Finding Topological Subgraphs is Fixed-Parameter Tractable

Martin Grohe Institut für Informatik Humboldt-Universität zu Berlin Unter den Linden 6 10099 Berlin, Germany grohe@informatik.huberlin.de

Dániel Marx[†] Institut für Informatik Humboldt-Universität zu Berlin Unter den Linden 6 10099 Berlin, Germany dmarx@informatik.huberlin.de

ABSTRACT

We prove that for every fixed undirected graph H, there is an $O(|V(G)|^3)$ time algorithm that, given a graph G, tests if G contains H as a topological subgraph (that is, a subdivision of H is subgraph of G). This shows that topological subgraph testing is fixed-parameter tractable, resolving a longstanding open question of Downey and Fellows from 1992. As a corollary, for every H we obtain an $O(|V(G)|^3)$ time algorithm that tests if there is an immersion of H into a given graph G. This answers another open question raised by Downey and Fellows in 1992.

Categories and Subject Descriptors

F.2 [**Theory of Computing**]: Analysis of Algorithms and Problem Complexity

General Terms

Algorithms

Keywords

topological minors, fixed-parameter tractability

Copyright 2011 ACM 978-1-4503-0691-1/11/06 ...\$10.00.

Ken-ichi Kawarabayashi* National Institute of Informatics 2-1-2 Hitotsubashi, Chiyoda-ku Tokyo 101-8430, Japan k_keniti@nii.ac.jp

Paul Wollan Department of Computer Science University of Rome, *La Sapienza* Via Salaria 113 Rome, 00198 Italy wollan@di.uniroma1.it

1. Introduction

A graph *H* is a *topological subgraph* (or *topological minor*) of graph *G* if a subdivision of *H* is a subgraph of *G*. Equivalently, *H* is a topological subgraph of *G* if *H* can be obtained from *G* by deleting edges, deleting vertices, and dissolving degree 2 vertices (which means deleting the vertex and making its two neighbors adjacent). This notion appears for example in the classical result of Kuratowski in 1935 stating that a graph is planar if and only if it does not have a topological subgraph isomorphic to K_5 or $K_{3,3}$.

Given graphs H and G, it is NP-complete to decide if H is a topological subgraph of G (e.g., a cycle of length |V(G)| is a topological subgraph of G if and only if G is Hamiltonian). On the other hand, our main result gives a cubic algorithm for every fixed H:

THEOREM 1.1. For every fixed undirected graph H, there is a $O(|V(G)|^3)$ time algorithm that decides if H is a topological subgraph of G.

Actually, our algorithm is uniform in H, and this shows that the problem of testing if H is a topological subgraph of G is fixedparameter tractable parameterized by the number of vertices of H. Recall that a problem is *fixed-parameter tractable* by some parameter k if it can be solved in time $f(k) \cdot n^{O(1)}$ for a function f depending only on k. Thus Theorem 1.1 answers a longstanding open question, first raised in 1992 by Downey and Fellows [3] and then restated at many places, including the open problem list of the monograph [4]. The problem of testing for topological subgraphs, which is also known as the subgraph homeomorphism problem, was already studied in the 1970s by Lapaugh and Rivest [10] (also see [7]). Fortune, Hopcroft, and Wyllie [6] studied the directed version of the problem and showed that there are simple digraphs Hsuch that the problem of testing whether a given digraph G contains H as a (directed) topological subgraph is NP-complete. In a major breakthrough, Robertson and Seymour [11] proved that this cannot happen for undirected graphs: For every (undirected) graph H there is a polynomial time algorithm testing whether a given graph Gcontains H as a topological subgraph. (We will discuss Robertson and Seymour's result in more detail below.) However, the running time of Robertson and Seymour's algorithm is $|V(G)|^{|V(H)|}$. This

^{*}Research partly supported by Japan Society for the Promotion of Science, Grant-in-Aid for Scientific Research, by Kayamori Foundation and by Inoue Research Award for Young Scientists.

[†]Research supported in part by ERC Advanced grant DMMCA, the Alexander von Humboldt Foundation, and the Hungarian National Research Fund (Grant Number OTKA 67651).

Permission to make digital or hard copies of all or part of this work for personal or classroom use is granted without fee provided that copies are not made or distributed for profit or commercial advantage and that copies bear this notice and the full citation on the first page. To copy otherwise, to republish, to post on servers or to redistribute to lists, requires prior specific permission and/or a fee.

STOC'11, June 6-8, 2011, San Jose, California, USA.

prompted Downey and Fellows' questions of whether the problem is fixed-parameter tractable. Our Theorem 1 answers this question.

We also study the related problem of testing for immersed subgraphs. An *immersion* of a graph *H* into a graph *G* is defined like a topological embedding, expect that the paths in *G* corresponding to the edges of *H* are only required to be edge disjoint instead of internally vertex disjoint. Formally, an immersion of *H* into *G* is a mapping α that associates with each vertex $v \in V(H)$ a distinct vertex $\alpha(v) \in V(G)$ and with each edge $e = vw \in E(H)$ a path $\alpha(e)$ in *G* with endpoints $\alpha(v)$ and $\alpha(w)$ in such a way that the paths $\alpha(e)$ for $e \in E(H)$ are mutually edge disjoint. Robertson and Seymour [14] showed that graphs are well-quasi-ordered under the immersion relation, proving a conjecture of Nash-Williams. Here we obtain the following algorithmic result as a corollary to Theorem 1.1:

COROLLARY 1.2. For every fixed undirected graph H, there is a $O(|V(G)|^3)$ time algorithm that decides if there is an immersion of H into G.

Again, our algorithm is uniform in H, which implies that the immersion problem is fixed-parameter tractable. This answers another open question by Downey and Fellows [3, 4]. Corollary 1.2 also holds for the more restrictive "strong immersion" version, where $\alpha(v)$ cannot be the internal vertex of $\alpha(e)$ for any $v \in V(G)$ and $e \in E(G)$.

Yet another related problem is minor containment testing. We say that graph H is a *minor* of G if H can be obtained from G by deleting vertices, deleting edges, and contracting edges. A celebrated result of Robertson and Seymour [11] shows that for every fixed H, there is a $O(|V(G)|^3)$ time algorithm for testing if H is a minor of G. Their algorithm actually solves a more general rooted version of the problem. This rooted version contains as a special case the k-DISJOINT PATHS problem, where given pairs (s_1, t_1) , ..., (s_k, t_k) of vertices, the task is to find vertex disjoint paths P_1 , ..., P_k such that P_i connects s_i and t_i . It is not difficult to reduce testing if H is a topological subgraph of G to k-DISJOINT PATHS. For each vertex v of H, we guess a vertex v' of G, and then for each edge uv of H, we find a path connecting u' and v' in G such that these |E(H)| paths are pairwise internally disjoint. This approach vields the $|V(G)|^{O(|V(H)|)}$ time algorithm for topological subgraph testing mentioned above.

