

W[1]-hardness

Dániel Marx

Recent Advances in Parameterized Complexity
Tel Aviv, Israel, December 3, 2017

Lower bounds

So far we have seen positive results: basic algorithmic techniques for fixed-parameter tractability.

What kind of negative results we have?

- Can we show that a problem (e.g., **CLIQUE**) is **not** FPT?
- Can we show that a problem (e.g., **VERTEX COVER**) has **no** algorithm with running time, say, $2^{o(k)} \cdot n^{O(1)}$?

Lower bounds

So far we have seen positive results: basic algorithmic techniques for fixed-parameter tractability.

What kind of negative results we have?

- Can we show that a problem (e.g., **CLIQUE**) is **not** FPT?
- Can we show that a problem (e.g., **VERTEX COVER**) has **no** algorithm with running time, say, $2^{o(k)} \cdot n^{O(1)}$?

This would require showing that $P \neq NP$: if $P = NP$, then, e.g., k -**CLIQUE** is polynomial-time solvable, hence FPT.

Can we give some evidence for negative results?

Goals of this talk

Two goals:

- 1 Explain the theory behind parameterized intractability.
- 2 Show examples of parameterized reductions.

Classical complexity

Nondeterministic Turing Machine (NTM): single tape, finite alphabet, finite state, head can move left/right only one cell. In each step, the machine can branch into an arbitrary number of directions. Run is successful if at least one branch is successful.

NP: The class of all languages that can be recognized by a polynomial-time NTM.

Polynomial-time reduction from problem P to problem Q : a function ϕ with the following properties:

- $\phi(x)$ is a yes-instance of $Q \iff x$ is a yes-instance of P ,
- $\phi(x)$ can be computed in time $|x|^{O(1)}$.

Definition: Problem Q is **NP-hard** if any problem in **NP** can be reduced to Q .

If an **NP-hard** problem can be solved in polynomial time, then every problem in **NP** can be solved in polynomial time (i.e., $P = NP$).

Parameterized complexity

To build a complexity theory for parameterized problems, we need two concepts:

- An appropriate notion of reduction.
- An appropriate hypothesis.

Polynomial-time reductions are not good for our purposes.

Parameterized complexity

To build a complexity theory for parameterized problems, we need two concepts:

- An appropriate notion of reduction.
- An appropriate hypothesis.

Polynomial-time reductions are not good for our purposes.

Example: Graph G has an independent set k if and only if it has a vertex cover of size $n - k$.

⇒ Transforming an **INDEPENDENT SET** instance (G, k) into a **VERTEX COVER** instance $(G, n - k)$ is a correct polynomial-time reduction.

However, **VERTEX COVER** is FPT, but **INDEPENDENT SET** is not known to be FPT.

Parameterized reduction

Definition

Parameterized reduction from problem P to problem Q : a function ϕ with the following properties:

- $\phi(x)$ is a yes-instance of $Q \iff x$ is a yes-instance of P ,
- $\phi(x)$ can be computed in time $f(k) \cdot |x|^{O(1)}$, where k is the parameter of x ,
- If k is the parameter of x and k' is the parameter of $\phi(x)$, then $k' \leq g(k)$ for some function g .

Fact: If there is a parameterized reduction from problem P to problem Q and Q is FPT, then P is also FPT.

Parameterized reduction

Definition

Parameterized reduction from problem P to problem Q : a function ϕ with the following properties:

- $\phi(x)$ is a yes-instance of $Q \iff x$ is a yes-instance of P ,
- $\phi(x)$ can be computed in time $f(k) \cdot |x|^{O(1)}$, where k is the parameter of x ,
- If k is the parameter of x and k' is the parameter of $\phi(x)$, then $k' \leq g(k)$ for some function g .

Fact: If there is a parameterized reduction from problem P to problem Q and Q is FPT, then P is also FPT.

Non-example: Transforming an **INDEPENDENT SET** instance (G, k) into a **VERTEX COVER** instance $(G, n - k)$ is **not** a parameterized reduction.

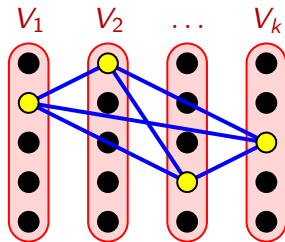
Example: Transforming an **INDEPENDENT SET** instance (G, k) into a **CLIQUE** instance (\overline{G}, k) is a parameterized reduction.

MULTICOLORED CLIQUE

A useful variant of **CLIQUE**:

MULTICOLORED CLIQUE: The vertices of the input graph G are colored with k colors and we have to find a clique containing one vertex from each color.

(or **PARTITIONED CLIQUE**)



Theorem

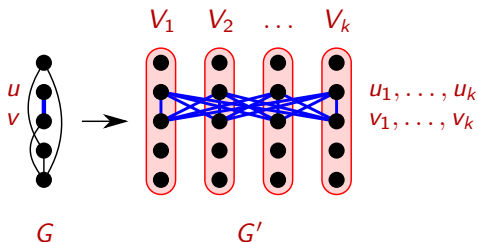
There is a parameterized reduction from **CLIQUE** to **MULTICOLORED CLIQUE**.

MULTICOLORED CLIQUE

Theorem

There is a parameterized reduction from **CLIQUE** to **MULTICOLORED CLIQUE**.

Create G' by replacing each vertex v with k vertices, one in each color class. If u and v are adjacent in the original graph, connect all copies of u with all copies of v .



