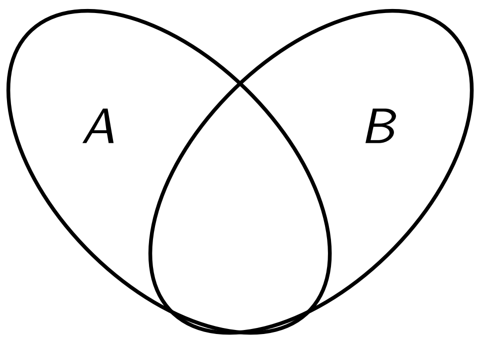

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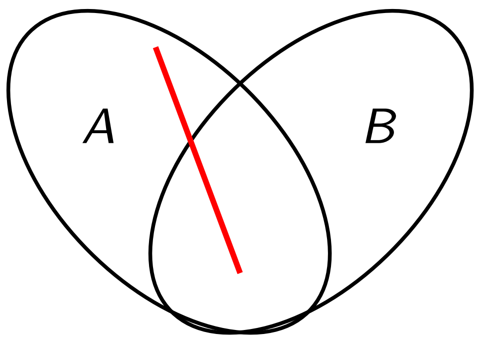

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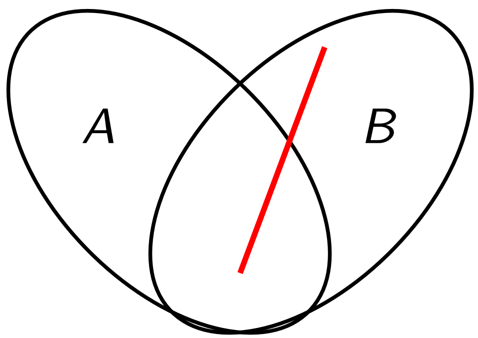

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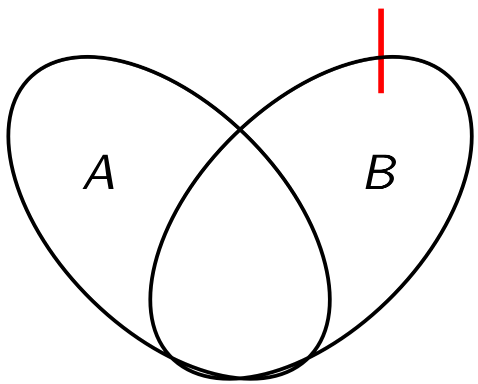

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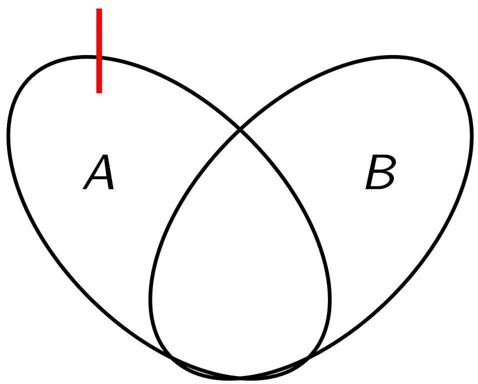

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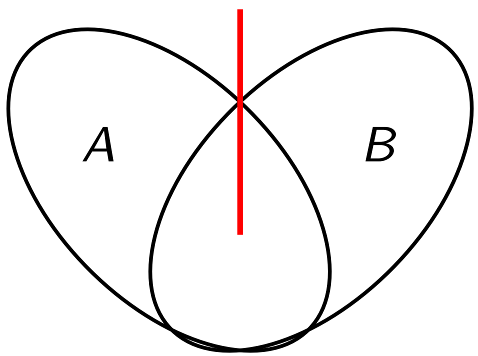

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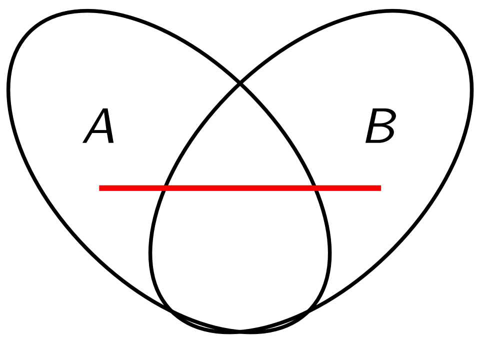

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Consequence: Let λ be the minimum (X, Y)-separator size. There is a unique maximal $R_{\max} \supseteq X$ such that $\delta(R_{\max})$ is an (X, Y)-separator of size λ.

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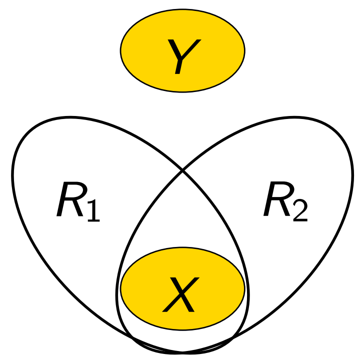
Proof: Let $R_1, R_2 \supseteq X$ be two sets such that $\delta(R_1), \delta(R_2)$ are (X, Y)-separators of size λ.

$$\underbrace{|\delta(R_1)|}_{\lambda} + \underbrace{|\delta(R_2)|}_{\lambda} \geq \underbrace{|\delta(R_1 \cap R_2)|}_{\geq \lambda} + |\delta(R_1 \cup R_2)|$$

$$\Rightarrow |\delta(R_1 \cup R_2)| \leq \lambda$$



Note: Analogous result holds for a unique minimal $R_{\min}$.

Important separators

Theorem: There are at most 4^k important (X, Y)-separators of size at most k.

Proof: Let λ be the minimum (X, Y)-separator size and let $\delta(R_{\max})$ be the unique important separator of size λ such that $R_{\max}$ is maximal.

First we show that $R_{\max} \subseteq R$ for every important separator $\delta(R)$.

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By the submodularity of δ:

$$\underset{\lambda}{|\delta(R_{\max})|} + |\delta(R)| \geq \underset{\geq \lambda}{|\delta(R_{\max} \cap R)|} + |\delta(R_{\max} \cup R)|$$

$$\Downarrow$$

$$|\delta(R_{\max} \cup R)| \leq |\delta(R)|$$

$$\Downarrow$$

If $R \neq R_{\max} \cup R$, then $\delta(R)$ is not important.