Our algorithm for finding topological subgraphs follows the general framework of Robertson and Seymour for minor testing, but it deviates from it significantly. Let us give a very high-level overview of Robertson and Seymour's algorithm [11]. If the treewidth of G is "small," then standard techniques allow us to solve the problem in linear time. If the treewidth of G is "large," then we find an *irrel*evant vertex whose deletion provably does not change the answer to the problem. By iteratively finding and deleting irrelevant vertices, we eventually arrive to a G whose treewidth is small. To find an irrelevant vertex if the treewidth of G is large, we use the the so-called Weak Structure Theorem, which allows us either to find a large clique minor or to show that the graph has a large "flat wall." The case of a large clique minor is easy to handle: if there are no roots, then it immediately solves the problem (as every small graph appears in the large clique minor) and even if roots are present, we can argue that a large part of the clique is irrelevant. The most difficult part of the algorithm is to deal with the case of a flat wall and to identify an irrelevant vertex there. Indeed, this case needs the majority of the work. The analysis of this case requires the whole series of Graph Minor papers and the structure theorem of [12]. Very recently, a significantly simpler treatment of this case was presented in [9].

Let us now give an overview for our algorithm. The case of small treewidth goes through for topological minor testing without any difficulty. The new proof in [9] for minor testing in the case when there is no large clique minor can be adapted for topological minor testing. Specifically, for the case where there is a large flat wall, using the unique linkage theorem [13] and its much shorter proof [9], we can indeed find an irrelevant vertex in the middle of the large flat wall. This case is similar to that for the minor testing, however, we may need to change almost all of the branch vertices of a given topological minor inside the flat wall. This gives rise to some amount of technical difficulties, which we overcome in this paper. Let us emphasis that our proof of the correctness for our algorithm does not depend on the full power of the graph minor structure theorem [12], while Robertson and Seymour's analysis for their algorithm does need the whole series of Graph Minor papers and the structure theorem of [12]. Utilizing some results in [9], we are able to avoid the much of the heavy machinery of the graph minor structure theory.

Let us now look at the case when there is a large clique minor. Identifying a large clique minor was an easy situation to handle in the case of finding minors, but it is not obvious how it is of any use in the case of finding topological subgraphs. The problem is that the degrees of the vertices matter much more in finding topological subgraphs than in finding minors. If H is, say, 4-regular and we have found a large clique minor in a part of G that contains only degree-3 vertices, then this clique minor does not immediately solve the problem. Furthermore, as G can contain many vertices of degree at least 4 close to this clique minor and each such vertex is potentially the image of some vertex of H, there is no easy argument that shows that some part of the clique is irrelevant. We circumvent these problems by introducing a new operation that was not present in the framework of [11]. If a small number of vertices can separate away a large part of the graph, then we recursively "understand" this part and then replace it with an equivalent smaller graph. We show that if no such step can be performed, then we can completely understand how the large clique minor can be used by a topological subgraph. This new operation and the associated recursion changes the high-level structure of our algorithm considerably: unlike in [11], it is no longer just an iterative removal of irrelevant vertices.

Similarly to [11], we define and solve a very general rooted version of the problem ("finding folios"). It is important to point out that we are solving this rooted generalization not (only) for the sake of obtaining maximum generality of the result. In the recursion steps involving separators, we argue about topological subgraphs using the separator in a certain way, and the concept of roots is needed to express these requirements.

Due to the page limitations of this extended abstract, we discuss in detail only the main algorithmic framework (Section 3), the case of handling a large clique minor (Section 4), and the reduction from immersion testing to finding topological subgraphs. These are the parts that contain the most significant differences compared to minor testing. While the case of handling a large flat wall also required overcoming significant technical difficulties, the treatment of this case appears in the full version.

2. Folios

All graphs in this paper are finite and simple: they do not have loops or parallel edges (but can have isolated vertices). A *rooted* graph is an undirected graph G with a set $R(G) \subseteq V(G)$ of vertices specified as roots and an injective mapping $\rho_G : R(G) \to \mathbb{N}$ assigning a distinct positive integer label to each root vertex. Isomorphism of rooted graphs are defined the obvious way, i.e., roots must be mapped to roots with the same label. We say that two rooted graphs G_1 and G_2 are *compatible* if $\rho_{G_1}(R(G_1)) = \rho_{G_2}(R(G_2))$, i.e. the same set of positive integers appear on G_1 and G_2 (which means in particular that $|R(G_1)| = |R(G_2)|$).

We say that rooted graph *H* is a *topological minor* of rooted graph *G* if there is a mapping ϕ (a *model* of *H* in *G*) that assigns to each $v \in V(H)$ a vertex $\phi(v) \in V(G)$ and to each $e \in E(G)$ a path $\phi(e)$ in *G* such that

- (1) The vertices $\phi(v)$ ($v \in V(H)$) are distinct.
- (2) If $u, v \in V(H)$ are the endpoints of $e \in E(H)$, then path $\phi(e)$ connects $\phi(u)$ and $\phi(v)$.
- (3) The paths φ(e) (e ∈ E(H)) are pairwise internally vertex disjoint, i.e., the internal vertices of φ(e) do not appear as an (internal or end) vertex of φ(e') for any e' ≠ e.
- (4) For every $v \in R(H)$, $\rho_G(\phi(v)) = \rho_H(v)$.

Even if H is a topological minor of G, they are not necessarily compatible: G can have more root vertices than H.

The *folio* of *G* is the set of all topological minors of *G*. Clearly, the folio is closed under isomorphism, i.e., if rooted graphs *H* and *H'* are isomorphic and *H* is in the folio of *G*, then *H'* is in the folio as well. If $\delta \ge 0$ is an integer, then the δ -*folio* of *G* contains every topological minor *H* of *G* with $|E(H)| + is(H) \le \delta$, where is(*H*) is the number of isolated vertices of *H*. Obviously, every graph in the δ -folio has at most 2δ vertices.

OBSERVATION 2.1. The number of distinct graphs (up to isomorphism) in the δ -folio of G can be bounded by a function of δ and |R(G)|.

