



Parameterized complexity of constraint satisfaction problems

Dániel Marx

Budapest University of Technology and Economics

`dmarx@cs.bme.hu`

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Outline of the talk

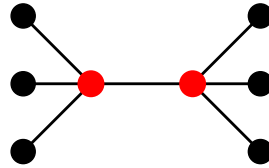
- ⑥ Parameterized complexity
- ⑥ Schaefer's Dichotomy Theorem
- ⑥ A parameterized dichotomy theorem
- ⑥ Sketch of proof
- ⑥ Planar formulae

Parameterized complexity

Problem: MINIMUM VERTEX COVER

Input: Graph G , integer k

Question: Is it possible to cover the edges with k vertices?

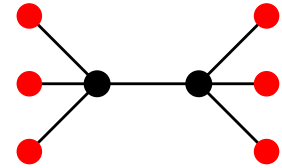


Complexity: NP-complete

Problem: MAXIMUM INDEPENDENT SET

Input: Graph G , integer k

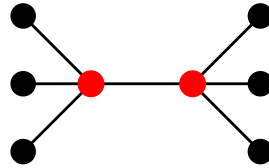
Question: Is it possible to find k independent vertices?



Complexity: NP-complete

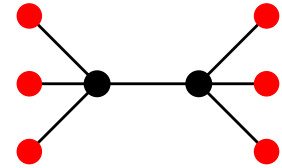
Parameterized complexity

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Complete enumeration: $O(n^k)$ possibilities

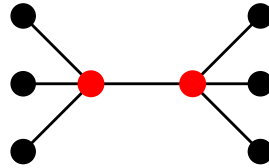
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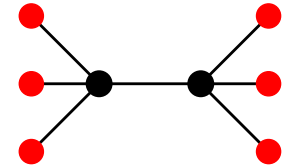
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Input: Graph G , integer k
Question: Is it possible to cover the edges with k vertices?



Complexity: NP-complete
Complete enumeration: $O(n^k)$ possibilities
 $O(2^k n^2)$ algorithm exists



Problem: MAXIMUM INDEPENDENT SET
Input: Graph G , integer k
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Complexity: NP-complete
Complete enumeration: $O(n^k)$ possibilities
No $n^{o(k)}$ algorithm known



Bounded search tree method

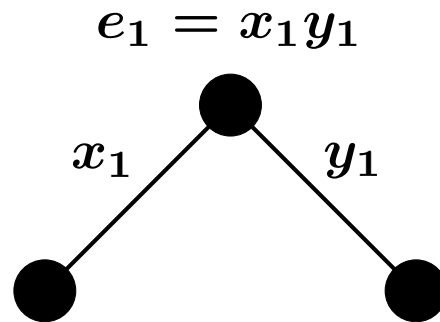
Algorithm for MINIMUM VERTEX COVER:

$$e_1 = x_1 y_1$$



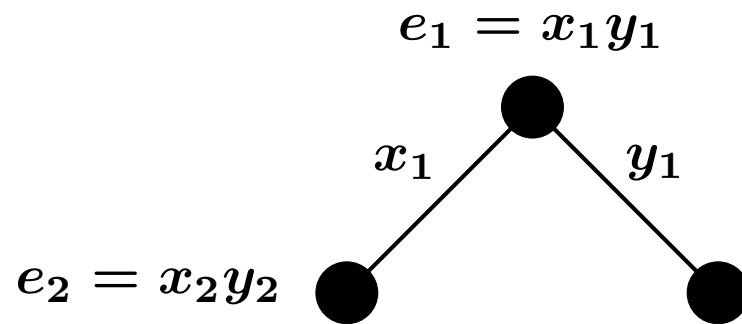
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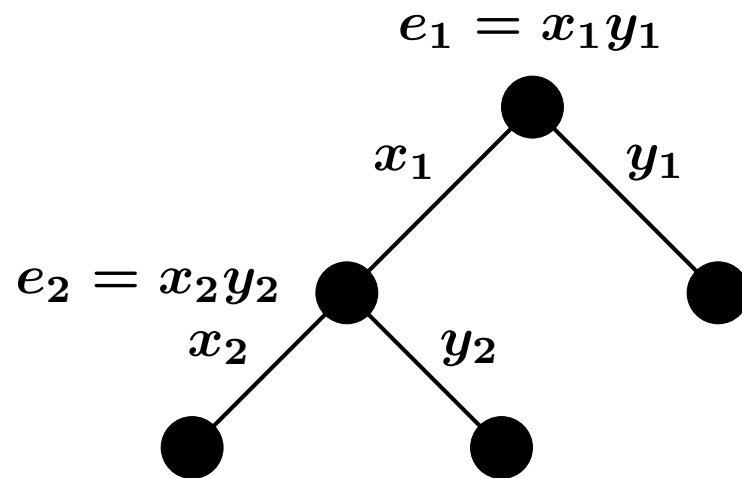
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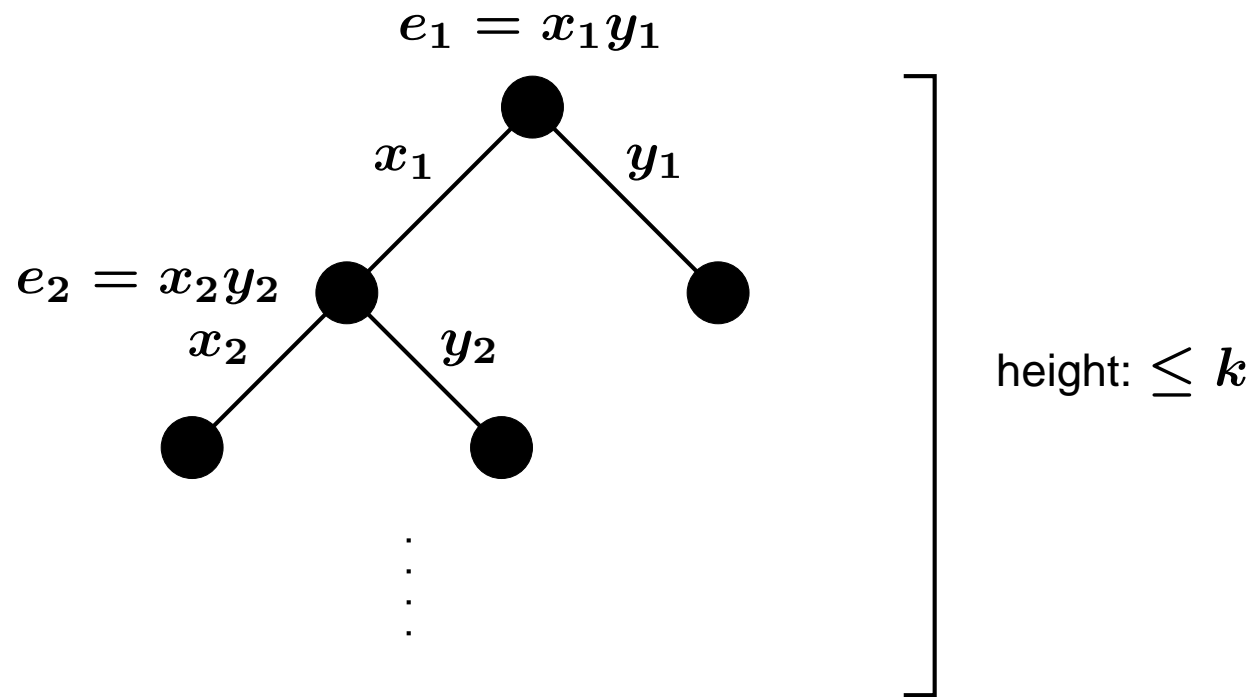
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Algorithm for MINIMUM VERTEX COVER:



Bounded search tree method

Algorithm for MINIMUM VERTEX COVER:



Height of the search tree is $\leq k \Rightarrow$ number of nodes is $O(2^k) \Rightarrow$ complete search requires $2^k \cdot \text{poly steps}$.

Fixed-parameter tractability

Definition: a parameterized problem is fixed-parameter tractable (FPT) if there is an $f(k)n^c$ time algorithm for some constant c .

We have seen that MINIMUM VERTEX COVER is in FPT. Best known algorithm:

$O(1.2832^k k + k|V|)$ [Niedermeier, Rossmanith, 2003]

Main goal of parameterized complexity: to find fixed-parameter tractable problems.

Fixed-parameter tractability

Definition: a parameterized problem is fixed-parameter tractable (FPT) if there is an $f(k)n^c$ time algorithm for some constant c .

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Main goal of parameterized complexity: to find fixed-parameter tractable problems.

Examples of **NP**-hard problems that are in FPT:

- LONGEST PATH
- DISJOINT TRIANGLES
- FEEDBACK VERTEX SET
- GRAPH GENUS
- etc.

Fixed-parameter tractability (cont.)

- ⑥ Practical importance: efficient algorithms for small values of k .
- ⑥ Powerful toolbox for designing FPT algorithms:

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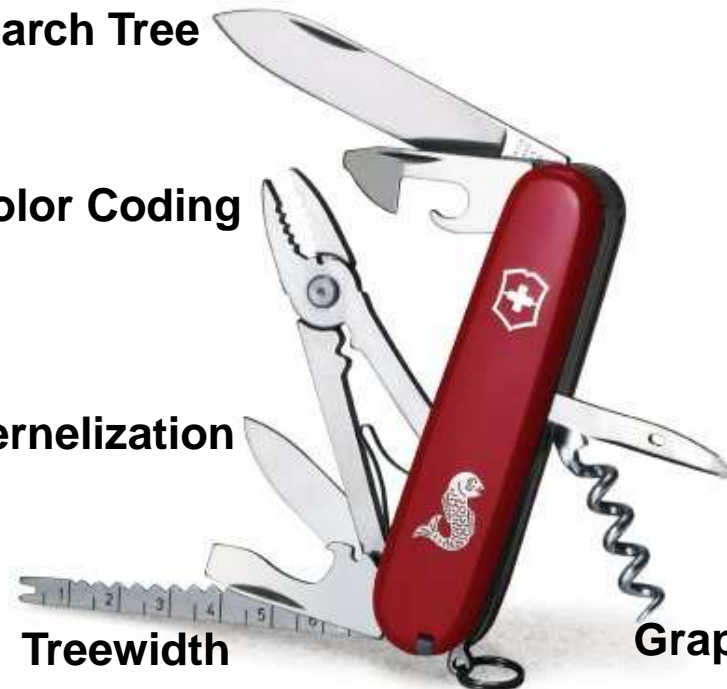
Color Coding