Thus the important (X, Y)- and $(R_{\max}, Y)$-separators are the same.
$\Rightarrow$ We can assume $X = R_{\max}$.

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Theorem: There are at most 4^k important (X, Y)-separators of size at most k.

Search tree algorithm for enumerating all these separators:

An (arbitrary) edge uv leaving $X = R_{\max}$ is either in the separator or not.

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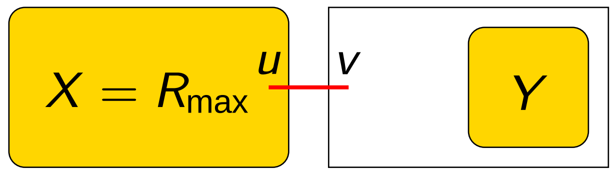

Branch 2: If $uv \notin S$, then S is an important $(X \cup v, Y)$-separator of size at most k in G.

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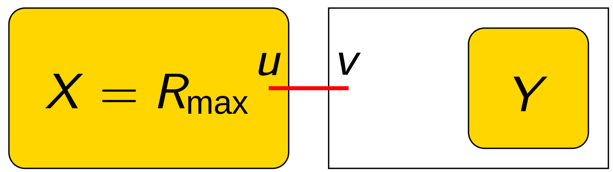
$\Rightarrow$ k decreases by one, λ decreases by at most 1.



Branch 2: If $uv \notin S$, then S is an important $(X \cup v, Y)$-separator of size at most k in G.

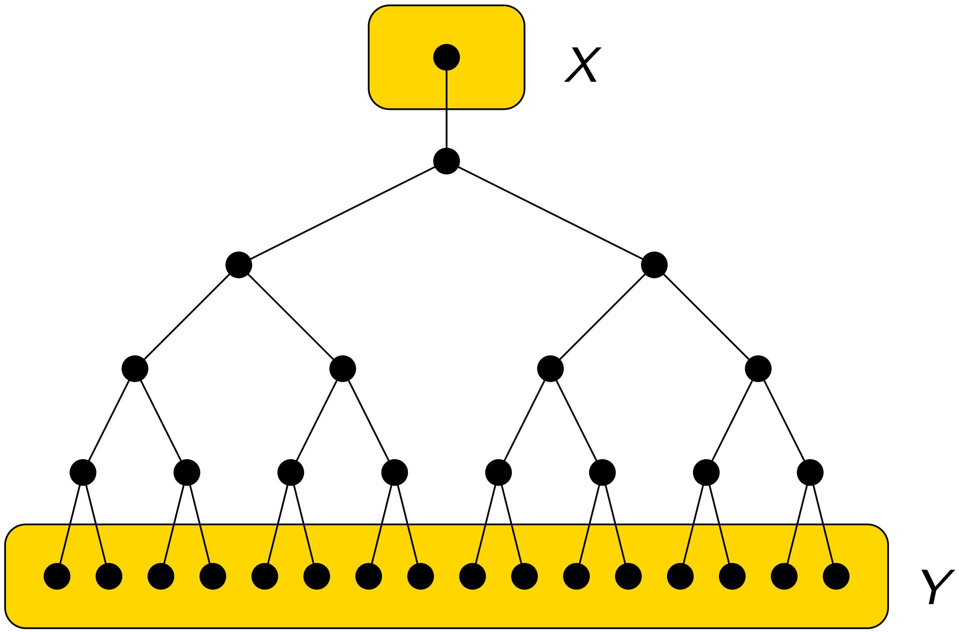
$\Rightarrow$ k remains the same, λ increases by 1.

The measure $2k - \lambda$ decreases in each step.

$\Rightarrow$ Height of the search tree $\leq 2k \Rightarrow \leq 2^{2k}$ important separators of size $\leq k$.

Important separators

Example: The bound 4^k is essentially tight.



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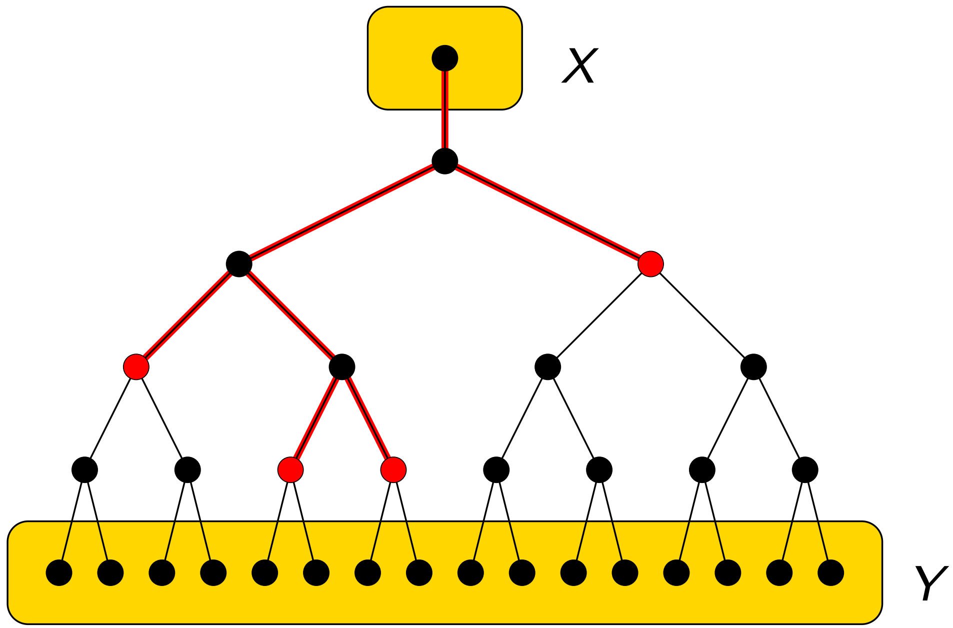

Any subtree with k leaves gives an important (X, Y)-separator of size k.

