

# FDBG, the CLP( $\mathcal{FD}$ ) Debugger Library of SICStus Prolog

Péter Szeredi, Dávid Hanák, Tamás Szeredi  
Budapest University of Technology and Economics  
szeredi@cs.bme.hu, {dhanak,tszeredi}@inf.bme.hu



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# Introduction

# CLP( $\mathcal{FD}$ ) and Debugging

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- CLP( $\mathcal{FD}$ ) implementations:
  - ★ Designated development environments (e.g. OPL Studio);
  - ★ Embedded into a host language – Prolog is a logical choice (backtracking, logic variables).
- CLP( $\mathcal{FD}$ ) and debugging in SICStus Prolog:
  - ★ Extensive CLP( $\mathcal{X}$ ) libraries, including CLP( $\mathcal{FD}$ );
  - ★ An excellent, flexible, extensible debugger for Prolog;
  - ★ minimal support for CLP( $\mathcal{X}$ ) debugging (until FDBG).
- Possible approaches to observe a CLP( $\mathcal{FD}$ ) run:
  - ★ interactive tools (e.g. step-by-step debuggers);
  - ★ assertion based methods;
  - ★ *trace generation* and analysis – ideal for nonlinear program execution, like in the case of CLP( $\mathcal{FD}$ ).

# FDBG and its Event Trace

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- FDBG = Finite domain DeBuGger
- Main purpose: enable  $CLP(\mathcal{FD})$  programmers to gather information about constraints and variables possibly even without modifying the observed program.
- FDBG translates the run of a  $CLP(\mathcal{FD})$  program into an event trace:
  - ★ a sequence of log entries;
  - ★ each entry corresponds to a  $CLP(\mathcal{FD})$  event;
  - ★ an event represents:
    - \* the activity of a *constraint* and its effect on variables;
    - \* a *labeling* decision while exploring the search tree.
  - ★ appearance of entries is fully customizable.

# A Sample Session with FDBG

---

| ?-

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```
| ?- use_module(library(clpfd)), use_module(library(fdbg)),  
     fdbg_on.
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| ?- X #< 6, X #> 3, labeling([], [X]).
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<fdvar_1> in inf..5  
      fdvar_1 = inf..sup -> inf..5  
      Constraint exited.
```

```
<fdvar_1> in 4..sup  
      fdvar_1 = inf..5 -> 4..5  
      Constraint exited.
```

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<fdvar_1> in 4..sup  
      fdvar_1 = inf..5 -> 4..5  
      Constraint exited.
```

```
Labeling [3, <fdvar_1>]: starting in range 4..5.  
Labeling [3, <fdvar_1>]: step: <fdvar_1> = 4  
X = 4 ? ;  
Labeling [3, <fdvar_1>]: step: <fdvar_1> >= 5  
X = 5 ? ;  
Labeling [3, <fdvar_1>]: failed.
```

# Basic Concepts

## CLP( $\mathcal{FD}$ ) Events

---

- CLP( $\mathcal{FD}$ ) problem solving consists of two repeated phases:
  - ★ narrowing a variable domain due to constraint propagation;
  - ★ narrowing a variable domain due to labeling.
- Observation: with *two classes of events* we can describe the behavior of a CLP( $\mathcal{FD}$ ) program:
  - ★ constraint events
    - \* a constraint is woken up and performs propagation;
  - ★ labeling events
    - \* a choicepoint is created or exhausted (through failure);
    - \* the domain of a variable is narrowed.
- Events are intercepted and dispatched to *visualizers* by the FDBG core.

# Visualizers

---

- Predicates responsible for handling CLP( $\mathcal{FD}$ ) events;
- Usually display trace information;
- In general can do any kind of processing (like checking invariants);
- Analogously to event classes, there are two types:
  - ★ constraint visualizers;
  - ★ labeling visualizers.
- FDBG provides default built-in visualizers for both types;
- Utility predicates support writing custom visualizers.

# The User Interface

# An Example – The N-queens Problem

---

```
nqueens(N, Queens) :-
    bb_put(board_size, N),
    length(Queens, N),
    fdbg_assign_name(Queens, queen),
    domain(Queens, 1, N),
    constrain_all(Queens),
    %      asiymmetric(N, Queens),          % break symmetry
    labeling([ff], Queens).

...

no_threat(X, Y, I) :-
    fd_global(no_threat(X,Y,I), 1, [val(X),val(Y)]).

:- multifile clpfd:dispatch_global/4.
clpfd:dispatch_global(no_threat(X,Y,I), S, S, Actions) :-
    (   integer(X) -> no_threat_prop(Y, X, I, Actions)
    ;   integer(Y) -> no_threat_prop(X, Y, I, Actions)
    ;
      Actions = []
    ).

...
```



## Built-in Visualizers

---

- FDBG uses built-in visualizers by default;
- Built-in visualizers can work without any program modification.