Kernelization

Treewidth

Well-Quasi-Ordering

Graph Minors Theorem



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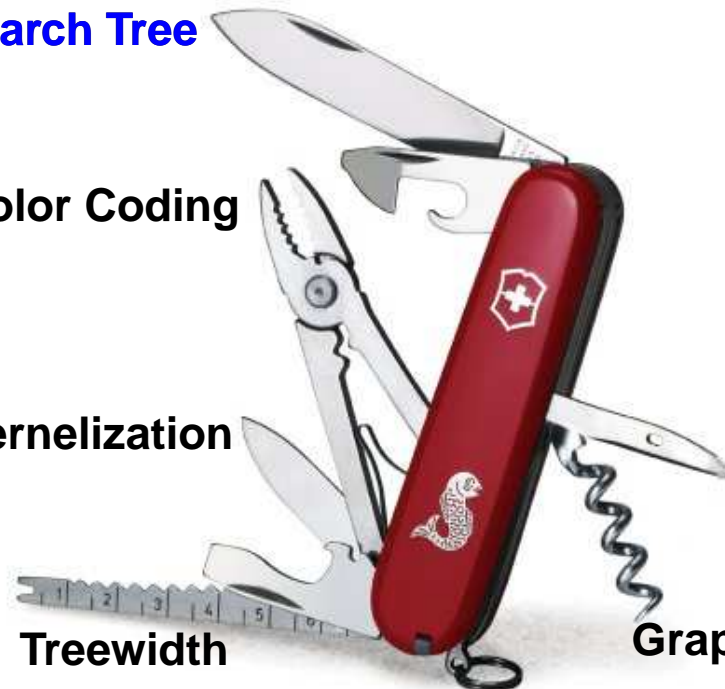
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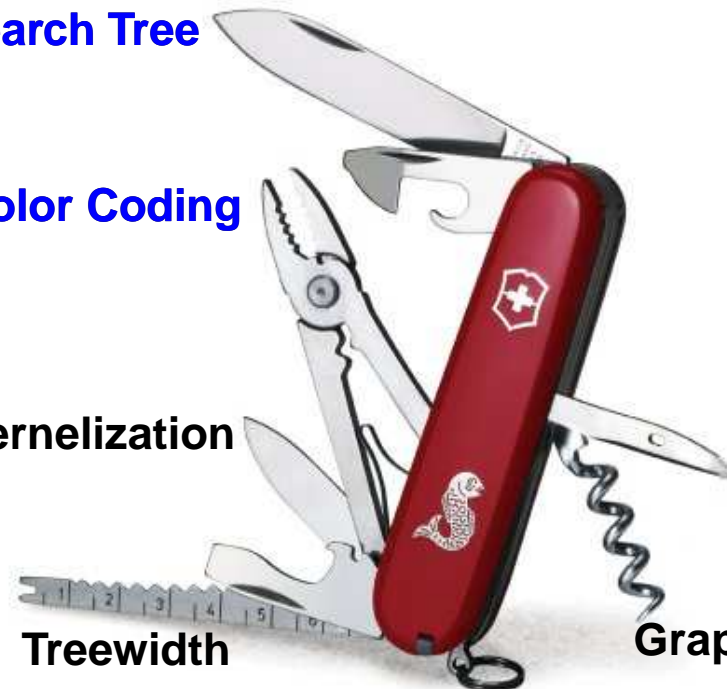
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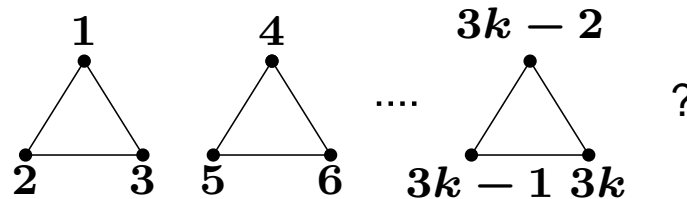
Color Coding: Disjoint Triangles

Task: Find k vertex disjoint triangles in a graph G .

Method:

⑥ Assign random labels $1, 2, \dots, 3k$ to the vertices.

⑥ Are there k triangles such that



The existence of such triangles is easy to check.

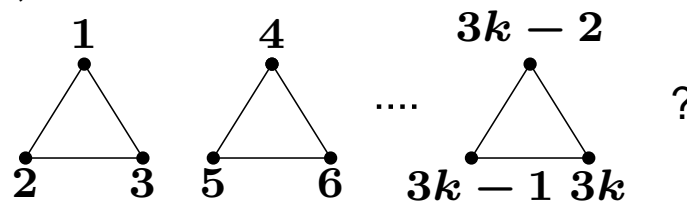
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If there are k disjoint triangles

⇒ with probability $1/(3k)^{3k}$ they are labeled as on the figure

⇒ we need on average $(3k)^{3k}$ random assignments to find the k triangles!

Color coding: useful if we want to select a **small** number of disjoint **small** objects from a **large** list.

Method can be derandomized using families of k -perfect hash functions.

Parameterized intractability

We expect that MAXIMUM INDEPENDENT SET is not fixed-parameter tractable, no $n^{o(k)}$ algorithm is known.

W[1]-complete \approx “as hard as MAXIMUM INDEPENDENT SET”

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Parameterized reductions: L_1 is reducible to L_2 , if there is a function f that transforms (x, k) to (x', k') such that

- ⑥ $(x, k) \in L_1$ if and only if $(x', k') \in L_2$,
- ⑥ f can be computed in $f(k)|x|^c$ time,
- ⑥ **k' depends only on k**

If L_1 is reducible to L_2 , and L_2 is in FPT, then L_1 is in FPT as well.

Most **NP**-completeness proofs are not good for parameterized reductions.

Parameterized Complexity: Summary

Two key concepts:

- ⑥ A parameterized problem is **fixed-parameter tractable** if it has an $f(k)n^c$ time algorithm.
- ⑥ To show that a problem L is hard, we have to give a **parameterized reduction** from a known **W[1]-complete** problem to L .