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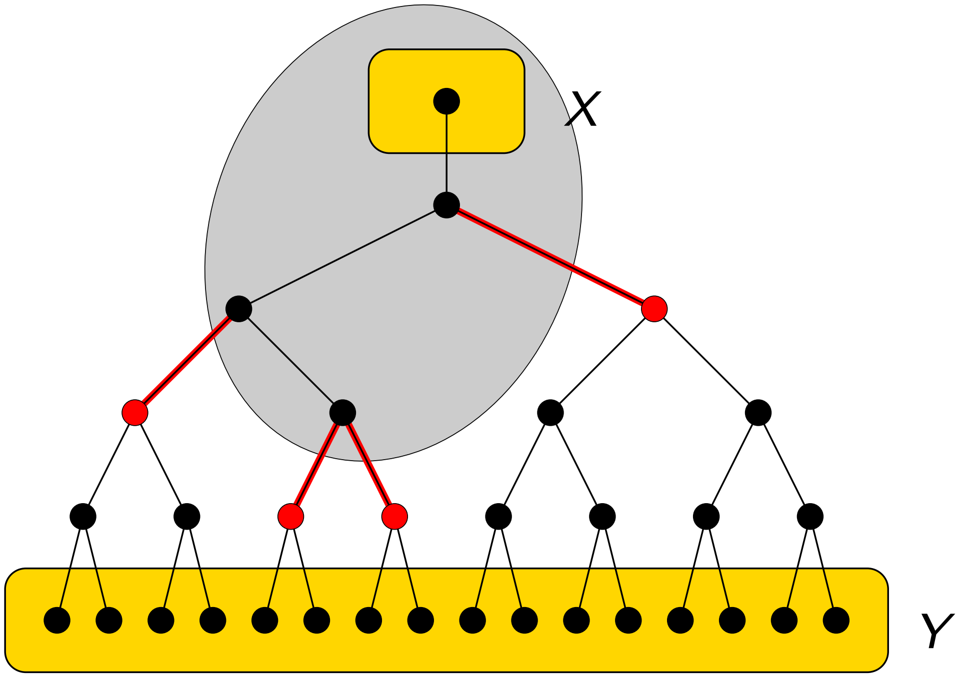

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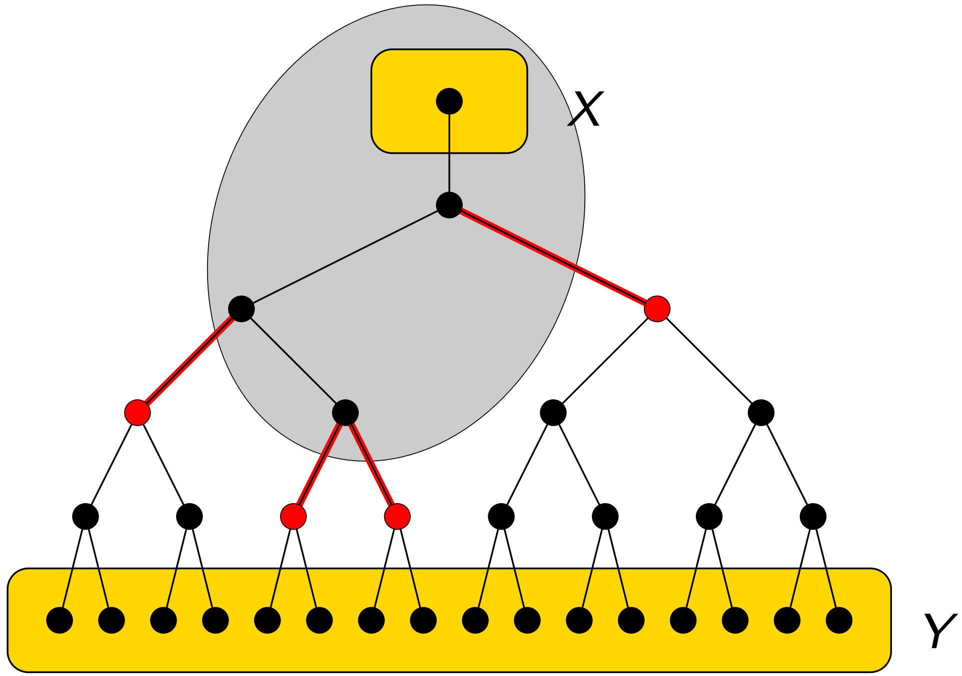

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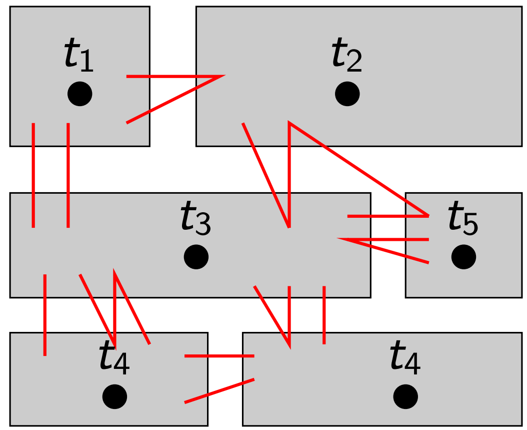
The number of subtrees with k leaves is the Catalan number

$$C_{k-1} = \frac{1}{k}\binom{2k-2}{k-1} \geq 4^k/\mathrm{poly}(k).$$

MULTIWAY CUT

Definition: A **multiway cut** of a set of terminals T is a set S of edges such that each component of $G \setminus S$ contains at most one vertex of T.

MULTIWAY CUT
Input: Graph G, set T of vertices, integer k
Find: A **multiway cut** S of at most k edges.



Polynomial for $|T| = 2$, but NP-hard for any fixed $|T| \geq 3$ [Dalhaus et al. 1994].

Trivial to solve in polynomial time for fixed k (in time $n^{O(k)}$).

Theorem: MULTIWAY CUT can be solved in time $4^k \cdot n^{O(1)}$, i.e., it is fixed-parameter tractable (FPT) parameterized by the size k of the solution.