### One block of output of the constraint visualizer

```
no_threat(2, <queen_3>, 2)
  queen_3: 1..2 -> {1}
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*Legend:* domain narrowings;  
constraint behavior.

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<code>no_threat(2, &lt;queen_3&gt;, 2)</code>	The constraint itself;
<code>queen_3: 1..2 -&gt; {1}</code>	<i>Legend:</i> domain narrowings;
Constraint exited.	constraint behavior.

#### Details:

- The legend lists *all* the variables of the constraint;
- Most common behaviors are entailment (above) and failure.
- Variable names:
  - ★ all variables are assigned a name for clarity;
  - ★ needed because name in source is not preserved in Prolog;
  - ★ usually displayed between angle brackets (<queen\_3>).

## Built-in Visualizers – cont.

---

### Output of the labeling visualizer

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Labeling [3, <fdvar_1>]: starting in range 4..5.  
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### Details:

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- This is followed by a specification of the event:
  - ★ choicepoint creation (start);



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  - ★ failure.

# Variable Naming

---

- Variables are assigned a name:
  - ★ manually by calling `fdbg_assign_name/2`;
  - ★ automatically when calling `fdbg_annotate/2,3`;
  - ★ auto-assigned names look like `fdvar_N` ( $N$  unique counter).
- Names are primarily used to refer to variables in the trace;
- This done via *annotation*: each variable in a term is replaced by a term containing its name, itself, and its narrowed domain;
- Convenience service: assign names to an entire term and each variable in it with a single call:

term/variable	selector	name	
<code>bar(A, [B, C])</code>	<code>[]</code>	<code>foo</code>	assigned name

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<code>A</code>	<code>[1]</code>	<code>foo_1</code>	} implicit derived names
<code>B</code>	<code>[2,#1]</code>	<code>foo_2_1</code>	
<code>C</code>	<code>[2,#2]</code>	<code>foo_2_2</code>	

# Customizing Visualizers

---

- Built-in visualizers have no knowledge of the problem structure;
- Customized visualization can exploit this additional knowledge;
- Customization is possible on two levels:
  - ★ slight modification of the output of the built-in visualizers by defining hook predicates;
  - ★ writing custom visualizers.
- Use a hook predicate to modify the legend of *N-queens*:
  - ★ 

```
no_threat(2,<queen_3>,2)
      queen_3: [ X - . . ]
      Constraint exited.
```
- Or a custom visualizer to completely redefine it:
  - ★ 

```
no_threat(4,<queen_3>,1)
      [ X X . . ]
      [ . . . X ]
      [ X X - - ]
      [ X X X X ]
```

# Legend Portray Hook

---

```
fdbg:legend_portray(Name, Var, After) :-  
    write(Name), write(': '),  
    print_row(Var, After).
```

```
print_row(Var, After) :-  
    bb_get(board_size, N),  
    fd_set(Var, Now),  
    write('[ '), print_fields(1, N, Now, After), write('] ').
```

```
print_fields(I, N, _, _) :-  
    I > N, !, write(' ').
```

```
print_fields(I, N, Now, After) :-  
    write(' '),  
    (    fdset_member(I, After) -> write('X') % allowed  
    ;    fdset_member(I, Now)   -> write('-') % being pruned  
    ;                                     write('.') % pruned  
    ),  
    I1 is I+1,  
    print_fields(I1, N, Now, After).
```

# Custom Visualizer

---

```
nqueens_show(Constraint, Actions) :-  
    fdbg_current_name(Queens, queen),  
    fdbg_annotate(Constraint, AConst, _),  
    fdbg_annotate(Queens, Actions, AQueens, _),  
    print(AConst), nl,  
    print_board(AQueens).
```