Constraint satisfaction problems

Let \mathcal{R} be a set Boolean of relations. An \mathcal{R} -formula is a conjunction of relations in \mathcal{R} :

$$R_1(x_1, x_4, x_5) \wedge R_2(x_2, x_1) \wedge R_1(x_3, x_3, x_3) \wedge R_3(x_5, x_1, x_4, x_1)$$

\mathcal{R} -SAT

- Given: an \mathcal{R} -formula φ
- Find: a variable assignment satisfying φ

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$$\mathcal{R} = \{a \neq b\} \Rightarrow \mathcal{R}\text{-SAT} = \text{2-coloring of a graph}$$

$$\mathcal{R} = \{a \vee b, a \vee \bar{b}, \bar{a} \vee \bar{b}\} \Rightarrow \mathcal{R}\text{-SAT} = \text{2SAT}$$

$$\mathcal{R} = \{a \vee b \vee c, a \vee b \vee \bar{c}, a \vee \bar{b} \vee \bar{c}, \bar{a} \vee \bar{b} \vee \bar{c}\} \Rightarrow \mathcal{R}\text{-SAT} = \text{3SAT}$$

Question: \mathcal{R} -SAT is polynomial time solvable for which \mathcal{R} ?

It is **NP**-complete for which \mathcal{R} ?

Schaefer's Dichotomy Theorem (1978)

For every \mathcal{R} , the \mathcal{R} -SAT problem is polynomial time solvable if one of the following holds, and **NP**-complete otherwise:

- ⑥ Every relation is satisfied by the all 0 assignment
- ⑥ Every relation is satisfied by the all 1 assignment
- ⑥ Every relation can be expressed by a 2SAT formula
- ⑥ Every relation can be expressed by a Horn formula
- ⑥ Every relation can be expressed by an anti-Horn formula
- ⑥ Every relation is an affine subspace over $GF(2)$

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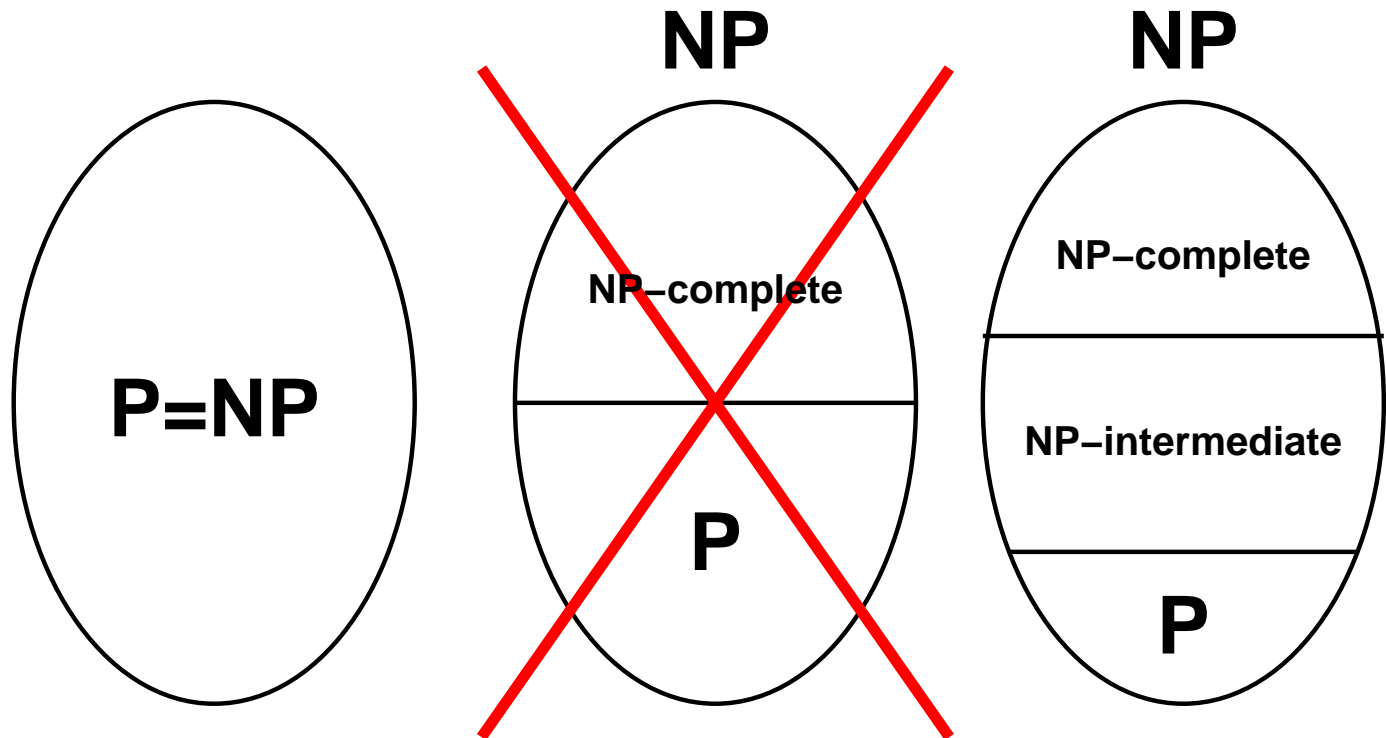
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Why is it surprising?

Ladner's Theorem (1975)

If $P \neq NP$, then there is a language $L \in NP \setminus P$ that is not NP-complete.



Other dichotomy results

- ⑥ Approximability of MAX-SAT, MIN-UNSAT [Khanna et al., 2001]
- ⑥ Approximability of MAX-ONES, MIN-ONES [Khanna et al., 2001]
- ⑥ Generalization to 3 valued variables [Bulatov, 2002]
- ⑥ Inverse satisfiability [Kavvadias and Sideri, 1999]
- ⑥ etc.

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Our contribution: parameterized analogue of Schaefer's dichotomy theorem.

Parameterized version

Parameterized \mathcal{R} -SAT

- ⑥ **Input:** an \mathcal{R} -formula φ , an integer k
- ⑥ **Parameter:** k
- ⑥ **Question:** Does φ have a satisfying assignment of weight exactly k ?