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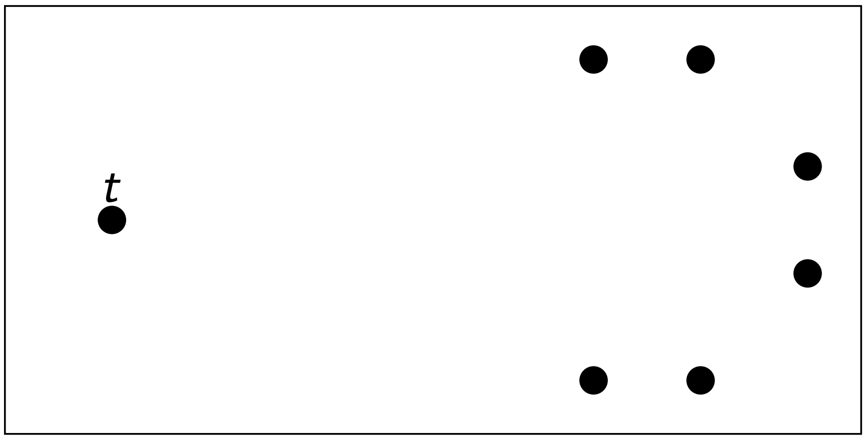
Intuition: Consider a $t \in T$. A subset of the solution S is a $(t, T \setminus t)$-separator.



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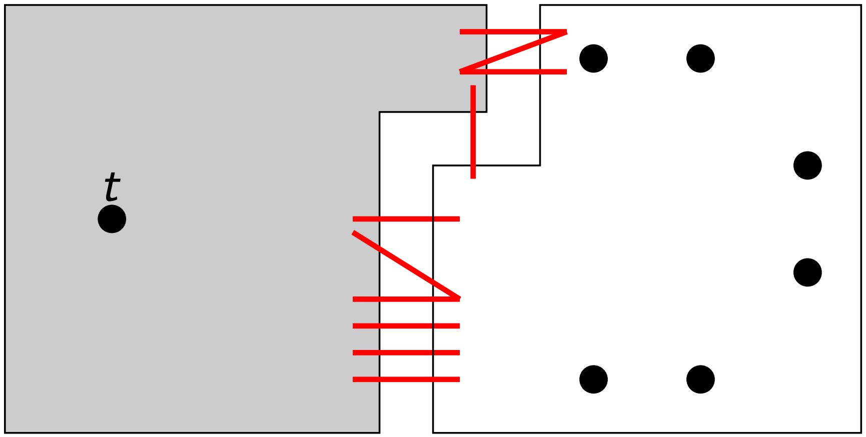

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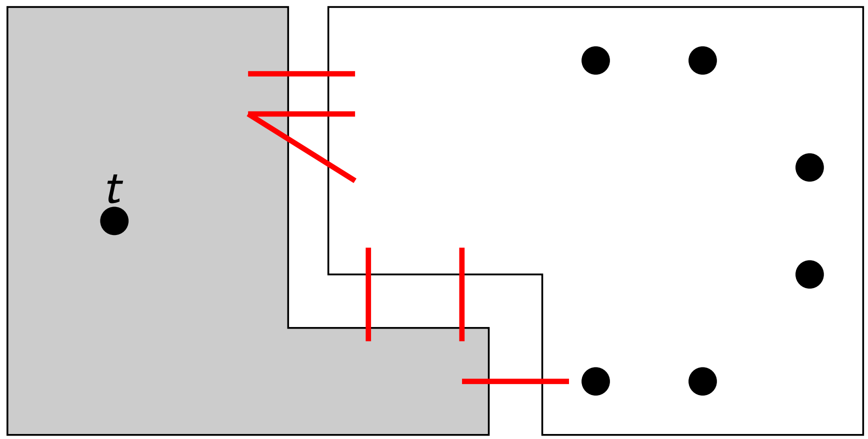

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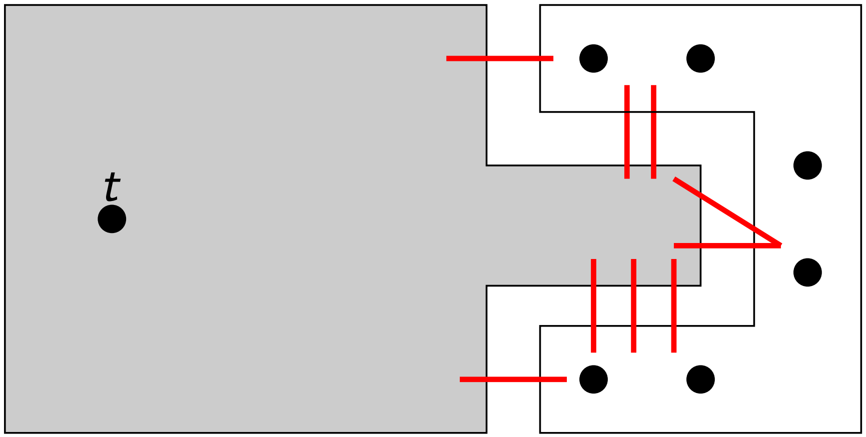

There are many such separators.

But a separator farther from t and closer to $T \setminus t$ seems to be more useful.

MULTIWAY CUT *and important separators*

Pushing Lemma: Let $t \in T$. The MULTIWAY CUT problem has a solution S that contains an important $(t, T \setminus t)$-separator.

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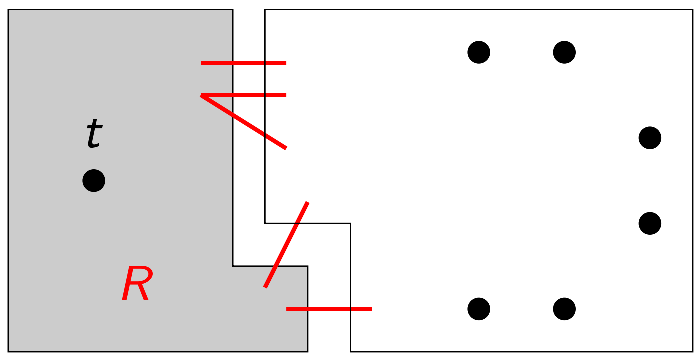