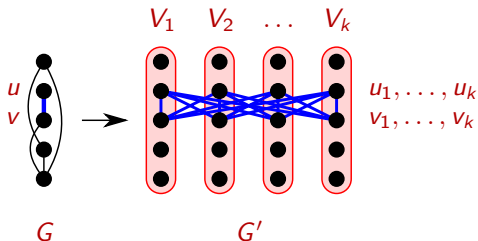
k -clique in $G \iff$ multicolored k -clique in G' .

MULTICOLORED CLIQUE

Theorem

There is a parameterized reduction from **CLIQUE** to **MULTICOLORED CLIQUE**.

Create G' by replacing each vertex v with k vertices, one in each color class. If u and v are adjacent in the original graph, connect all copies of u with all copies of v .



k -clique in $G \iff$ multicolored k -clique in G' .

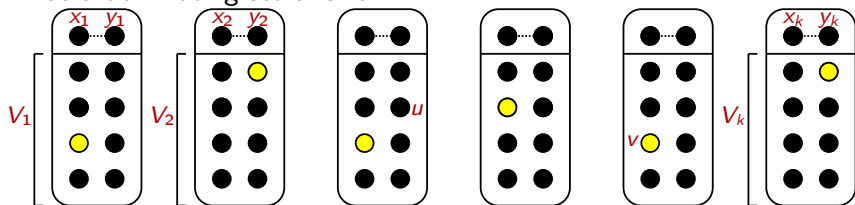
Similarly: reduction to **MULTICOLORED INDEPENDENT SET**.

DOMINATING SET

Theorem

There is a parameterized reduction from **MULTICOLORED INDEPENDENT SET** to **DOMINATING SET**.

Proof: Let G be a graph with color classes V_1, \dots, V_k . We construct a graph H such that G has a multicolored k -clique iff H has a dominating set of size k .



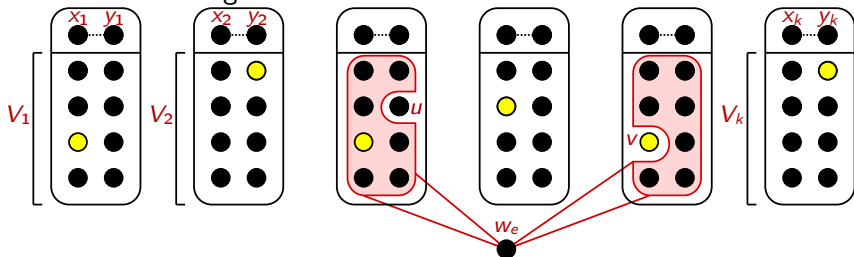
- The dominating set has to contain one vertex from each of the k cliques V_1, \dots, V_k to dominate every x_i and y_i .

DOMINATING SET

Theorem

There is a parameterized reduction from **MULTICOLORED INDEPENDENT SET** to **DOMINATING SET**.

Proof: Let G be a graph with color classes V_1, \dots, V_k . We construct a graph H such that G has a multicolored k -clique iff H has a dominating set of size k .



- The dominating set has to contain one vertex from each of the k cliques V_1, \dots, V_k to dominate every x_i and y_i .
- For every edge $e = uv$, an additional vertex w_e ensures that these selections describe an independent set.

Variants of DOMINATING SET

- **DOMINATING SET**: Given a graph, find k vertices that dominate every vertex.
- **RED-BLUE DOMINATING SET**: Given a bipartite graph, find k vertices on the red side that dominate the blue side.
- **SET COVER**: Given a set system, find k sets whose union covers the universe.
- **HITTING SET**: Given a set system, find k elements that intersect every set in the system.

All of these problems are equivalent under parameterized reductions, hence at least as hard as **CLIQUE**.

Basic hypotheses

It seems that parameterized complexity theory cannot be built on assuming $P \neq NP$ – we have to assume something stronger.

Let us choose a basic hypothesis:

Engineers' Hypothesis

k -CLIQUE cannot be solved in time $f(k) \cdot n^{O(1)}$.

Basic hypotheses

It seems that parameterized complexity theory cannot be built on assuming $P \neq NP$ – we have to assume something stronger.

Let us choose a basic hypothesis:

Engineers' Hypothesis

k -CLIQUE cannot be solved in time $f(k) \cdot n^{O(1)}$.

Theorists' Hypothesis

k -STEP HALTING PROBLEM (is there a path of the given NTM that stops in k steps?) cannot be solved in time $f(k) \cdot n^{O(1)}$.

Basic hypotheses

It seems that parameterized complexity theory cannot be built on assuming $P \neq NP$ – we have to assume something stronger.

Let us choose a basic hypothesis:

Engineers' Hypothesis

k -CLIQUE cannot be solved in time $f(k) \cdot n^{O(1)}$.

Theorists' Hypothesis

k -STEP HALTING PROBLEM (is there a path of the given NTM that stops in k steps?) cannot be solved in time $f(k) \cdot n^{O(1)}$.

Exponential Time Hypothesis (ETH)

n -variable 3SAT cannot be solved in time $2^{o(n)}$.

Which hypothesis is the most plausible?

Basic hypotheses

It seems that parameterized complexity theory cannot be built on assuming $P \neq NP$ – we have to assume something stronger.

Let us choose a basic hypothesis:

Engineers' Hypothesis

k -CLIQUE cannot be solved in time $f(k) \cdot n^{O(1)}$.



Theorists' Hypothesis

k -STEP HALTING PROBLEM (is there a path of the given NTM that stops in k steps?) cannot be solved in time $f(k) \cdot n^{O(1)}$.