```
print_board([]) :- nl.  
print_board([fdvar(_,Var,After)|Qs]) :- !,  
    write('    '),  
    print_row(Var, After), nl,  
    print_board(Qs).  
print_board([V|Qs]) :-  
    write('    '),  
    fdset_singleton(Set, V),  
    print_row(V, Set), nl,  
    print_board(Qs).
```

# Implementation Issues



## Event detection

---

- SICStus debugger provides *advice points*: programmable breakpoints;
- FDBG places advice points on all constraint handling predicates;
- Limitation: only *global constraints* are handled, *indexicals* are ignored;
- Workaround: when FDBG is turned on, constraints otherwise compiled as indexicals translate into global constraints (through *goal expansion*);
- Consequences:
  - ★ FDBG should be consulted before the program to be traced;
  - ★ Negligible effect on performance compared to overhead of FDBG in general;
  - ★ Minor behavioral changes (slightly different propagation);
  - ★ Original form of constraints is lost in the process.

# Variable Naming Revisited

---

## Reminder

- Names can be assigned by the user to any term or variable;
- Visualizers refer to variables with names exploiting *annotation*;
- *Annotation* is the process of replacing variables in a term with descriptive compound terms.

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## Reminder

- Names can be assigned by the user to any term or variable;
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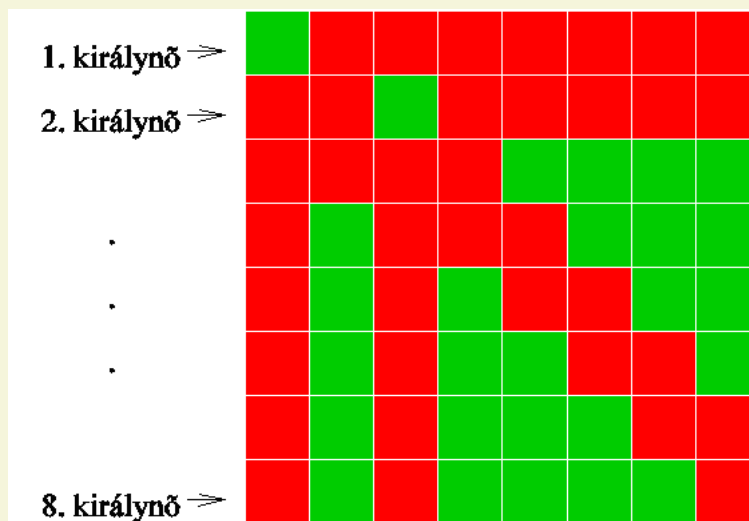
## Implementation

- Names are stored in an AVL tree in the *global private* field;
- As a result, the name store is *volatile* (fresh for each query);
- Consequences:
  - ★ No need to clear the name store after each query (good);
  - ★ Need to assign names in each query (seemingly inconvenient but unavoidable: different variables!);
  - ★ The best place to do this is within the program itself.

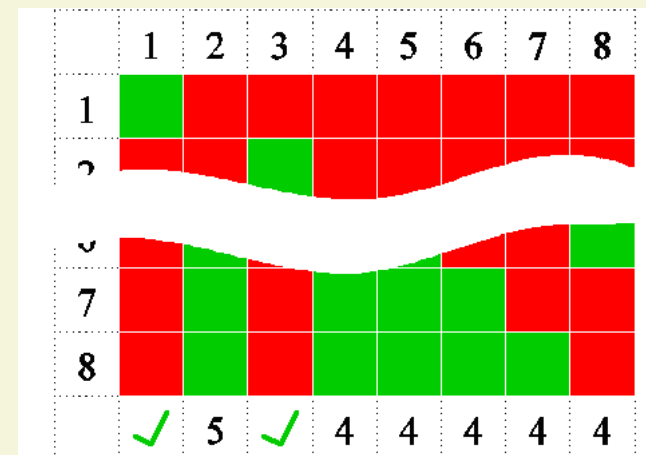
## **Future Work and Conclusions**

# Future Work

- Indexical to global constraint redirection fails to preserve original form of constraints – need to find an acceptable solution;
- When labeling fails, there is no information in the log about what state the domains of variables are *restored* to through backtracking;
- A generic, configurable graphical visualizer – plans have already been proposed, still need to implement it.



Basic 2-dimensional visualization



Embellished version

## Conclusions

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- Presented basic tracing scheme for CLP( $\mathcal{FD}$ ) programs written in SICStus Prolog;
- Introduced events and visualizers;
- Showed how variable naming and output customization can help to clarify the trace log;
- Given examples to visualizer customization;
- Covered a few implementational details;
- Sketched possible directions of future development.

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**Thanks for your attention!**