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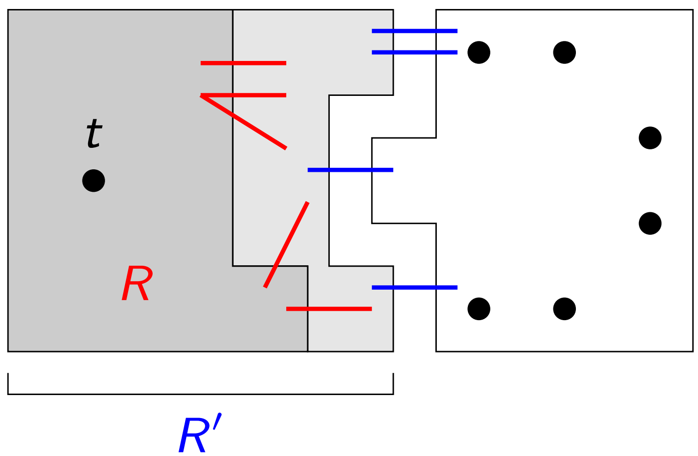

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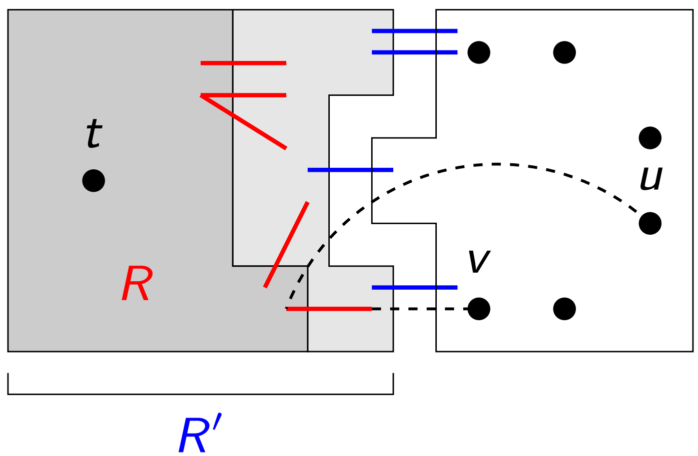

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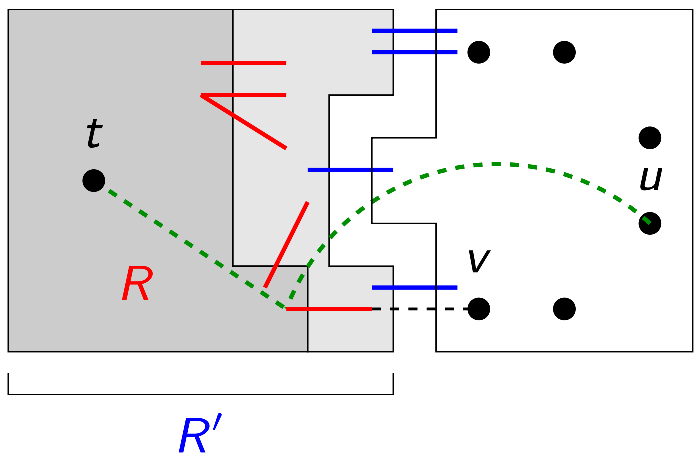

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Algorithm for Multiway Cut

1. If every vertex of T is in a different component, then we are done.
2. Let $t \in T$ be a vertex that is not separated from every $T \setminus t$.
3. Branch on a choice of an important $(t, T \setminus t)$ separator S of size at most k.
4. Set $G := G \setminus S$ and $k := k - |S|$.
5. Go to step 1.

We branch into at most 4^k directions at most k times.

(Better analysis gives 4^k bound on the size of the search tree.)

MULTICUT

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Input: Graph G, pairs $(s_1, t_1), \ldots, (s_\ell, t_\ell)$, integer k

Find: A set S of edges such that $G \setminus S$ has no s_i-t_i path for any i.

Theorem: MULTICUT can be solved in time $f(k, \ell) \cdot n^{O(1)}$ (FPT parameterized by combined parameters k and ℓ).

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Proof: The solution partitions $\{s_1, t_1, \ldots, s_\ell, t_\ell\}$ into components. Guess this partition, contract the vertices in a class, and solve MULTIWAY CUT.

Theorem: [Bousquet, Daligault, Thomassé 2011] [M., Razgon 2011] MULTICUT is FPT parameterized by the size k of the solution.

Directed graphs

Definition: $\vec{\delta}(R)$ is the set of edges leaving R.

Observation: Every inclusionwise-minimal directed (X,Y)-separator S can be expressed as $S = \vec{\delta}(R)$ for some $X \subseteq R$ and $R \cap Y = \emptyset$.

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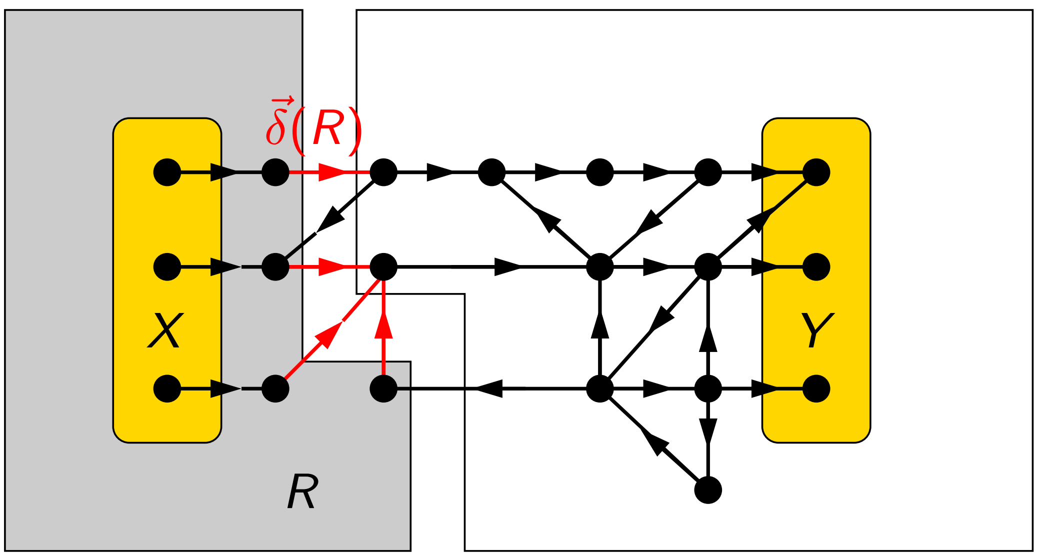