Exponential Time Hypothesis (ETH)

n -variable 3SAT cannot be solved in time $2^{o(n)}$.

Which hypothesis is the most plausible?

Summary

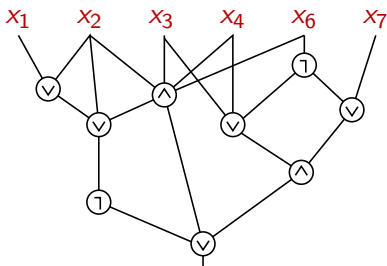
- INDEPENDENT SET and k -STEP HALTING PROBLEM can be reduced to each other \Rightarrow Engineers' Hypothesis and Theorists' Hypothesis are equivalent!
- INDEPENDENT SET and k -STEP HALTING PROBLEM can be reduced to DOMINATING SET.

Summary

- INDEPENDENT SET and k -STEP HALTING PROBLEM can be reduced to each other \Rightarrow Engineers' Hypothesis and Theorists' Hypothesis are equivalent!
- INDEPENDENT SET and k -STEP HALTING PROBLEM can be reduced to DOMINATING SET.
- Is there a parameterized reduction from DOMINATING SET to INDEPENDENT SET?
- Probably not. Unlike in NP-completeness, where most problems are equivalent, here we have a hierarchy of hard problems.
 - INDEPENDENT SET is $W[1]$ -complete.
 - DOMINATING SET is $W[2]$ -complete.
- Does not matter if we only care about whether a problem is FPT or not!

Boolean circuit

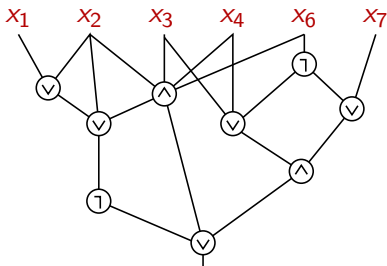
A **Boolean circuit** consists of input gates, negation gates, AND gates, OR gates, and a single output gate.



CIRCUIT SATISFIABILITY: Given a Boolean circuit C , decide if there is an assignment on the inputs of C making the output true.

Boolean circuit

A **Boolean circuit** consists of input gates, negation gates, AND gates, OR gates, and a single output gate.



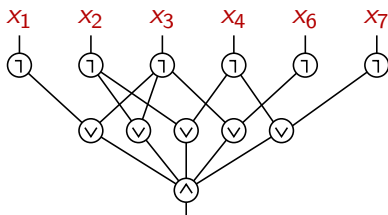
CIRCUIT SATISFIABILITY: Given a Boolean circuit C , decide if there is an assignment on the inputs of C making the output true.

Weight of an assignment: number of true values.

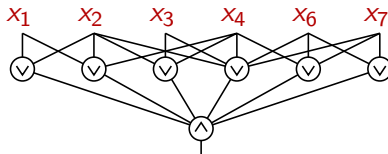
WEIGHTED CIRCUIT SATISFIABILITY: Given a Boolean circuit C and an integer k , decide if there is an assignment of weight k making the output true.

WEIGHTED CIRCUIT SATISFIABILITY

INDEPENDENT SET can be reduced to WEIGHTED CIRCUIT SATISFIABILITY:

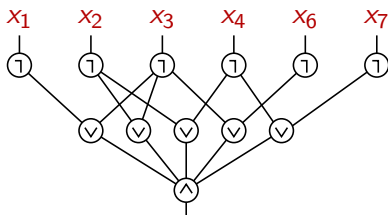


DOMINATING SET can be reduced to WEIGHTED CIRCUIT SATISFIABILITY:

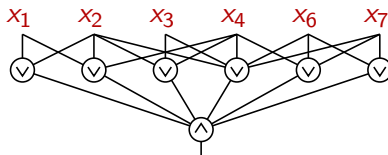


WEIGHTED CIRCUIT SATISFIABILITY

INDEPENDENT SET can be reduced to WEIGHTED CIRCUIT SATISFIABILITY:



DOMINATING SET can be reduced to WEIGHTED CIRCUIT SATISFIABILITY:



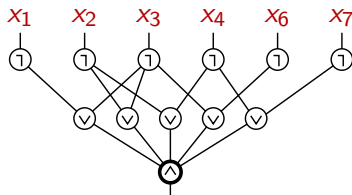
To express DOMINATING SET, we need more complicated circuits.

Depth and weft

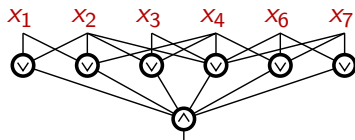
The **depth** of a circuit is the maximum length of a path from an input to the output.

A gate is **large** if it has more than 2 inputs. The **weft** of a circuit is the maximum number of large gates on a path from an input to the output.

INDEPENDENT SET: weft 1, depth 3



DOMINATING SET: weft 2, depth 2



The W-hierarchy

Let $C[t, d]$ be the set of all circuits having weft at most t and depth at most d .

Definition

A problem P is in the class $W[t]$ if there is a constant d and a parameterized reduction from P to **WEIGHTED CIRCUIT SATISFIABILITY** of $C[t, d]$.

We have seen that **INDEPENDENT SET** is in $W[1]$ and **DOMINATING SET** is in $W[2]$.

Fact: **INDEPENDENT SET** is $W[1]$ -complete.

Fact: **DOMINATING SET** is $W[2]$ -complete.

The W-hierarchy

Let $C[t, d]$ be the set of all circuits having weft at most t and depth at most d .