There are $2^{\binom{|R(G)|}{2}}$ possible undirected graphs on R(G). For each such graph *X*, we slightly abuse notation by defining G + X to be the graph on V(G) having edge set $E(G) \cup E(X)$. The rooted graph G+X has a δ -folio, which may or may not be different from the δ -folio of *G*. The $2^{\binom{|R(G)|}{2}}$ -tuple of all these δ -folios will be called the *extended* δ -folio of *G*. To extended δ -folios are considered equal if the folios are equal for each choice of the set *X*.

Given an extended δ -folio \mathcal{F} , a *representative* of \mathcal{F} is a rooted graph G whose extended δ -folio is \mathcal{F} . We define the constant $L_{\delta,r}$ to be the smallest integer such that for every rooted graph G with at most r roots, the extended δ -folio of G has a representative on at most $L_{\delta,r}$ vertices. It is clear that $L_{\delta,r}$ is finite.

LEMMA 2.2. There is a computable function $\ell(\delta, r)$ with $L_{\delta,r} \leq \ell(\delta, r)$ for every $\delta, r \geq 0$.

The (extended) δ -folio of a graph *G* with respect to a set $Z \subseteq V(G)$ is the (extended) δ -folio of the graph *G'*, where *G'* has the same set of vertices and edges as *G*, but R(G') = Z. We will use this notion to avoid defining new graphs that differ only in the set of roots. Some straightforward observations:

PROPOSITION 2.3. Let G be a rooted graph and let $\delta \ge 0$ be an integer.

- (1) The extended 0-folio of G contains only the empty graph.
- (2) Let $R \subseteq Q \subseteq V(G)$ be two sets of vertices. The δ -folio of G with respect to R can be computed from the δ -folio of G with respect to Q.
- (3) Let $R_1, ..., R_t$ be subsets of V(G) such that for every subset $Q \subseteq R(G)$ of size at most 2δ there is a $1 \le i \le t$ such that $Q \subseteq R_i$. The δ -folio of G can be computed from the δ -folios of G with respect to $R_1, ..., R_t$.
- (4) The extended δ -folio of G can be computed from the $(\delta + |R(G)|)$ -folio of G.

2.1 Separations and replacements

A separation of a graph G is a pair (A, B) of subgraphs such that $V(G) = V(A) \cup V(B)$, $E(G) = E(A) \cup E(B)$, and $E(A) \cap E(B) = \emptyset$. The order of the separation (A, B) is $|V(A) \cap V(B)|$.

Let (A, B) be a separation of rooted graph *G* such that $V(A) \cap V(B) \subseteq R(G)$. Let *A'* be a rooted graph compatible with *A*. *Replacing A* with *A'* in the separation (A, B) gives the graph *G'* defined as follows. We have $V(G') = V(A') \cup (V(B) \setminus V(A))$, *G'* has every edge of *A'* and $B \setminus V(A)$, and *G'* has the following additional edges: if $u \in V(A) \cap V(B)$ and $v \in V(B) \setminus V(A)$ are adjacent in *G*, and $u' \in V(A')$ is a vertex with $\rho_A(u) = \rho_{A'}(u')$, then u' and v are adjacent in *G'*. Intuitively, we remove *A* from *G*, and replace it by *A'* such that the role of $V(A) \cap V(B)$ is taken by the matching root vertices of *A'*. The following lemmas show how the folio changes after replacement:

LEMMA 2.4. Let (G_1, G_2) be a separation of a rooted graph G, let $S = V(G_1) \cap V(G_2)$, and suppose that $S \subseteq R(G)$. Let G'_1 be a rooted graph compatible with G_1 such that G_1 and G'_1 have the same extended δ -folio. Let G' be the graph obtained by replacing G_1 with G'_1 in the separation (G_1, G_2) . Then G and G' have the same extended δ -folio.

PROOF. Without loss of generality, we can assume that $R(G) \cap V(G_1) = S$: extending G_2 such that $V(G_2)$ fully contains R(G) does not change the statement of the theorem. Under this assumption, it is sufficient to prove the weaker statement that G and G' have the same (not extended) δ -folio (but the condition that G_1 and G'_1 have the same *extended* δ -folio is not changed). To see this, consider an arbitrary graph X on R(G). Let X_1 be the subgraph of X induced by $R(G) \cap V(G_1) = S$ and let $X_2 = X \setminus E(X_1)$. Now G + X has a separation $(G_1 + X_1, G_2 + X_2)$ and G' + X has a separation $(G'_1 + X_1, G'_2 + X_2)$. As G_1 and G'_1 have the same extended δ -folio, graphs $G_1 + X_1$ and $G'_1 + X_1$ have the same extended δ -folio as well. Therefore, the weaker statement shows that G + X and G' + X have the same δ -folio. As this is true for every X on R(G), it follows that G and G' have the same extended δ -folio.

Let *H* be a rooted graph with $|E(H)| + is(H) \le \delta$ and let ϕ be a model of *H* in *G*. We need to show that *H* has a model ϕ' in *G'*.

We define the graph X^* on $S = R(G) \cap V(G_1)$ such that $uv \in X^*$ for some $u, v \in S$ if there is an edge $e \in E(H)$ such that $\phi(e)$ has a subpath with endpoints u and v and every internal vertex in $V(G_2) \setminus V(G_1)$. For every $uv \in E(X^*)$, let P_{uv} be this subpath. Given a path P in G with endpoints in $V(G_1)$, we denote by $[P]_{G_1}$ the path obtained by replacing subpaths of P that leave $V(G_1)$ by appropriate edges of X^* . Similarly, if Q is a path in $G_1 + X^*$, then we denote by $[Q]^G$ the path of G obtained by replacing each edge uv of X^* by the corresponding path P_{uv} .

We define a graph H^* and a model ψ of H^* in $G_1 + X^*$ as follows. First, graph H^* contains every vertex $v \in V(H)$ with $\phi(v) \in V(G_1)$; if $v \in R(H)$, then v is in $R(H^*)$ and has the same root number in H and H^* . For such vertices, we set $\psi(v) = \phi(v)$. We introduce additional vertices and edges to H^* as follows. We classify each edge $e = uv \in V(H)$ into one of 6 types, and modify H^* accordingly.