For which \mathcal{R} is there an $f(k) \cdot n^c$ algorithm for \mathcal{R} -SAT?

Main theorem: For every constraint family \mathcal{R} , the parameterized \mathcal{R} -SAT problem is either fixed-parameter tractable or $W[1]$ -complete.
(+ simple characterization of FPT cases)

Technical notes

- ⑥ Are constants allowed in the formula?

E.g., $R(x_1, 0, 1) \wedge R(1, x_2, x_3)$

- ⑥ Can a variable appear multiple times in a constraint?

E.g., $R(x_1, x_1, x_2) \wedge R(x_3, x_3, x_3)$

- ⑥ Constraints that are not satisfied by the all **0** assignment can be handled easily (bounded search tree).

Weak separability

Definition: \mathcal{R} is weakly separable if

1. the union of two disjoint satisfying assignments is also satisfying, and
2. if a satisfying assignment contains a smaller satisfying assignment, then their difference is also satisfying.

Example of 1:

$$R(\mathbf{1}, \mathbf{1}, \mathbf{1}, \mathbf{1}, \mathbf{0}, \mathbf{0}, \mathbf{0}, \mathbf{0}, \mathbf{0}) = 1$$

$$R(\mathbf{0}, \mathbf{0}, \mathbf{0}, \mathbf{0}, \mathbf{1}, \mathbf{1}, \mathbf{0}, \mathbf{0}, \mathbf{0}) = 1$$

⇓

$$R(\mathbf{1}, \mathbf{1}, \mathbf{1}, \mathbf{1}, \mathbf{1}, \mathbf{1}, \mathbf{0}, \mathbf{0}, \mathbf{0}) = 1$$

Example of 2:

$$R(\mathbf{1}, \mathbf{1}, \mathbf{1}, \mathbf{1}, \mathbf{1}, \mathbf{1}, \mathbf{0}, \mathbf{0}) = 1$$

$$R(\mathbf{0}, \mathbf{0}, \mathbf{1}, \mathbf{1}, \mathbf{1}, \mathbf{1}, \mathbf{0}, \mathbf{0}) = 1$$

⇓

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Main theorem: \mathcal{R} -SAT is FPT if and only if every constraint is weakly separable, and W[1]-complete otherwise.

Weak separability: examples

The constraint EVEN is weakly separable:

Property 1:

$$R(\overbrace{1, 1, 1, 1}^{\text{even}}, 0, 0, 0, 0, 0) = 1$$

$$R(0, 0, 0, 0, \underbrace{1, 1}_{\text{even}}, 0, 0, 0) = 1$$

⇓

$$R(\underbrace{1, 1, 1, 1, 1, 1}_{\text{even}}, 0, 0, 0) = 1$$

Property 2:

$$R(\overbrace{1, 1, 1, 1, 1, 1}^{\text{even}}, 0, 0) = 1$$

$$R(0, 0, \underbrace{1, 1, 1, 1}_{\text{even}}, 0, 0) = 1$$

⇓

$$R(\underbrace{1, 1}_{\text{even}}, 0, 0, 0, 0, 0, 0) = 1$$

More generally: every **affine** constraint is weakly separable.

Weak separability: examples (cont.)

The following constraint is trivially weakly separable:

$$R(0, 0, 0, 0, 0) = 1$$

$$R(1, 1, 1, 0, 0) = 1$$

$$R(0, 1, 1, 1, 0) = 1$$

$$R(0, 0, 1, 1, 1) = 1$$

$$R(x_1, x_2, x_3, x_4, x_5) = 0 \text{ otherwise.}$$

Reason: Property 1 and 2 vacuously hold, no disjoint sets, no subsets.

More generally: if the non-zero satisfying assignments are **intersecting** and form a **clutter**, then it is weakly separable.

Example: $R(x_1, \dots, x_n) = 1$ if and only if 0 or exactly t out of n variables are 1
($t > n/2$)

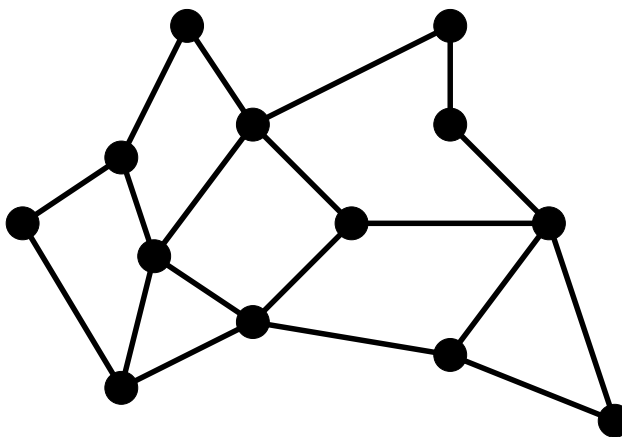
Parameterized vs. classical

The easy and hard cases are different in the classical and the parameterized version:

Constraint	Classical	Parameterized
$x \vee y$	in P	FPT (VERTEX COVER)
$\bar{x} \vee \bar{y}$	in P	W[1]-complete (MAXIMUM INDEPENDENT SET)
affine	in P	FPT
2-in-3	NP-complete	FPT

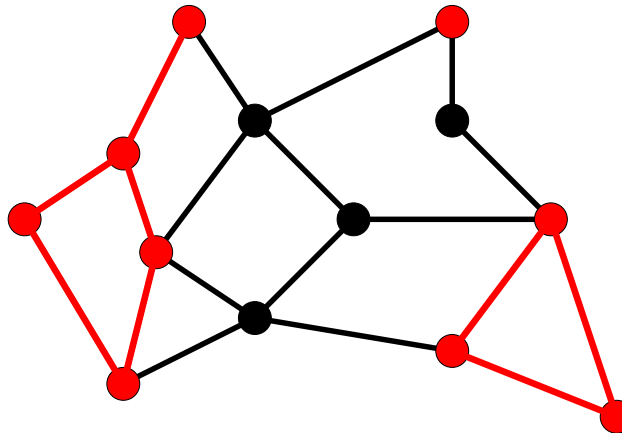
Bounded number of occurrences

Primal graph: Vertices are the variables, two variables are connected if they appear in some clause together.