Definition

A problem P is in the class $W[t]$ if there is a constant d and a parameterized reduction from P to **WEIGHTED CIRCUIT SATISFIABILITY** of $C[t, d]$.

We have seen that **INDEPENDENT SET** is in $W[1]$ and **DOMINATING SET** is in $W[2]$.

Fact: **INDEPENDENT SET** is $W[1]$ -complete.

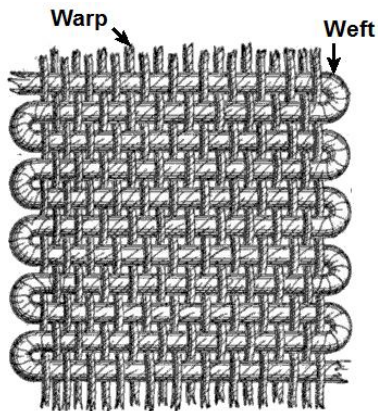
Fact: **DOMINATING SET** is $W[2]$ -complete.

If any $W[1]$ -complete problem is FPT, then $FPT = W[1]$ and every problem in $W[1]$ is FPT.

If any $W[2]$ -complete problem is in $W[1]$, then $W[1] = W[2]$.

\Rightarrow If there is a parameterized reduction from **DOMINATING SET** to **INDEPENDENT SET**, then $W[1] = W[2]$.

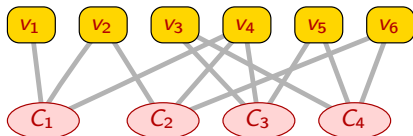
Weft



Weft is a term related to weaving cloth: it is the thread that runs from side to side in the fabric.

Parameterized reductions

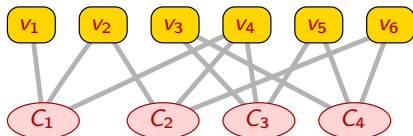
Typical NP-hardness proofs: reduction from e.g., CLIQUE or 3SAT, representing each vertex/edge/variable/clause with a gadget.



Usually does not work for parameterized reductions: cannot afford the parameter increase.

Parameterized reductions

Typical NP-hardness proofs: reduction from e.g., CLIQUE or 3SAT, representing each vertex/edge/variable/clause with a gadget.



Usually does not work for parameterized reductions: cannot afford the parameter increase.

Types of parameterized reductions:

- Reductions keeping the structure of the graph.
 - CLIQUE \Rightarrow INDEPENDENT SET
- Reductions with vertex representations.
 - MULTICOLORED INDEPENDENT SET \Rightarrow DOMINATING SET
- Reductions with vertex and edge representations.

LIST COLORING

LIST COLORING is a generalization of ordinary vertex coloring:
given a

- graph G ,
- a set of colors C , and
- a list $L(v) \subseteq C$ for each vertex v ,

the task is to find a coloring c where $c(v) \in L(v)$ for every v .

Theorem

VERTEX COLORING is FPT parameterized by treewidth.

However, list coloring is more difficult:

Theorem

LIST COLORING is $W[1]$ -hard parameterized by treewidth.

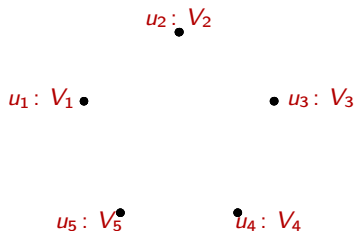
LIST COLORING

Theorem

LIST COLORING is $W[1]$ -hard parameterized by treewidth.

Proof: By reduction from MULTICOLORED INDEPENDENT SET.

- Let G be a graph with color classes V_1, \dots, V_k .
- Set C of colors: the set of vertices of G .
- The colors appearing on vertices u_1, \dots, u_k correspond to the k vertices of the clique, hence we set $L(u_i) = V_i$.



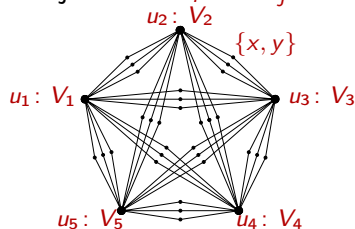
LIST COLORING

Theorem

LIST COLORING is $W[1]$ -hard parameterized by treewidth.

Proof: By reduction from MULTICOLORED INDEPENDENT SET.

- Let G be a graph with color classes V_1, \dots, V_k .
- Set C of colors: the set of vertices of G .
- The colors appearing on vertices u_1, \dots, u_k correspond to the k vertices of the clique, hence we set $L(u_i) = V_i$.
- If $x \in V_i$ and $y \in V_j$ are adjacent in G , then we need to ensure that $c(u_i) = x$ and $c(u_j) = y$ are not true at the same time \Rightarrow we add a vertex adjacent to u_i and u_j whose list is $\{x, y\}$.



Vertex representation

Key idea

- Represent the k vertices of the solution with k gadgets.
- Connect the gadgets in a way that ensures that the represented values are **compatible**.

ODD SET

ODD SET: Given a set system \mathcal{F} over a universe U and an integer k , find a set S of at most k elements such that $|S \cap F|$ is odd for every $F \in \mathcal{F}$.

Theorem

ODD SET is $W[1]$ -hard parameterized by k .

ODD SET

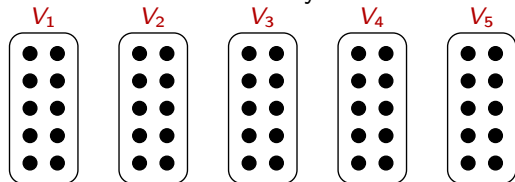
Theorem

ODD SET is $W[1]$ -hard parameterized by k .