- (1) $\phi(u), \phi(v) \in V(G_1)$. For each such edge, there is a corresponding edge $e^* = uv$ in H^* . We define $\psi(e^*) = [\phi(e)]_{G_1}$.
- (2) $\phi(u) \in V(G_1), \phi(v) \notin V(G_1)$, and $\phi(e)$ has an internal vertex in $V(G_1)$. For each such edge, let us introduce a new vertex v_e^* that has the same root number as the last vertex *w* of $\phi(e)$ (going from *u* to *v*) that is in $V(G_1)$. Note that this last vertex has to be in $S \subseteq R(G)$, hence it is a root vertex. Let $\psi(v_e^*) =$ *w*. We introduce an edge $e^* = uv_e^*$ in H^* and set $\psi(e^*) =$ $[P]_{G_1}$, where *P* is the subpath of $\phi(e)$ from *u* to *w*.

- (3) φ(u) ∈ V(G₁), φ(v) ∉ V(G₁), and φ(e) has no internal vertex in V(G₁). This is only possible if u ∈ V(G₁) ∩ V(G₂), hence u is a root. We modify H* by making u a root (if it is not already a root), having the same root number as φ(u).
- (4) φ(u), φ(v) ∉ V(G₁), and φ(e) has no internal vertex in V(G₁). No change is done to H*.
- (5) $\phi(u), \phi(v) \notin V(G_1)$, and $\phi(e)$ has a single internal vertex w in $V(G_1)$. This is only possible if $w \in V(G_1) \cap V(G_2)$, and hence w is a root. An isolated root vertex i_e^* is introduced to H^* , with the same root number as w. Let $\psi(i_e^*) = w$.
- (6) φ(u), φ(v) ∉ V(G₁), and φ(e) has more than one internal vertex in V(G₁). Let u_e ≠ v_e be the first and last vertices, respectively, on φ(e) (going from u to v) that are in V(G₁). Note that u_e and v_e are in V(G₁) ∩ V(G₂), hence they are root vertices. Let us introduce root vertices v_e^{*} and u_e^{*} in H^{*} that have the same root numbers as u_e and v_e, respectively; let ψ(u_e^{*}) = u_e and ψ(v_e^{*}) = v_e. Let us also introduce an edge e^{*} connecting v_e^{*} and u_e^{*}, and let ψ(e^{*}) = [P]_{G₁}, where P is the subpath of φ(e) from u_e to v_e.

This completes the description of H^* . It should be clear that ψ is a model of H^* in $G_1 + X^*$. Furthermore, we claim that $|E(H^*)| + is(H^*) \le |E(H)| + is(H) \le \delta$. First, for each edge of H, we introduce at most one edge in H^* (for type 3–5 edges, we introduce no new edge in H^*). Moreover, a vertex of H^* can be isolated only if it was isolated in H, or only type 3 edges were adjacent to it, or it was introduced introduced as a vertex i_e^* corresponding to a type 5 edge e. This means that the number of isolated vertices in H^* is at most is(H) plus the number of type 3–5 edges in H.

As H^* is a topological minor of $G_1 + X^*$, it is a topological minor of $G'_1 + X^*$ as well; let ψ' be a model of H^* in $G'_1 + X^*$. We show that ψ' can be used to define a model ϕ' of H in G', what we need to show. For every $v \in V(H)$ with $\phi(v) \in V(G_1)$, let $\phi'(v) = \psi'(v)$ (as $v \in V(H^*)$ in this case) and for every $v \in V(H)$ with $\phi(v) \in$ $V(G_2) \setminus V(G_1)$, let $\phi'(v) = \phi(v)$. The images of the 6 different type of edges in H are defined as follows.

- (1) Let $\phi'(e) := [\psi'(e)]^{G'}$.
- (2) Let w ∈ S be the last vertex on φ(e) from u to v. We obtain φ'(e) by concatenating [ψ'(uv^{*}_e)]^{G'} (which goes from ψ'(u) to w) and the subpath of φ(e) from w to v.
- (3) $\phi'(e) := \phi(e)$.
- (4) $\phi'(e) := \phi(e)$.
- (5) $\phi'(e) := \phi(e)$.
- (6) The path φ'(e) is obtained by concatenating the subpath of φ(e) from u to u_v, the path [ψ'(u_e^{*}v_e^{*})]^{G'}, and the subpath of φ(e) from u_v to u.

It is not difficult to verify that the paths $\phi'(e)$ defined above are internally disjoint. What is important to observe is that if a subpath of $\phi(e)$ is used in the definition above, then every vertex of this subpath in $V(G_1) \cap V(G_2)$ corresponds to a root of H^* , hence it cannot conflict with that paths $\psi'(e)$. Thus ϕ' is a model of H in G', what we had to show. \Box

Lemma 2.4 implies that a separation allows us to determine the folio from the folios of two smaller graphs.

PROPOSITION 2.5. Let (G_1, G_2) be a separation of a rooted graph G, let $S = V(G_1) \cap V(G_2)$, and suppose that $S \subseteq R(G)$. The extended δ -folio of G can be computed from the extended δ -folios of G_1 and G_2 . Given a rooted graph *G*, let *w* be a weight function that assigns a positive integer to each vertex of V(G). The *w*-bounded δ -folio of *G* contains those members *H* of the δ -folio of *G* that have a model ϕ satisfying the additional requirement that for every $v \in R(H)$, the degree of v in *H* is at most $w(\phi(v))$. Note that we do not make any restriction on the degree of a non-root vertex *u* of *H*, even if $\phi(u)$ happens to be a root vertex of *G*. The term *unbounded* δ -folio is used when we want to emphasize that we are referring to the original definition of δ -folio. The *w*-bounded extended δ -folio is defined analogously. Given a weight function *w* on the vertices of *G*, we define $w(S) = \sum_{v \in S} w(v)$ for every $S \subseteq V(G)$.

Lemma 2.4 does not remain true for *w*-bounded folios: it is not true that *G* and *G'* have the same *w*-bounded extended δ -folio if *G*₁ and *G'*₁ have the same *w*-bounded extended δ -folio. The particular point where the proof would fail is that a type 3 edge can make a vertex of *H* a root which was not a root in *H*, and therefore it is not true that the model ψ is *w*-bounded. However, the proof can be fixed if we impose the additional assumption that *G*₁ and *G'*₁ have the same unbounded extended (δ – 1)-folio. This statement will be used in Section 4 in a situation where the *w*-bounded δ -folio of *G*₁ is easy to determine and we can use recursion to compute the unbounded (δ – 1)-folio.

LEMMA 2.6. Let (G_1, G_2) be a separation of a rooted graph G, let $S = V(G_1) \cap V(G_2)$, and suppose that $S \subseteq R(G)$. Let w be a weight function that assigns a positive integer to each vertex of V(G). Let G'_1 be a rooted graph compatible with G_1 such that G_1 and G'_1 have the same w-bounded extended δ -folio and the same unbounded extended $(\delta - 1)$ -folio. Let G' be the graph obtained by replacing G_1 with G'_1 in the separation (G_1, G_2) . Then G and G' have the same w-bounded extended δ -folio.