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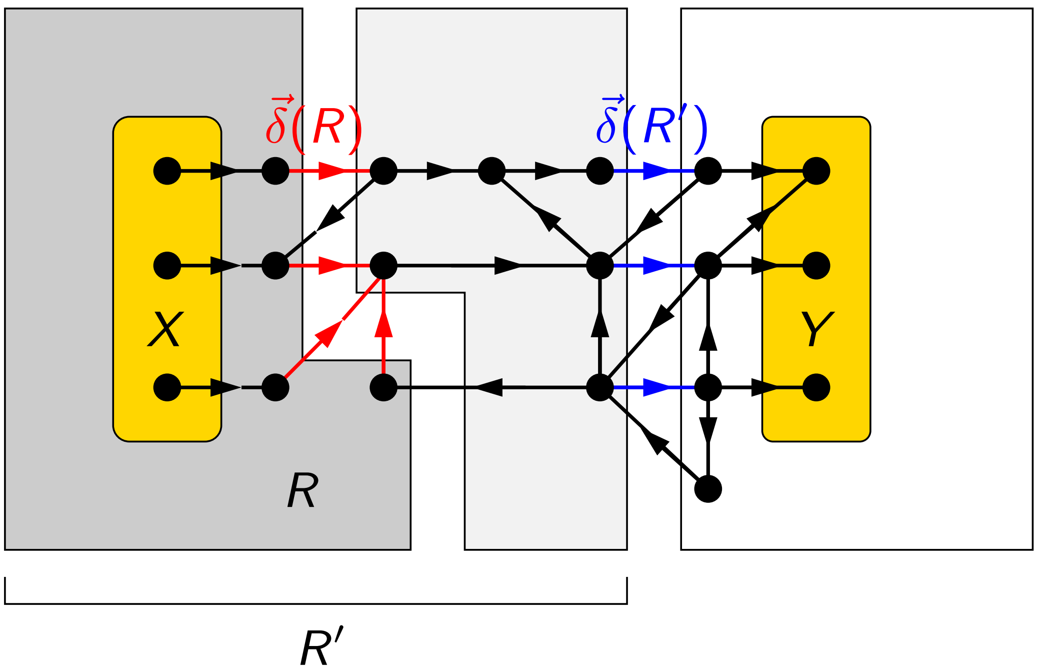

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The proof for the undirected case goes through for the directed case:

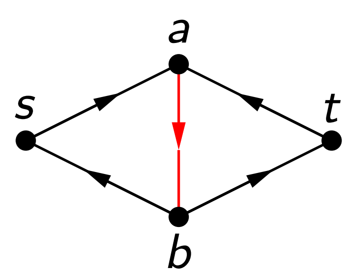
Theorem: There are at most 4^k important directed (X, Y)-separators of size at most k.

DIRECTED MULTIWAY CUT

The undirected approach does not work: the pushing lemma is not true.

Pushing Lemma: [for undirected graphs] Let $t \in T$. The MULTIWAY CUT problem has a solution S that contains an important $(t, T \setminus t)$-separator.

Directed counterexample:



Unique solution with $k = 1$ edges, but it is not an important separator (boundary of $\{s, a\}$, but the boundary of $\{s, a, b\}$ is of the same size).

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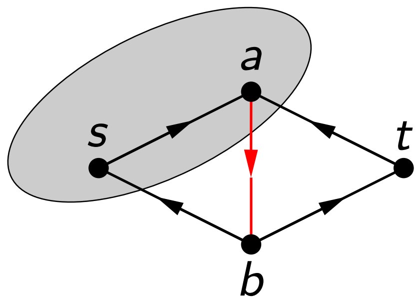

Unique solution with $k = 1$ edges, but it is not an important separator (boundary of $\{s, a\}$, but the boundary of $\{s, a, b\}$ is of the same size).

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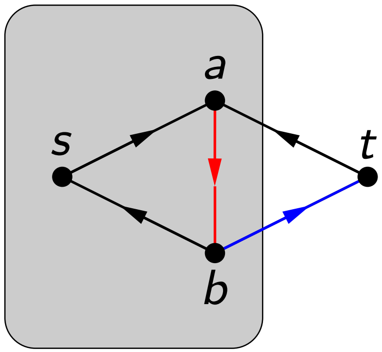

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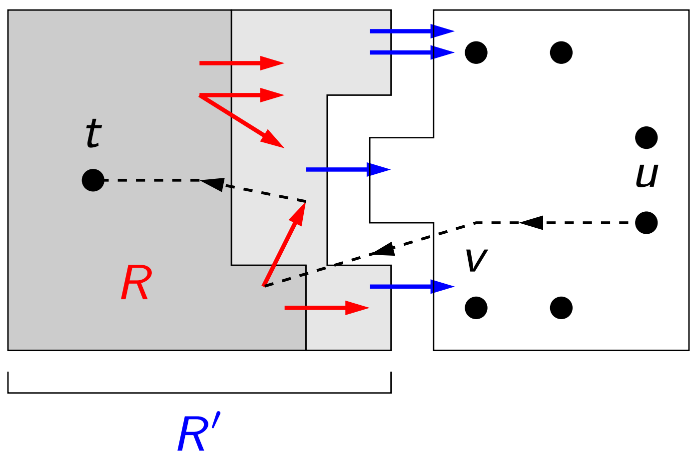

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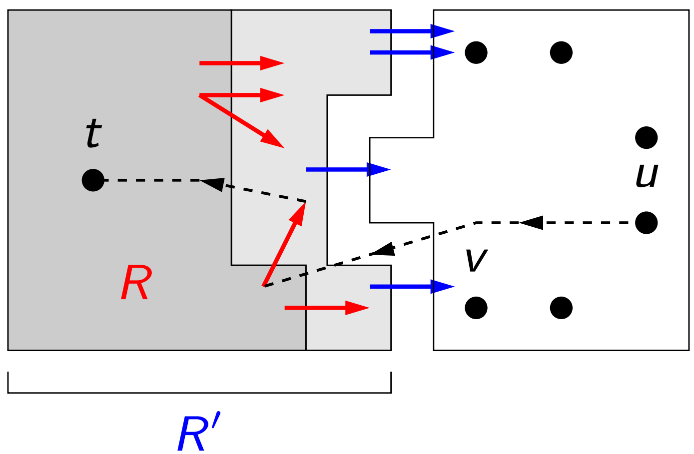

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Theorem: [Chitnis, Hajiaghayi, M. 2011] DIRECTED MULTIWAY CUT is FPT parameterized by the size k of the solution.