First try: Reduction from MULTICOLORED INDEPENDENT SET.

Let $U = V_1 \cup \dots \cup V_k$ and introduce each set V_i into \mathcal{F} .

\Rightarrow The solution has to contain exactly one element from each V_i .



If $xy \in E(G)$, how can we express that $x \in V_i$ and $y \in V_j$ cannot be selected simultaneously?

ODD SET

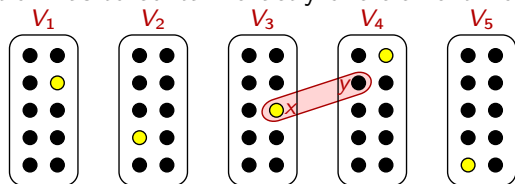
Theorem

ODD SET is $W[1]$ -hard parameterized by k .

First try: Reduction from MULTICOLORED INDEPENDENT SET.

Let $U = V_1 \cup \dots \cup V_k$ and introduce each set V_i into \mathcal{F} .

\Rightarrow The solution has to contain exactly one element from each V_i .



If $xy \in E(G)$, how can we express that $x \in V_i$ and $y \in V_j$ cannot be selected simultaneously? Seems difficult:

- introducing $\{x, y\}$ into \mathcal{F} forces that exactly one of x and y appears in the solution,

ODD SET

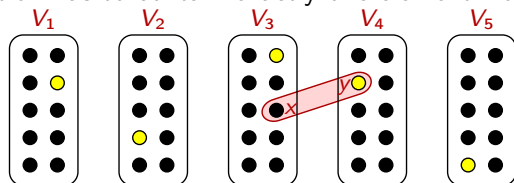
Theorem

ODD SET is $W[1]$ -hard parameterized by k .

First try: Reduction from MULTICOLORED INDEPENDENT SET.

Let $U = V_1 \cup \dots \cup V_k$ and introduce each set V_i into \mathcal{F} .

\Rightarrow The solution has to contain exactly one element from each V_i .



If $xy \in E(G)$, how can we express that $x \in V_i$ and $y \in V_j$ cannot be selected simultaneously? Seems difficult:

- introducing $\{x, y\}$ into \mathcal{F} forces that exactly one of x and y appears in the solution,

ODD SET

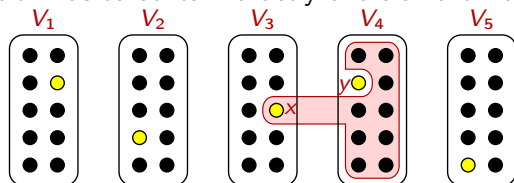
Theorem

ODD SET is $W[1]$ -hard parameterized by k .

First try: Reduction from MULTICOLORED INDEPENDENT SET.

Let $U = V_1 \cup \dots \cup V_k$ and introduce each set V_i into \mathcal{F} .

\Rightarrow The solution has to contain exactly one element from each V_i .



If $xy \in E(G)$, how can we express that $x \in V_i$ and $y \in V_j$ cannot be selected simultaneously? Seems difficult:

- introducing $\{x, y\}$ into \mathcal{F} forces that **exactly one** of x and y appears in the solution,
- introducing $\{x\} \cup (V_j \setminus \{y\})$ into \mathcal{F} forces that either **both** x and y or **none** of x and y appear in the solution.

ODD SET

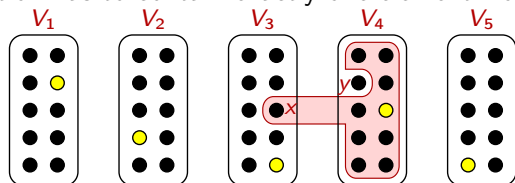
Theorem

ODD SET is $W[1]$ -hard parameterized by k .

First try: Reduction from MULTICOLORED INDEPENDENT SET.

Let $U = V_1 \cup \dots \cup V_k$ and introduce each set V_i into \mathcal{F} .

\Rightarrow The solution has to contain exactly one element from each V_i .



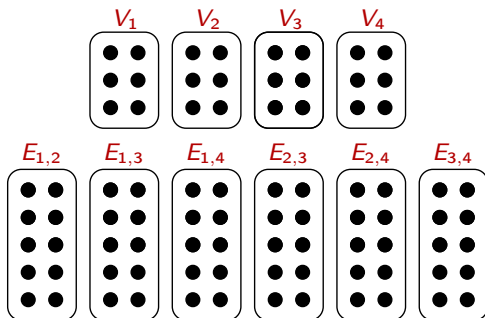
If $xy \in E(G)$, how can we express that $x \in V_i$ and $y \in V_j$ cannot be selected simultaneously? Seems difficult:

- introducing $\{x, y\}$ into \mathcal{F} forces that **exactly one** of x and y appears in the solution,
- introducing $\{x\} \cup (V_j \setminus \{y\})$ into \mathcal{F} forces that either **both** x and y or **none** of x and y appear in the solution.

ODD SET

Reduction from **MULTICOLORED CLIQUE**.

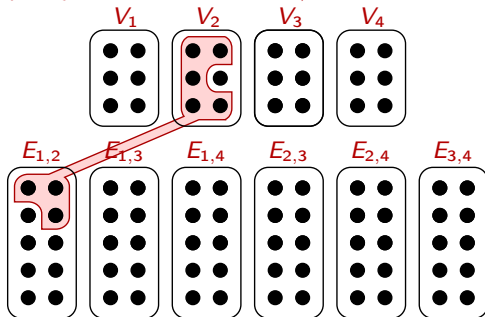
- $U := \bigcup_{i=1}^k V_i \cup \bigcup_{1 \leq i < j \leq k} E_{i,j}$.
- $k' := k + \binom{k}{2}$.
- Let \mathcal{F} contain V_i ($1 \leq i \leq k$) and $E_{i,j}$ ($1 \leq i < j \leq k$).