PROOF. The proof is the same as the proof Lemma 2.4 with one additional argument. Suppose first that $|E(H^*)| + is(H^*) \le \delta - 1$. In this case, we know that H^* is in the $(\delta - 1)$ -folio of $G'_1 + X^*$ as well, thus the model ψ' exists and the model ϕ' can be constructed. Note that $R(G) = R(G_2)$, which means that $\phi'(v) = \phi(v)$ for every root vertex of H and therefore ϕ' is w-bounded if ϕ is w-bounded.

Suppose now that $|E(H^*)| + is(H^*) = \delta$. We claim that in this case ψ is w-bounded and hence H^* is in the w-bounded δ -folio of $G_1 + X^*$ (not only in the unbounded δ -folio). The vertices in $V(H^*) \setminus V(H)$ have degree at most 1, thus the degree bound holds for such vertices (recall that $w(\psi(v))$ is strictly positive). If a vertex $v \in R(H^*) \cap V(H)$ is in R(H), then $\psi(v) = \phi(v)$ and hence the degree condition holds. Thus we have potential problems only with vertices in $(R(H^*) \cap V(H)) \setminus R(H)$, i.e., vertices that were already present as non-root vertices in H, but became roots in H^* . The only way such a vertex u could have become a root is if u was incident to a type 3 edge uv. If u is isolated in H^* , then the degree bound immediately holds. If u is not isolated, then the type 3 edge uvdoes not create any edge or any new isolated vertex in H^* , thus there is at least one edge of H that does not contribute towards $|E(H^*)| + is(H^*)$, contradicting $|E(H^*)| + is(H^*) = \delta$. Thus no such vertex u is possible, and it follows that ψ is w-bounded. As G_1 and G'_1 have the same w-bounded extended δ -folio, the model ψ' exists, and the rest of the proof is the same as before. \Box

PROPOSITION 2.7. Let (G_1, G_2) be a separation of a rooted graph G, let $S = V(G_1) \cap V(G_2)$, and suppose that $S \subseteq R(G)$. Let w be a weight function that assigns a positive integer to each vertex of R(G). The w-bounded extended δ -folio of G can be computed from the w-bounded extended δ -folio of G_1 , the unbounded extended $(\delta - 1)$ -folio of G_1 , and the unbounded extended δ -folio of G_2 .

3. Algorithmic framework

The main result of the paper is an algorithm FINDFOLIO that determines the extended δ -folio of the given graph.

FINDFOLIOInput:Rooted graph G, integer δ .Output:The extended δ -folio of G.

THEOREM 3.1. There is an algorithm satisfying the specification of FINDFOLIO that runs in $f_1(\delta, |R(G)|) \cdot |V(G)|^3$ steps, for some computable function f_1 .

For technical reasons, we prove Theorem 3.1 in the following form:

LEMMA 3.2. There is an algorithm satisfying the specification of FINDFOLIO on instances with $|R(G)| \le 16\delta^2$ that runs in $f'_1(\delta) \cdot |V(G)|^3$ steps, for some computable function f'_1 .

It is clear that Lemma 3.2 implies Theorem 3.1: by increasing δ to, say, |R(G)|, the algorithm of Lemma 3.2 can be used even if |R(G)| is arbitrary.

First we design three auxiliary algorithms that either return the extended δ -folio, or some information that is helps our progress: an irrelevant vertex, a clique minor, or an appropriate separation. We say that a set *X* of vertices is *irrelevant* to the (extended) δ -folio of *G*, if rooted graphs *G* and $G \setminus X$ have the same (extended) δ -folio. We say that a vertex *v* is irrelevant if the set {*v*} is irrelevant. Note that even if every vertex of a set *X* is irrelevant, the set *X* need not be irrelevant.

FINDIRRELEVANTOR SEPARATION Input: Rooted graph G, integer δ , integer L. Output: - The extended δ -folio of G, or - a vertex $v \in V(G)$ irrelevant to the extended δ -folio of G, or - a separation (G_1, G_2) of G with $|V(G_1)|, |V(G_2)| \ge L$ and having order at most $4\delta^2$.

We say that B_1, \ldots, B_k are the *branch sets* of a K_k -minor, if they are pairwise disjoint, induce connected subgraphs, and for every $1 \le i < j \le k$, there is an edge with one endpoint in B_i and one endpoint in B_j .

FINDIRRELEVANTORCLIQUE

```
Input: Rooted graph G, integer \delta, integer k.

Output: – The \delta-folio of G, or

– a vertex v \in V(G) irrelevant to the \delta-folio of G,

or

– the branch sets B_1, \ldots, B_k of a K_k-minor in G.
```

FINDIRRELEVANTORCLIQUEX

Input: Rooted graph G, integer δ , integer k. Output: – The *extended* δ -folio of G, or – a vertex $v \in V(G)$ irrelevant to the *extended* δ -

folio of *G*, or – the branch sets B_1, \ldots, B_k of a K_k -minor in *G*.

THEOREM 3.3. For some computable function f_2 , there is an algorithm satisfying the specification of FINDIRRELEVANTORCLIQUE that runs in $f_2(\delta, |R(G)|, k) \cdot |V(G)|$ steps.

Theorem 3.3 is proved in the full version of the paper. It is easy to show that an algorithm for FINDIRRELEVANTORCLIQUE can be used to obtain an algorithm for FINDIRRELEVANTORCLIQUEX:

Algorithm 1 FINDFOLIO

```
1: Let L := 4\delta^2 + 1.
```

- 2: Let $X := \emptyset \{ X \text{ is irrelevant to the extended } \delta \text{-folio of } G \}$
- 3: Let $Ret = FINDIRRELEVANTORSEPARATION(G \setminus X, \delta, L)$.
- 4: if *Ret* is the extended δ -folio \mathcal{F} of $G \setminus X$ then
- 5: return \mathcal{F}
- 6: if Ret is an irrelevant vertex v then
- 7: Let $X := X \cup \{v\}$
- 8: **goto** 3

9: if *Ret* is a separation (G_1, G_2) of $G \setminus X$ then

10: $S := V(G_1) \cap V(G_2)$

- 11: $G'_1 := \operatorname{AddRoot}(G_1, S)$
- 12: $\mathcal{F} = \text{FINDFOLIO}(G'_1, \delta)$
- 13: **if** there is a representative G_1'' of \mathcal{F} with at most *L* vertices **then**

```
14: G'' := (G''_1, G_2)
```

```
15: G''' := \operatorname{RemoveRoot}(G'', S \setminus R(G))
```

```
16: return FINDFOLIO(G''', \delta)
```

17: else

- 18: Let L := L + 1
- 19: goto 3

9. goto 3

COROLLARY 3.4. For some computable function f'_2 , there is an algorithm satisfying the specification of FINDIRRELEVANTOR-CLIQUEX that runs in $f'_2(\delta, |R(G)|, k) \cdot |V(G)|$ steps.