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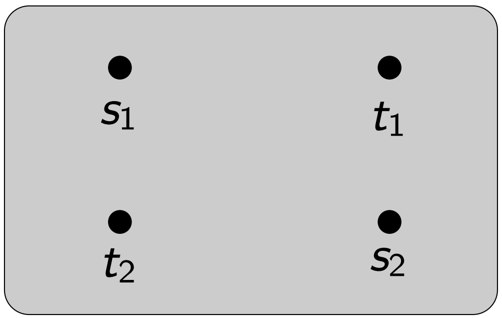

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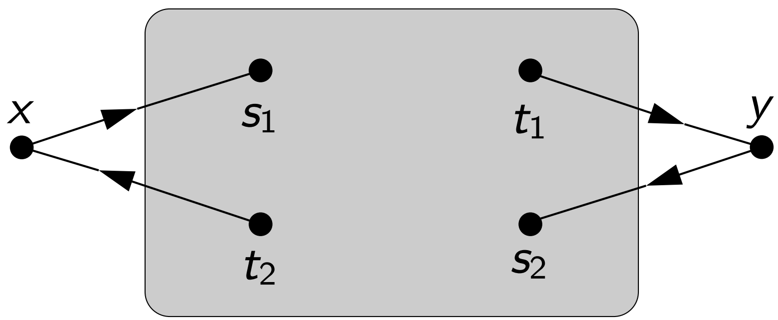

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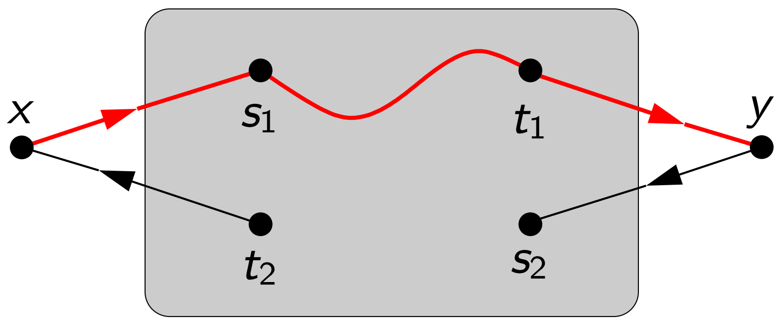

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Corollary: DIRECTED MULTICUT with $\ell = 2$ is FPT parameterized by the size k of the solution.

?

Open: Is DIRECTED MULTICUT with $\ell = 3$ FPT?

Open: Is there an $f(k,\ell) \cdot n^{O(1)}$ algorithm for DIRECTED MULTICUT?

SKEW MULTICUT

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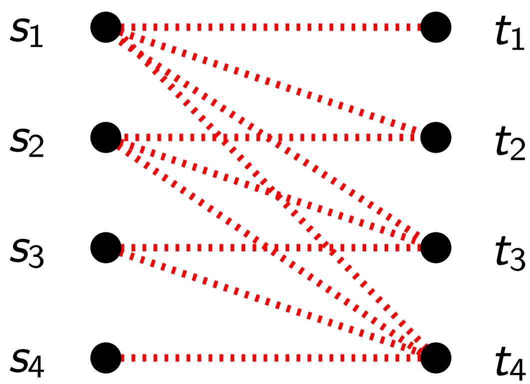
Input: Graph G, pairs $(s_1, t_1), \dots, (s_\ell, t_\ell)$, integer k

Find: A set S of k directed edges such that $G \setminus S$ contains no $s_i \to t_j$ path for any $i \le j$.



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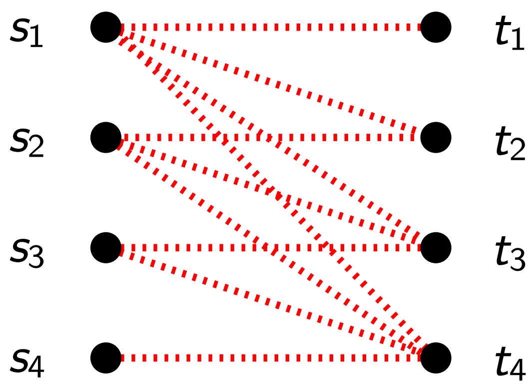

Pushing Lemma: SKEW MULTCUT problem has a solution S that contains an important $(s_1, \{t_1, \ldots, t_\ell\})$-separator.

Theorem: [Chen, Liu, Lu, O'Sullivan, Razgon 2008] SKEW MULTICUT can be solved in time $4^k \cdot n^{O(1)}$.

DIRECTED FEEDBACK VERTEX SET

DIRECTED FEEDBACK VERTEX/EDGE SET	
Input:	Directed graph G, integer k
Find:	A set S of k vertices/edges such that $G \setminus S$ is acyclic.

Note: Edge and vertex versions are equivalent, we will consider the edge version here.

Theorem: [Chen, Liu, Lu, O'Sullivan, Razgon 2008] DIRECTED FEEDBACK EDGE SET is FPT parameterized by the size k of the solution.

Solution uses the technique of **iterative compression** introduced by [Reed, Smith, Vetta 2004].

The compression problem

DIRECTED FEEDBACK EDGE SET COMPRESSION	
Input:	Directed graph G, integer k, a set S' of $k+1$ edges such that $G \setminus S'$ is acyclic
Find:	A set S of k edges such that $G \setminus S$ is acyclic.

Easier than the original problem, as the extra input S' gives us useful structural information about G.

Lemma: The compression problem is FPT parameterized by k.