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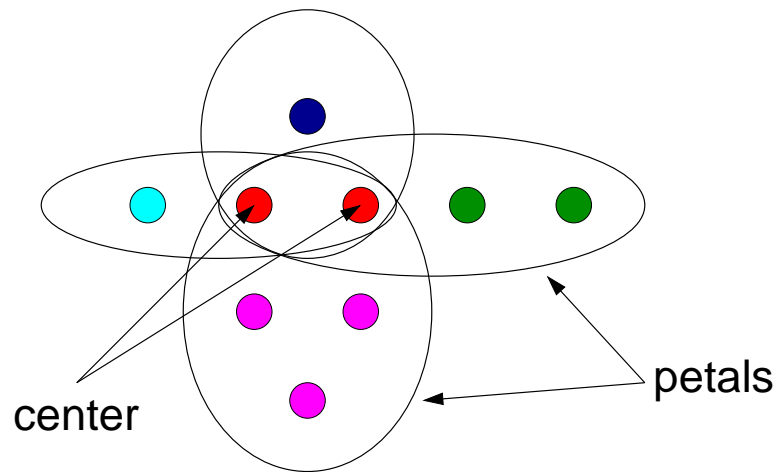
Every satisfying assignment is composed of **connected satisfying assignments**.

Lemma: There are at most $(rd)^{k^2} \cdot n$ connected satisfying assignments of size at most k . (r is the maximum arity, d is the maximum no. of occurrences)

Algorithm: Use color coding to put together the connected assignments to obtain a size k assignment.

The sunflower lemma

Definition: Sets S_1, S_2, \dots, S_k form a **sunflower** if the sets $S_i \setminus (S_1 \cap S_2 \cap \dots \cap S_k)$ are disjoint.



Lemma (Erdős and Rado, 1960): If the size of a set system is greater than $(p - 1)^\ell \cdot \ell!$ and it contains only sets of size at most ℓ , then the system contains a sunflower with p petals.

Sunflower of clauses

Definition: A **sunflower** is a set of k clauses such that for every i

- ⊗ either the same variable appears at position i in every clause,
- ⊗ or every clause “owns” its i th variable.

$$R(x_1, x_2, x_3, x_4, x_5, x_6)$$

$$R(x_1, x_2, x_3, x_7, x_8, x_9)$$

$$R(x_1, x_2, x_3, x_{10}, x_{11}, x_{12})$$

$$R(x_1, x_2, x_3, x_{13}, x_{14}, x_{15})$$

Lemma: If a variable occurs more than $c_{\mathcal{R}}(k)$ times in an \mathcal{R} -formula, then the formula contains a sunflower of clauses with more than k petals.

Plucking the sunflower

For weakly separable constraints, the formula can be reduced if there is a sunflower with $k + 1$ petals. Example:

$$k + 1 \left\{ \begin{array}{l} \text{EVEN}(x_1, x_2, x_3, x_4, x_5, x_6) \\ \text{EVEN}(x_1, x_2, x_3, x_7, x_8, x_9) \\ \text{EVEN}(x_1, x_2, x_3, x_{10}, x_{11}, x_{12}) \\ \text{EVEN}(x_1, x_2, x_3, x_{13}, x_{14}, x_{15}) \end{array} \right.$$

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$$\text{EVEN}(x_1, x_2, x_3)$$

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The algorithm

- ⑥ If there is a variable that occurs more than $c_{\mathcal{R}}(k)$ times:
 - △ Find a sunflower with $k + 1$ petals
 - △ Pluck the sunflower \Rightarrow shorter formula
- ⑥ If every variable occurs at most $c_{\mathcal{R}}(k)$ times:
 - △ Apply the bounded occurrence algorithm

Running time: $2^{k^{r+2} \cdot 2^{2^{O(r)}}} \cdot n \log n$, where r is the maximum arity in the constraint family \mathcal{R} .

Hardness results: case 1

Definition: R is weakly separable if

1. the union of two disjoint satisfying assignments is also satisfying, and
2. if a satisfying assignment contains a smaller satisfying assignment, then their difference is also satisfying.

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If property 1 is violated:

$$R(0, 0, 0, 0, 0, 0, 0, 0) = 1$$

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$$R(x, x, x, y, y, 0, 0, 0) = 1 \iff \bar{x} \vee \bar{y}$$

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MAXIMUM INDEPENDENT SET

\Rightarrow can be expressed!

Hardness results: case 2

Definition: R is weakly separable if

1. the union of two disjoint satisfying assignments is also satisfying, and
2. if a satisfying assignment contains a smaller satisfying assignment, then their difference is also satisfying.

If property 2 is violated:

$$R(0, 0, 0, 0, 0, 0, 0, 0) = 1$$

$$R(1, 1, 1, 1, 1, 0, 0, 0) = 1$$

$$R(0, 0, 0, 1, 1, 0, 0, 0) = 1$$

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↓

$$R(x, x, x, y, y, 0, 0, 0) = 1 \iff x \rightarrow y$$

Hardness results: case 2

Definition: R is weakly separable if

1. the union of two disjoint satisfying assignments is also satisfying, and
2. if a satisfying assignment contains a smaller satisfying assignment, then their difference is also satisfying.