ODD SET

Reduction from **MULTICOLORED CLIQUE**.

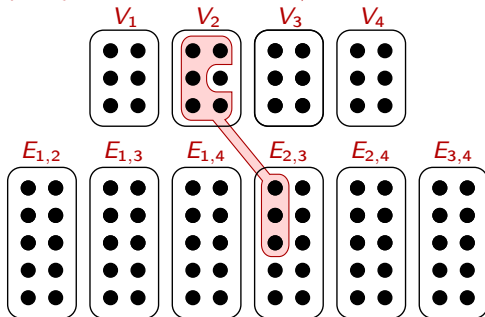
- $U := \bigcup_{i=1}^k V_i \cup \bigcup_{1 \leq i < j \leq k} E_{i,j}$.
- $k' := k + \binom{k}{2}$.
- Let \mathcal{F} contain V_i ($1 \leq i \leq k$) and $E_{i,j}$ ($1 \leq i < j \leq k$).
- For every $v \in V_i$ and $x \neq i$, we introduce the sets:
($V_i \setminus \{v\}$) \cup {every edge from $E_{i,x}$ with endpoint v }
($V_i \setminus \{v\}$) \cup {every edge from $E_{x,i}$ with endpoint v }



ODD SET

Reduction from **MULTICOLORED CLIQUE**.

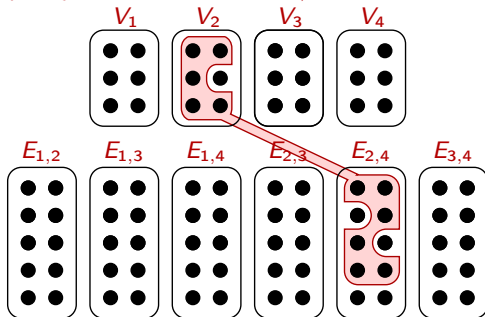
- $U := \bigcup_{i=1}^k V_i \cup \bigcup_{1 \leq i < j \leq k} E_{i,j}$.
- $k' := k + \binom{k}{2}$.
- Let \mathcal{F} contain V_i ($1 \leq i \leq k$) and $E_{i,j}$ ($1 \leq i < j \leq k$).
- For every $v \in V_i$ and $x \neq i$, we introduce the sets:
($V_i \setminus \{v\}$) \cup {every edge from $E_{i,x}$ with endpoint v }
($V_i \setminus \{v\}$) \cup {every edge from $E_{x,i}$ with endpoint v }



ODD SET

Reduction from **MULTICOLORED CLIQUE**.

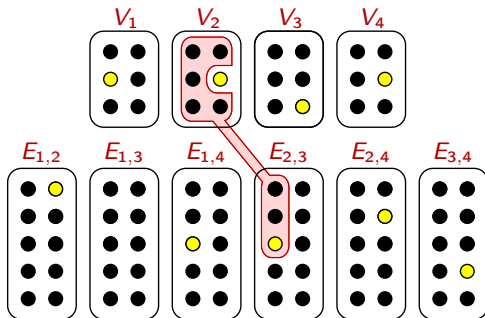
- $U := \bigcup_{i=1}^k V_i \cup \bigcup_{1 \leq i < j \leq k} E_{i,j}$.
- $k' := k + \binom{k}{2}$.
- Let \mathcal{F} contain V_i ($1 \leq i \leq k$) and $E_{i,j}$ ($1 \leq i < j \leq k$).
- For every $v \in V_i$ and $x \neq i$, we introduce the sets:
($V_i \setminus \{v\}$) \cup {every edge from $E_{i,x}$ with endpoint v }
($V_i \setminus \{v\}$) \cup {every edge from $E_{x,i}$ with endpoint v }



ODD SET

Reduction from **MULTICOLORED CLIQUE**.

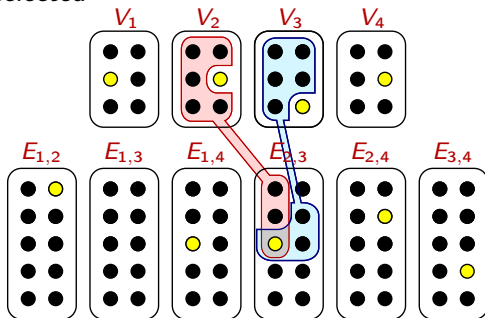
- For every $v \in V_i$ and $x \neq i$, we introduce the sets:
 $(V_i \setminus \{v\}) \cup \{\text{every edge from } E_{i,x} \text{ with endpoint } v\}$
 $(V_i \setminus \{v\}) \cup \{\text{every edge from } E_{x,i} \text{ with endpoint } v\}$
- $v \in V_i$ selected \iff edges with endpoint v are selected from $E_{i,x}$ and $E_{x,i}$



ODD SET

Reduction from **MULTICOLORED CLIQUE**.