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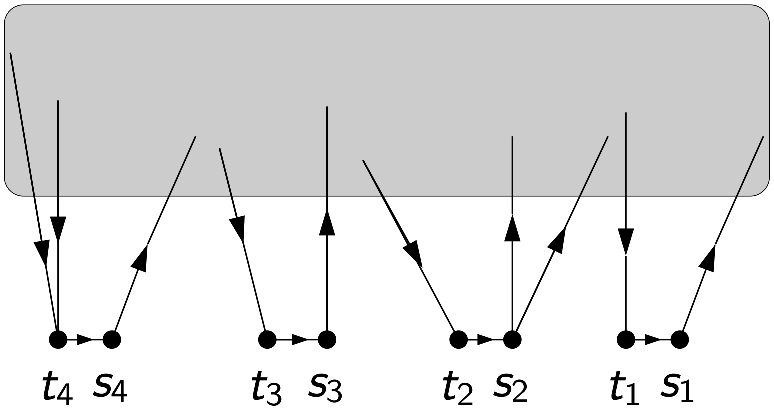
Proof: Let $S' = \{\overrightarrow{t_1 s_1}, \dots, \overrightarrow{t_{k+1} s_{k+1}}\}$.



- By guessing and removing $S \cap S'$, we can assume that S and S' are disjoint [2^{k+1} possibilities].
- By guessing the order of $\{s_1, \dots, s_{k+1}\}$ in the acyclic ordering of $G \setminus S$, we can assume that $s_{k+1} < s_k < \cdots < s_1$ in $G \setminus S$ [$(k+1)!$ possibilities].

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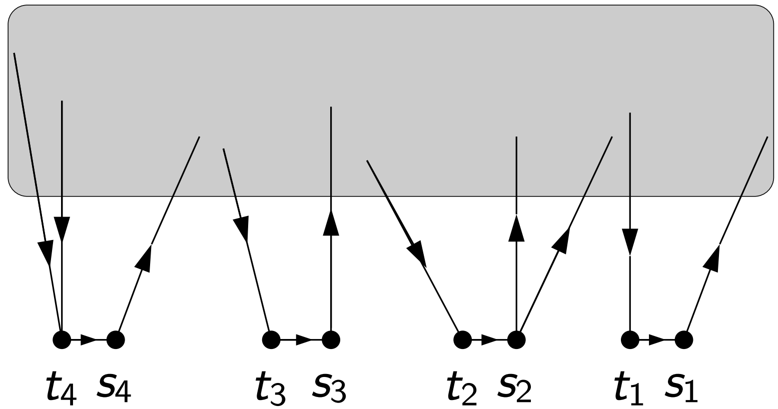

Claim: Suppose that $S' \cap S = \emptyset$.

$G \setminus S$ is acyclic and has an ordering with $s_{k+1} < s_k < \cdots < s_1$

$\Updownarrow$

S covers every $s_i \to t_j$ path for every $i \leq j$

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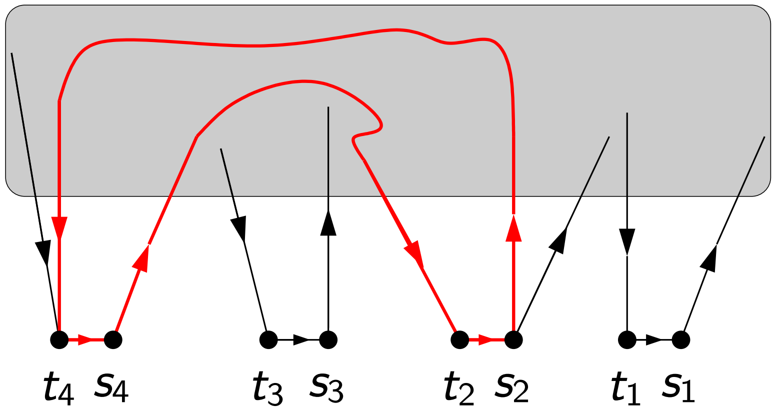

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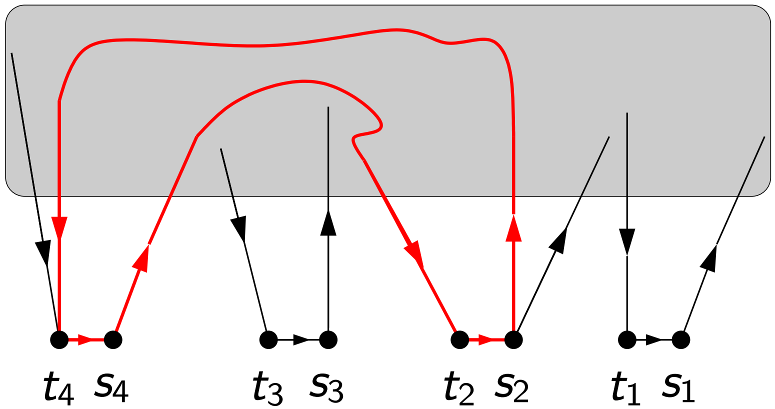

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$\Rightarrow$ We can solve the compression problem by $2^{k+1} \cdot (k+1)!$ applications of SKEW MULTICUT.

Iterative compression

We have given a $f(k)n^{O(1)}$ algorithm for the following problem:

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We get it for free!

Useful trick: **iterative compression** (introduced by [Reed, Smith, Vetta 2004] for BIPARTITE DELETION).

Iterative compression

Let $e_1, \dots, e_m$ be the edges of G and let G_i be the subgraph containing only the first i edges (and all vertices).

For every $i = 1, \dots, m$, we find a set S_i of k edges such that $G_i \setminus S_i$ is acyclic.

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- For $i = k$, we have the trivial solution $S_i = \{e_1, \ldots, e_k\}$.
- Suppose we have a solution S_i for G_i. Then $S_i \cup \{e_{i+1}\}$ is a solution of size $k+1$ in the graph G_{i+1}
- Use the compression algorithm for G_{i+1} with the solution $S_i \cup \{e_{i+1}\}$.
  - If there is no solution of size k for G_{i+1}, then we can stop.
  - Otherwise the compression algorithm gives a solution S_{i+1} of size k for G_{i+1}.

We call the compression algorithm m times, everything else is polynomial.
$\Rightarrow$ DIRECTED FEEDBACK EDGE SET is FPT.

Conclusions

- A simple (but essentially tight) bound on the number of important separators.
- Algorithmic results: FPT algorithms for
  - MULTIWAY CUT in undirected graphs,
  - SKEW MULTICUT in directed graphs, and
  - DIRECTED FEEDBACK VERTEX/EDGE SET.