Section 4 presents an algorithm for FINDIRRELEVANTORSEP-ARATION:

THEOREM 3.5. For some computable function f_3 , there is an algorithm satisfying the specification of FINDIRRELEVANTORSEP-ARATION that runs in $f_3(\delta, |R(G)|, L) \cdot |V(G)|^2$ steps.

We prove Theorem 3.5 and Lemma 3.2 by simultaneous induction. In the rest of this section, we prove Lemma 3.2 for some δ , assuming that Theorem 3.5 is true for this δ ; while in Section 4, we prove Theorem 3.5 for some δ , assuming that Lemma 3.2 is true for $\delta - 1$. It is clear that these two proofs together prove Theorem 3.5 and Lemma 3.2 for every $\delta \ge 0$.

PROOF (OF LEMMA 3.2). Let $L^* = \max\{L_{\delta,12\delta^2}, 16\delta^2\}$. This constant will be required only for the analysis of the algorithm and it does not appear explicitly in the description of the algorithm. Algorithm 1 shows the algorithm in pseudocode. The functions AddRoot(*G*,*S*) and RemoveRoot(*G*,*S*) return a rooted graph where *S* is added to/removed from the set of roots, respectively.

Let $L := 4\delta^2 + 1$. We will increase *L* during the algorithm, but (as we shall see) $L \le L^*$ will always hold. Initially we set $X := \emptyset$; it will always hold that the set of vertices *X* is irrelevant to the extended δ -folio of *G*.

Let us run algorithm FINDIRRELEVANTORSEPARATION of Theorem 3.5 with $G \setminus X$, δ , and L. If the output is the extended δ folio of $G \setminus X$, then we are done. If the output is a vertex v irrelevant to the extended δ -folio of $G \setminus X$, then let $X := X \cup \{v\}$ and call FINDIRRELEVANTORSEPARATION again. It is clear that the new X is irrelevant to the extended δ -folio of G. Suppose that (after returning some number of irrelevant vertices) FINDIRRELE-VANTORSEPARATION returns a separation (G_1, G_2) of $G \setminus X$ with $|V(G_1)|, |V(G_2)| \ge L$ and having order at most $4\delta^2$. Note that $L > 4\delta^2$, and hence $|V(G_1) \setminus V(G_2)|, |V(G_2) \setminus V(G_1)| > 0$.

Let G', G'_1 , G'_2 be the same as $G \setminus X$, G_1 , and G_2 , respectively, with the difference that every vertex of $S = V(G_1) \cap V(G_2)$ is a root (in addition to the original roots). Without loss of generality, we can assume that $|R(G_1)| \leq |R(G_2)|$ and hence $|R(G'_1)| \leq |R(G_2)|$

 $|R(G)|/2 + |S| \le 12\delta^2$. Let us call FINDFOLIO recursively to find the extended δ -folio of G'_1 and then let us try to construct by brute force a representative G''_1 of this folio having at most L vertices. If we do not find such a representative, then we increase L by one, and go back to calling FINDIRRELEVANTORSEPARATION (note that this is possible only if $L < L_{\delta,12\delta^2} \le L^*$, thus we never increase L above L^*). Otherwise, we replace G'_1 with G''_1 in the separation (G'_1, G'_2) ; let G'' be the new graph. By Lemma 2.4, G' and G'' have the same extended δ -folio. Let G''' be the graph obtained from G''by making those vertices of S non-roots that are non-roots in G (i.e., |R(G''')| = |R(G)|). It is clear that the extended δ -folio of $G \setminus X$ and G''' are the same. Thus we can finish the algorithm by recursively calling FINDFOLIO on G''' (note that $|R(G''')| \le 16\delta^2$).

It is obvious from the description that the answer returned by the algorithm is correct. Note that $|V(G'_1)|, |V(G'')| < |V(G)|$, thus this recursive procedure always terminates.

We need to show that the number of steps can be bounded by $g(\delta) \cdot |V(G)|^3$ for some function g. The running time required for instances with at most $L^* + 1$ vertices can be bounded by a constant depending only on δ . We show that there is a function g' such that the running time can be bounded by $g'(\delta)(|V(G) - L^* - 1)|V(G)|^2$ for instances with $|V(G)| > L^* + 1$. We prove by induction on |V(G)| that this holds if $g'(\delta)$ is sufficiently large.

Let us bound first the number of steps without the calls to FIND-IRRELEVANTORSEPARATION and the recursive calls to FINDFO-LIO. Let *x* be the number of times FINDIRRELEVANTORSEP-ARATION returned an irrelevant vertex. Then FINDIRRELEVAN-TORSEPARATION was called at most $x + L^*$ times (each call either returned an irrelevant vertex or increased *L*, but $L \le L^*$ always hold). Therefore, each line is executed at most $x + L^*$ times. Each step can be done in linear time in the size of the graph, thus we can bound the running time by $c_1 \cdot (x+1)|V(G)|^2$ for some constant c_1 depending on δ . By Theorem 3.5, each call to FINDIRREL-EVANTORSEPARATION can be bounded by $f_3(\delta, 16\delta^2, L)|V(G)|^2$ steps and the maximum possible value of *L* is a function of δ , thus the total time required for these calls can be bounded by $c_2 \cdot (x + 1)|V(G)|^2$ for some constant c_2 depending only on δ .