- For every $v \in V_i$ and $x \neq i$, we introduce the sets:
 $(V_i \setminus \{v\}) \cup \{\text{every edge from } E_{i,x} \text{ with endpoint } v\}$
 $(V_i \setminus \{v\}) \cup \{\text{every edge from } E_{x,i} \text{ with endpoint } v\}$
- $v \in V_i$ selected \iff edges with endpoint v are selected from $E_{i,x}$ and $E_{x,i}$
- $v_i \in V_i$ selected \iff edge $v_i v_j$ is selected in $E_{i,x}$
 $v_j \in V_j$ selected



Vertex and edge representation

Key idea

- Represent the vertices of the clique by k gadgets.
- Represent the edges of the clique by $\binom{k}{2}$ gadgets.
- Connect edge gadget $E_{i,j}$ to vertex gadgets V_i and V_j such that if $E_{i,j}$ represents the edge between $x \in V_i$ and $y \in V_j$, then it **forces** V_i to x and V_j to y .

Variants of ODD SET

The following problems are $W[1]$ -hard:

- ODD SET
- EXACT ODD SET (find a set of size exactly k ...)
- EXACT EVEN SET
- UNIQUE HITTING SET
(at most k elements that hit each set exactly once)
- EXACT UNIQUE HITTING SET
(exactly k elements that hit each set exactly once)

Variants of ODD SET

The following problems are $W[1]$ -hard:

- ODD SET
- EXACT ODD SET (find a set of size exactly k ...)
- EXACT EVEN SET
- UNIQUE HITTING SET
(at most k elements that hit each set exactly once)
- EXACT UNIQUE HITTING SET
(exactly k elements that hit each set exactly once)

Open question:

? EVEN SET: Given a set system \mathcal{F} and an integer k , find a nonempty set S of at most k elements such $|F \cap S|$ is even for every $F \in \mathcal{F}$.

Grid Tiling

GRID TILING

Input: A $k \times k$ matrix and a set of pairs $S_{i,j} \subseteq [D] \times [D]$ for each cell.

A pair $s_{i,j} \in S_{i,j}$ for each cell such that

- Find:
- Vertical neighbors agree in the 1st coordinate.
 - Horizontal neighbors agree in the 2nd coordinate.

(1,1)	(5,1)	(1,1)
(3,1)	(1,4)	(2,4)
(2,4)	(5,3)	(3,3)
(2,2)	(3,1)	(2,2)
(1,4)	(1,2)	(2,3)
(1,3)	(1,1)	(2,3)
(2,3)	(1,3)	(5,3)
(3,3)		

$$k = 3, D = 5$$

Grid Tiling

GRID TILING

Input: A $k \times k$ matrix and a set of pairs $S_{i,j} \subseteq [D] \times [D]$ for each cell.

A pair $s_{i,j} \in S_{i,j}$ for each cell such that

- Find:
- Vertical neighbors agree in the 1st coordinate.
 - Horizontal neighbors agree in the 2nd coordinate.

(1,1) (3,1) (2,4)	(5,1) (1,4) (5,3)	(1,1) (2,4) (3,3)
(2,2) (1,4)	(3,1) (1,2)	(2,2) (2,3)
(1,3) (2,3) (3,3)	(1,1) (1,3)	(2,3) (5,3)

$$k = 3, D = 5$$

Grid Tiling

GRID TILING

Input: A $k \times k$ matrix and a set of pairs $S_{i,j} \subseteq [D] \times [D]$ for each cell.

A pair $s_{i,j} \in S_{i,j}$ for each cell such that

- Find:
- Vertical neighbors agree in the 1st coordinate.
 - Horizontal neighbors agree in the 2nd coordinate.

Simple proof:

Fact

There is a parameterized reduction from k -CLIQUE to $k \times k$ GRID TILING.

Grid Tiling is $W[1]$ -hard

Reduction from k -CLIQUE

Definition of the sets:

- For $i = j$: $(x, y) \in S_{i,j} \iff x = y$
- For $i \neq j$: $(x, y) \in S_{i,j} \iff x$ and y are adjacent.

	(v_i, v_i)			

Each diagonal cell defines a value $v_i \dots$

Grid Tiling is $W[1]$ -hard

Reduction from k -CLIQUE

Definition of the sets:

- For $i = j$: $(x, y) \in S_{i,j} \iff x = y$
- For $i \neq j$: $(x, y) \in S_{i,j} \iff x$ and y are adjacent.

	(v_i, \cdot)			
(\cdot, v_i)	(v_i, v_i)	(\cdot, v_i)	(\cdot, v_i)	(\cdot, v_i)
	(v_i, \cdot)			
	(v_i, \cdot)			
	(v_i, \cdot)			

... which appears on a "cross"

Grid Tiling is $W[1]$ -hard

Reduction from k -CLIQUE

Definition of the sets:

- For $i = j$: $(x, y) \in S_{i,j} \iff x = y$
- For $i \neq j$: $(x, y) \in S_{i,j} \iff x$ and y are adjacent.

	(v_i, \cdot)			
(\cdot, v_i)	(v_i, v_i)	(\cdot, v_i)	(\cdot, v_i)	(\cdot, v_i)
	(v_i, \cdot)			
	(v_i, \cdot)		(v_j, v_j)	
	(v_i, \cdot)			

v_i and v_j are adjacent for every $1 \leq i < j \leq k$.

Grid Tiling is $W[1]$ -hard

Reduction from k -CLIQUE

Definition of the sets:

- For $i = j$: $(x, y) \in S_{i,j} \iff x = y$
- For $i \neq j$: $(x, y) \in S_{i,j} \iff x$ and y are adjacent.