If property 2 is violated:

$$R(0, 0, 0, 0, 0, 0, 0, 0) = 1$$

$$R(1, 1, 1, 1, 1, 0, 0, 0) = 1$$

$$R(0, 0, 0, 1, 1, 0, 0, 0) = 1$$

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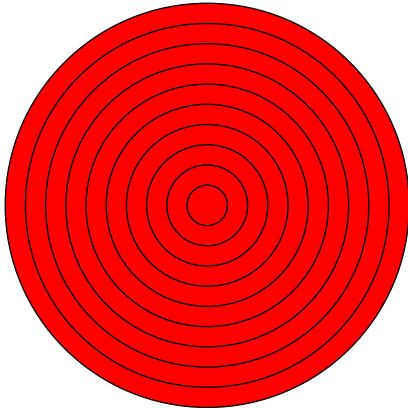
↓

$$R(x, x, x, y, y, 0, 0, 0) = 1 \iff x \rightarrow y$$

Lemma: The problem is
W[1]-complete for the
constraint \rightarrow .

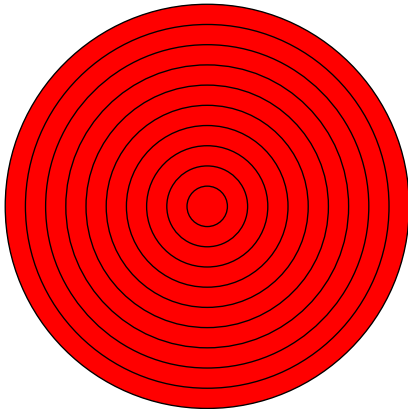
Planar formulae

If the primal graph of the formula is **planar**, then the layering method of Baker can be used.



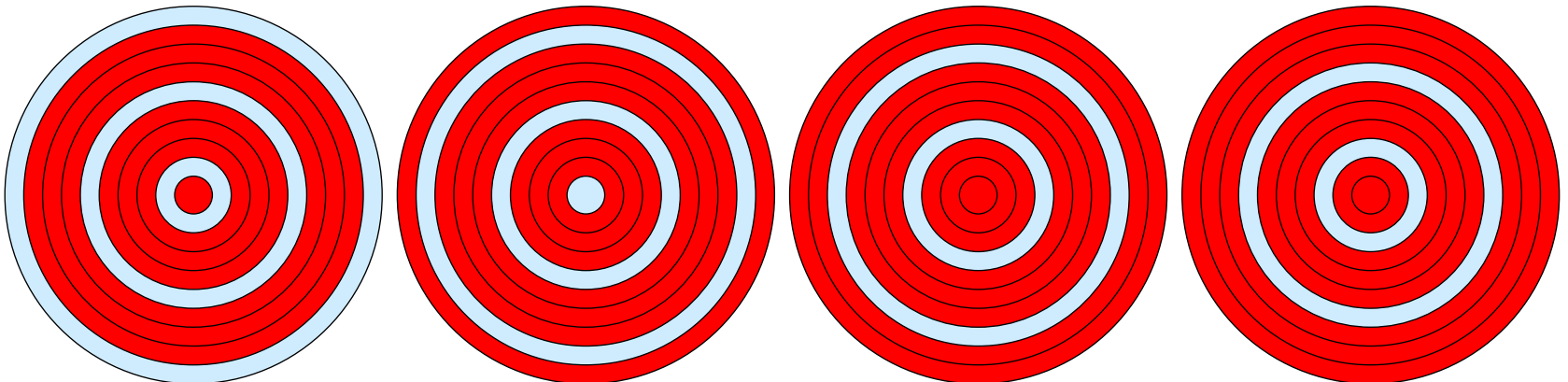
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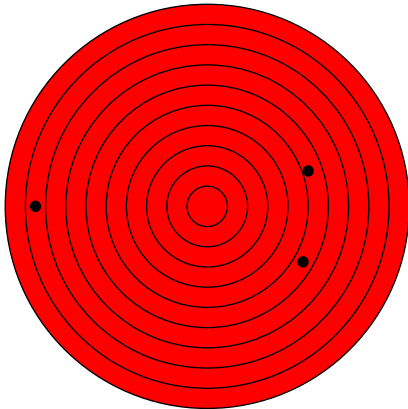
Set to 0 the variables in every $(k + 1)$ th layer.
There are $k + 1$ ways of doing this.
One of them will not hurt the solution.

Example with $k = 3$:



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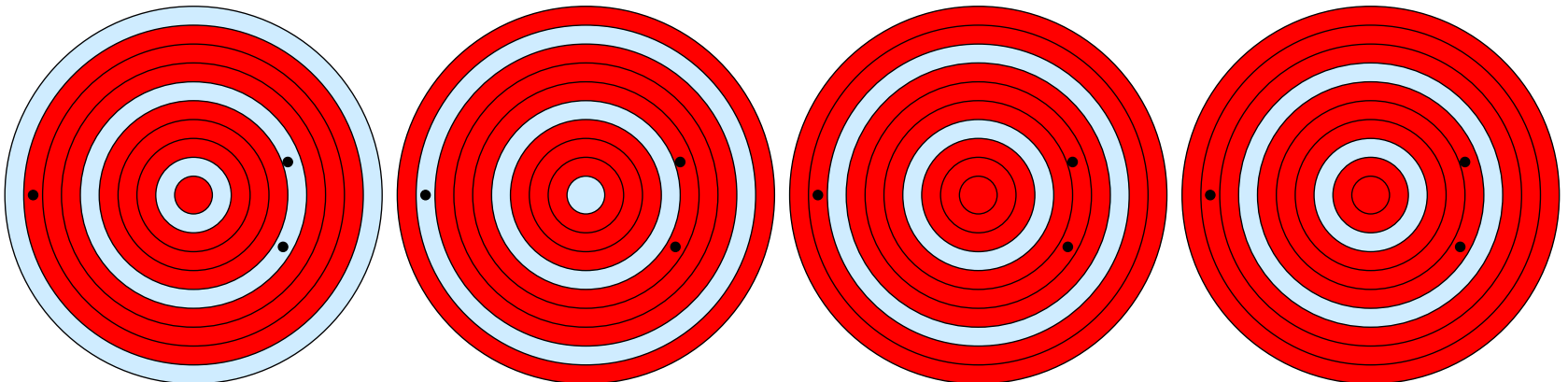