Finally, let us bound the running time of the recursive calls to FINDFOLIO. If $|V(G'_1)| \le L^* + 1$ or $|V(G''')| \le L^* + 1$, then the number of steps of these calls can be bounded by a constant depending only on δ . Let us assume that $|V(G'_1)|, |V(G''')| > L^* + 1$. As we noted earlier, $|V(G'_1)|, |V(G''')| < |V(G)|$, thus the induction hypothesis can be used to bound the running time of these calls. Therefore, the total running time can be bounded as follows:

$$\begin{split} (c_1+c_2)(x+1)|V(G)|^2 + g'(\delta)(|V(G'_1)| - L^* - 1)|V(G'_1)|^2 \\ + g'(\delta)(|V(G''')| - L^* - 1)|V(G''')|^2 \\ \leq g'(\delta)\left((x+1) + |V(G'_1)| - L^* - 1 + |V(G''')| - L^* - 1\right)|V(G)|^2 \\ \leq g'(\delta)\left((x+1) + |V(G'_1)| - L^* - 1 + |V(G'_2) \setminus V(G'_1)| - 1\right)|V(G)|^2 \\ \leq g'(\delta)(|V(G)| - L^* - 1)|V(G)|^2. \end{split}$$

In the first inequality, we assume that $g'(\delta) \ge c_1 + c_2$. The second inequality follows from $|V(G'')| = |V(G''_1) \cup V(G'_2)|$ and $|V(G''_1)| \le L \le L^*$. The last inequality follows from $|X| + |V(G'_1) \cup V(G'_2)| = |V(G)|$. \Box

4. Using a large clique minor

In this section, we prove Theorem 3.5 for some δ , assuming that Lemma 3.2 holds for $\delta - 1$. We use the following lemma due to Robertson and Seymour ((5.4) of [11]):

LEMMA 4.1. Let G be a graph and $Z \subseteq V(G)$. Let $k \ge (3/2) \cdot |Z|$, and let $B_1, \ldots, B_k \subseteq V(G)$ be the branch sets of a K_k -minor of G. Suppose that there is no separation (G_1, G_2) of G of order < |Z| with $Z \subseteq V(G_1)$ and $B_b \cap V(G_1) = \emptyset$ for some $b \in [k]$. Then for every partition (Z_1, \ldots, Z_n) of Z into nonempty subsets there are pairwise disjoint connected subgraphs $T_1, \ldots, T_n \subseteq G$ such that $V(T_i) \cap Z = Z_i$ for all $i \in [n]$.

We say that the δ -folio of a graph is *generic* if it is as large as possible: it contains every rooted graph *H* with $|E(H)| + is(H) \le \delta$ and $\rho_H(R(H)) \subseteq \rho_G(R(G))$. We say that the δ -folio of a graph is rooted-generic if it contains every such graph H with the additional condition that every vertex of H is rooted (thus generic implies rooted-generic, but not necessarily the other way). The notions of generic and rooted-generic are defined analogously for w-bounded folios: in this case we require that every graph that can possibly be present in the w-bounded folio is actually present. That is, we require only those graphs H to be in the folio that satisfy the additional condition that for every $v \in R(H)$ and $u \in R(G)$ having the same root numbers, we have $d_H(v) \le w(u)$. We say that the extended (w-bounded) δ -folio is (w-bounded) generic, if this is true for every choice of the set X. Note that if G has a generic δ -folio, then G + X has generic δ -folio for any graph X on R(G): adding edges can only add more graphs to the folio. Thus the extended δ -folio of G is generic if and only if the δ -folio is generic. We can use Lemma 4.1 to obtain sufficient conditions for generic folios:

LEMMA 4.2. Let G be a rooted graph. Let w be a positive integer weight function on V(G). Let $k \ge (3/2) \cdot w(R(G))$, and let $B_1, \ldots, B_k \subseteq V(G)$ be the branch sets of a K_k -minor of G. Suppose that there is no separation (G_1, G_2) of G with $w(V(G_1) \cap V(G_2)) < w(R(G))$, $R(G) \subseteq V(G_1)$, and $B_i \cap V(G_1) = \emptyset$ for some $i \in [k]$.

- (1) The w-bounded δ -folio of G is rooted-generic.
- (2) If there are at least 2δ vertices v in R(G) with $w(v) \ge 2\delta$, then the w-bounded δ -folio of G is generic.

PROOF. We need to show that every possible candidate *H* is in the *w*-bounded δ -folio of *G*. Suppose therefore that *H* is a rooted graph with $|E(H)| + is(H) \le \delta$, R(H) = V(H), and $\rho_H(R(H)) \subseteq \rho_G(R(G))$. For every $u \in V(H)$, let $\phi(u)$ be the vertex of *G* with the same root number as *u* and assume that $d_H(u) \le w(\phi(u))$ for every $u \in V(H)$. We need to show that *H* is a topological minor of *G*, i.e., ϕ can be extended to a model of *H* in *G*.

For every $v \in V(G)$, let us define $w'(v) = d_H(u)$ if $v = \phi(u)$ for some $u \in V(H)$, and let w'(v) = w(v) if there is no such u. Clearly, $w'(v) \le w(v)$ for every $v \in V(G)$: the degree condition holds for every $v \in R(H) = V(H)$ in ϕ . Let G' be the graph obtained from G by extending each vertex $z \in R(G)$ into a clique K_z of size w'(z), i.e., we introduce w'(z) - 1 new vertices that are adjacent to each other, to vertex z, and to every neighbor of z. The clique K_z contains z and these w'(z) - 1 new vertices. Let $Z := \bigcup_{z \in R(G)} K_z$. Let us show first that the conditions of Lemma 4.1 hold for Z in G'. Suppose for contradiction that (G'_1, G'_2) is a separation of G' of order less than $|Z| = w'(R(G)) \leq w(\tilde{R}(G))$ with $Z \subseteq V(G'_1)$ and $B_b \subseteq V(G'_2) \setminus V(G'_1)$ for some $b \in [k]$. Let S' := $V(G'_1) \cap V(G'_2)$ be the separator. Without loss of generality, we may assume that for all $z \in R(G)$, either $K_z \cap S' = \emptyset$ or $K_z \subseteq S'$. Let $G_1 := G'_1 \setminus (Z \setminus R(G))$ and $G_2 := G'_2 \setminus (Z \setminus R(G))$. Then (G_1, G_2) is a separation of G; let $S = V(G_1) \cap V(G_2)$ be the separator. Now it is clear that $w(S) = |S'| < |Z| = w'(R(G)) \le w(R(G))$. However, we also have $R(G) \subseteq V(G_1)$ and $B_h \cap V(G_1) = \emptyset$, contradicting the assumption of the lemma being proved. Thus we can conclude that there is no such separation (G'_1, G'_2) , and the conditions of Lemma 4.1 hold for Z and G'.