	(v_i, \cdot)		(v_j, \cdot)	
(\cdot, v_i)	(v_i, v_i)	(\cdot, v_i)	(v_j, v_i)	(\cdot, v_i)
	(v_i, \cdot)		(v_j, \cdot)	
(\cdot, v_j)	(v_i, v_j)	(\cdot, v_j)	(v_j, v_j)	(\cdot, v_j)
	(v_i, \cdot)		(v_j, \cdot)	

v_i and v_j are adjacent for every $1 \leq i < j \leq k$.

GRID TILING and planar problems

Theorem

$k \times k$ GRID TILING is $W[1]$ -hard and, assuming ETH, cannot be solved in time $f(k)n^{o(k)}$ for any function f .

This lower bound is the key for proving hardness results for planar graphs.

Examples:

- MULTIWAY CUT on planar graphs with k terminals
- INDEPENDENT SET for unit disks
- STRONGLY CONNECTED STEINER SUBGRAPH on planar graphs
- SCATTERED SET on planar graphs

Grid Tiling with \leq

GRID TILING WITH \leq

Input: A $k \times k$ matrix and a set of pairs $S_{i,j} \subseteq [D] \times [D]$ for each cell.

A pair $s_{i,j} \in S_{i,j}$ for each cell such that

- Find:**
- 1st coordinate of $s_{i,j} \leq$ 1st coordinate of $s_{i+1,j}$.
 - 2nd coordinate of $s_{i,j} \leq$ 2nd coordinate of $s_{i,j+1}$.

(5,1) (1,2) (3,3)	(4,3) (3,2)	(2,3) (2,5)
(2,1) (5,5) (3,5)	(4,2) (5,3)	(5,1) (3,2)
(5,1) (2,2) (5,3)	(2,1) (4,2)	(3,1) (3,2) (3,3)

$$k = 3, D = 5$$

Grid Tiling with \leq

GRID TILING WITH \leq

Input: A $k \times k$ matrix and a set of pairs $S_{i,j} \subseteq [D] \times [D]$ for each cell.

A pair $s_{i,j} \in S_{i,j}$ for each cell such that

- Find:**
- 1st coordinate of $s_{i,j} \leq$ 1st coordinate of $s_{i+1,j}$.
 - 2nd coordinate of $s_{i,j} \leq$ 2nd coordinate of $s_{i,j+1}$.

Variant of the previous proof:

Theorem










There is a parameterized reduction from $k \times k$ -GRID TILING to $O(k) \times O(k)$ GRID TILING WITH \leq .

Very useful starting point for geometric (and also some planar) problems!

Reduction to unit disks

Theorem

INDEPENDENT SET for unit disks is $W[1]$ -hard.

(5,1) (1,2) (3,3)	(4,3) (3,2)	(2,3) (2,5)			
(2,1) (5,5) (3,5)	(4,2) (5,3)	(5,1) (3,2)			
(5,1) (2,2) (5,3)	(2,1) (4,2)	(3,1) (3,2) (3,3)			

Every pair is represented by a unit disk in the plane.

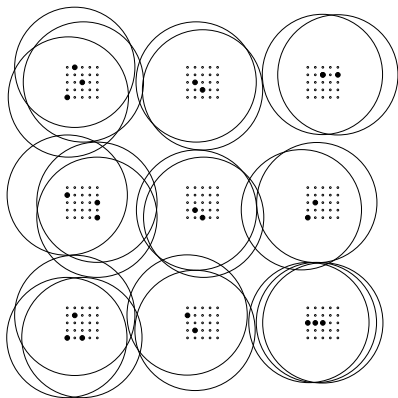
\leq relation between coordinates \iff disks do not intersect.

Reduction to unit disks

Theorem

INDEPENDENT SET for unit disks is $W[1]$ -hard.

(5,1) (1,2) (3,3)	(4,3) (3,2)	(2,3) (2,5)
(2,1) (5,5) (3,5)	(4,2) (5,3)	(5,1) (3,2)
(5,1) (2,2) (5,3)	(2,1) (4,2)	(3,1) (3,2) (3,3)



Every pair is represented by a unit disk in the plane.

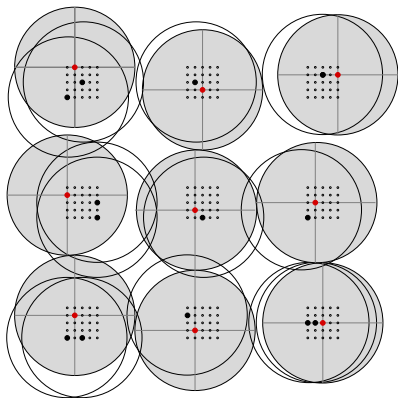
\leq relation between coordinates \iff disks do not intersect.

Reduction to unit disks

Theorem

INDEPENDENT SET for unit disks is $W[1]$ -hard.

(5,1) (1,2) (3,3)	(4,3) (3,2)	(2,3) (2,5)
(2,1) (5,5) (3,5)	(4,2) (5,3)	(5,1) (3,2)
(5,1) (2,2) (5,3)	(2,1) (4,2)	(3,1) (3,2) (3,3)



Every pair is represented by a unit disk in the plane.

\leq relation between coordinates \iff disks do not intersect.

Summary

- By parameterized reductions, we can show that lots of parameterized problems are at least as hard as **CLIQUE**, hence unlikely to be fixed-parameter tractable.
- Connection with Turing machines gives some supporting evidence for hardness (only of theoretical interest).
- The **W**-hierarchy classifies the problems according to hardness (only of theoretical interest).
- Important trick in **W[1]**-hardness proofs: vertex and edge representations.