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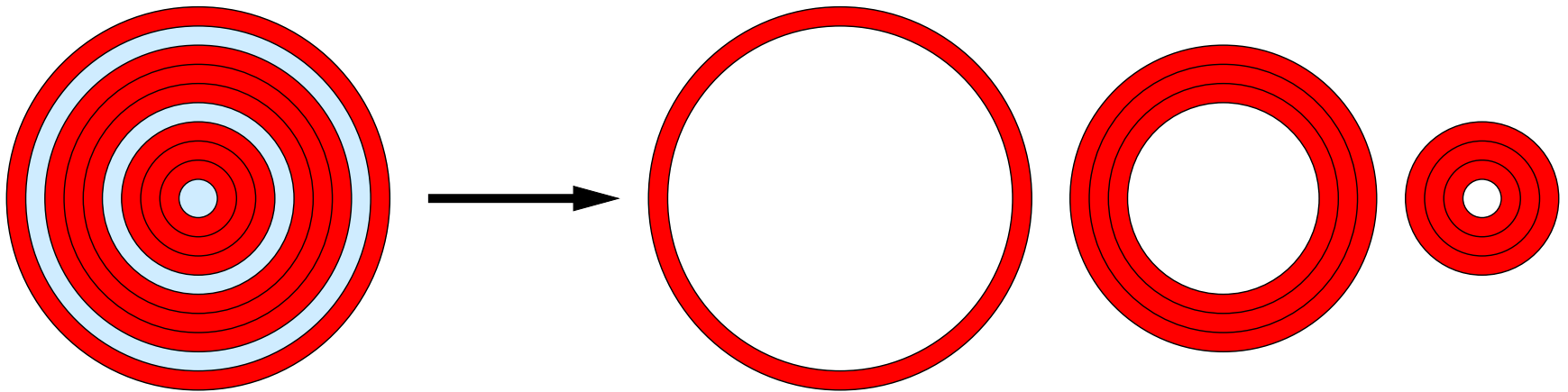
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Planar formulae (cont.)

If we delete every $(k + 1)$ th layer, then the remaining formula has only k layers:

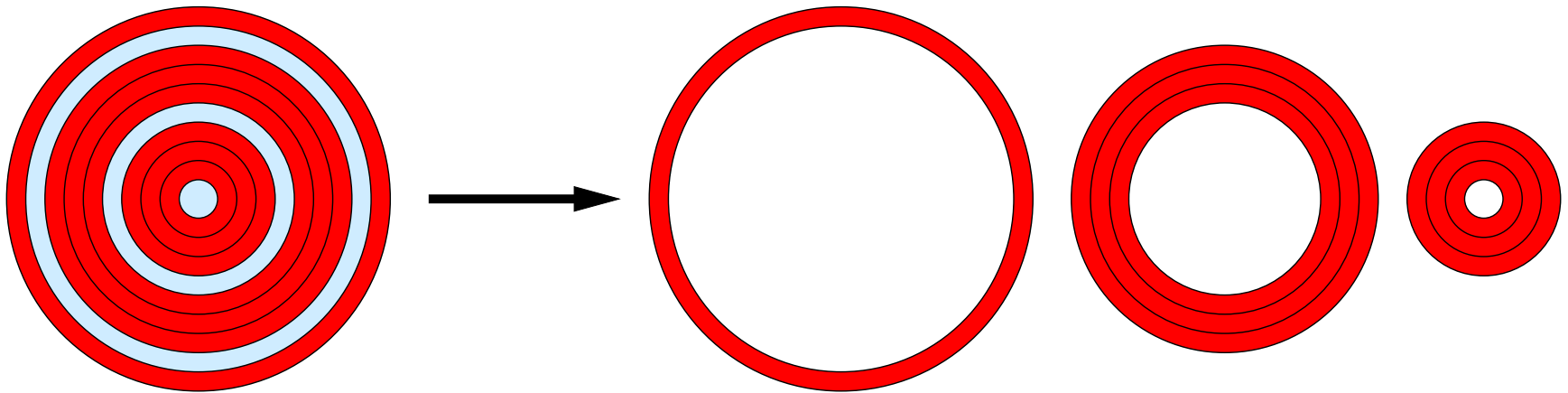


Lemma (Bodlaender): The treewidth of a k -layered graph is at most $3k - 1$.

If the primal graph has bounded treewidth, then the problem can be solved in linear time using standard techniques.

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Incidence graph: bipartite graph, vertices are the clauses and the variables, edge means “appears in”.

Theorem: Linear time alg. if the incidence graph of the formula is planar.

Summary

- ⑥ Parameterized version of \mathcal{R} -SAT
- ⑥ FPT or $W[1]$ -complete depending on weak separability
- ⑥ Bounded occurrences: color coding using connected solutions
- ⑥ Reduction using the sunflower lemma
- ⑥ Linear time solvable for planar and bounded treewidth formulae

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Thank you for your attention!
Questions?