Let us partition Z' in such a way that for every edge $uv \in E(H)$, there is a 2-element class of the partition consisting of a vertex in $K_{\phi(u)}$ and a vertex in $K_{\phi(v)}$. As $K_{\phi(u)}$ and $K_{\phi(v)}$ contain exactly $d_H(u)$ and $d_H(v)$ vertices, respectively, such a partition exists. Lemma 4.1 gives a set of pairwise disjoint subgraphs, one for each class of the partition. For every edge $uv \in E(H)$, let us denote by T_{uv} the connected subgraph corresponding to the class consisting of a vertex of $K_{\phi(u)}$ and a vertex of $K_{\phi(v)}$, and let us chose a path P'_{uv} in T_{uv} that goes from a vertex of $K_{\phi(u)}$ to a vertex of $K_{\phi(v)}$. It is clear that the collection \mathcal{P}' of |E(H)| paths obtained this way are pairwise disjoint in G'. Let us define P_{uv} such that whenever P'_{uv} contains a vertex of some K_z , then we replace it by z; let \mathcal{P} be the collection of these paths P_{uv} for every $uv \in E(H)$. Observe that the way G' was defined ensures that P_{uv} is a path in G. We claim that the paths in \mathcal{P} are pairwise internally disjoint in G. As the paths in \mathcal{P}' are pairwise disjoint, the only possible problem is that for some $w \in V(H)$, vertex $\phi(w)$ is an internal vertex of some path P_{uv} with $w \notin \{u, v\}$. However, there are $d_H(w) = |K_{\phi(w)}|$ paths in \mathcal{P} whose endpoint is $\phi(w)$ and hence the disjointness \mathcal{P}' ensure that there cannot be more than $d_H(w)$ paths using vertex $\phi(w)$. We finish the proof of the first statement by extending ϕ into a model of *H* by defining $\phi(uv)$ to be the path P_{uv} .

To prove the second statement, let *H* be a rooted graph with $|E(H)| + is(H) \le \delta$. Let us obtain *H'* by making every vertex of *H'* a root: if $v \in V(H)$ is not rooted, then let us assign to it a root number that appears on a vertex $v \in R(G)$ with $w(v) \ge \delta$ and is not already used by a vertex of *H*. As $|V(H)| \le 2\delta$, the conditions of the lemma show that we can assign root numbers this way. Since the *w*-bounded δ -folio of *G* is rooted-generic, *H'* is topological minor of *G*, which means that *H* is also a topological minor of *G*.

We prove Theorem 3.5, under the assumption that Theorem 3.1 is true for $\delta - 1$. Let us define the following constants:

$$h := 2\delta$$
$$s := 4\delta^2$$
$$k := \max\{L, 10\delta^2\} + |R(G)|$$

One possible correct output of FINDIRRELEVANTOR SEPARATION is a separation (G_1, G_2) of G with $|V(G_1)|, |V(G_2)| \ge L$ and $|V(G_1) \cap V(G_2)| \le s$. We refer to this as *finding a small separator*.

The algorithm for FINDIRRELEVANTORSEPARATION starts by calling FINDIRRELEVANTORCLIQUEX for G, δ , and k. If FIND-IRRELEVANTORCLIQUEX returns an irrelevant vertex or the extended δ -folio of G, then this is a valid output for FINDIRRELEVANTORSEPARATION as well. Suppose therefore that FINDIRRELEEVANTORCLIQUEX returns a k-clique minor with branch sets B_1 , ..., B_k . As at most |R(G)| of these sets intersect R(G), we can assume without loss of generality that B_1, \ldots, B_L are disjoint from R(G).

The rest of the section discusses two cases depending on the number of vertices with degree at least L in G'.

4.1 Case 1: Many high-degree vertices

Suppose that there are at least h vertices with degree at least L. Let U be a set of h such vertices.

Let us enumerate every nonempty subset of size at most 2δ of |R(G)|; let R_1, \ldots, R_t be these subsets. Let w_i be a weight assignment on V(G) such that $w(v) = \delta$ if $v \in R_i \cup U$ and w(v) = 1 otherwise. By Proposition 3, the folio of *G* can be obtained from the folios *G* with respect to R_1, \ldots, R_t . Furthermore, the w_i -bounded δ -folio of *G* with respect to R_i is obviously the same as the unbounded δ -folio with respect to R_i .

For every $1 \le i \le t$, we compute a separation (G_1^i, G_2^i) of G such that $R_i \cup U \subseteq V(G_1^i)$, there is a $1 \le b \le L$ with $B_b \subseteq V(G_2^i) \setminus V(G_1^i)$, and $w_i(V(G_1^i) \cap V(G_2^i))$ is as small as possible. Such a separation (G_1^i, G_2^i) can be done by running, for every $1 \le j \le L$, a weighted minimum vertex cutset algorithm to find a set of vertices that separates $R_i \cup U$ and B_j ; among these L separations, we define (G_1^i, G_2^i) to be the one that minimizes $w_i(V(G_1^i) \cap V(G_2^i))$. Let $S_i := V(G_1^i) \cap V(G_2^i)$.

Note that $(G[R_i \cup U], G \setminus E(G[R_i \cup U]))$ is always a separation that satisfies the requirements, thus we can assume that $w_i(S_i) \leq w(R_i \cup U) \delta(2\delta + h) = s$. As each of B_1, \ldots, B_L intersects $V(G_2^i)$, we have $|V(G_2^i)| \geq L$. This means that if $|V(G_1^i)| \geq L$ also holds, then separation (G_1^i, G_2^i) is a small separation that can be returned as a valid output of FINDIRRELEVANTORSEPARATION. Thus we can assume in the following that $|V(G_1^i)| < L$. This implies that $U \subseteq S_i$: if some $u \in U$ is not in S_i , then every neighbor of u is in $V(G_1^i)$, and $|V(G_1^i)| \geq L$ follows.

We use Lemma 4.2 to show that the w_i -bounded δ -folio of G_2^i is generic with respect to S_i . At most $|S_i| \le w_i(R_i \cup U) \le \delta(|R_i| + |U|) \le 4\delta^2$ of the sets B_1, \ldots, B_L intersect S_i , thus we can suppose without loss of generality that $B_1, \ldots, B_{6\delta^2}$ are disjoint from S_i . Suppose that G_2^i has a separation (F_1, F_2) contradicting the conditions of Lemma 4.2: $S_i \subseteq V(F_1), B_b \subseteq V(F_2) \setminus V(F_1)$ for some $1 \le b \le 6\delta^2$, and $w_i(V(F_1) \cap V(F_2)) < w_i(S_i)$. Such a separation can be extended to a separation (F_1', F_2') of G with $V(G_1^i) \subseteq V(F_1')$, $V(F_1') \cap V(F_2) = V(F_1) \cap V(F_2)$ and $B_b \subseteq V(F_2') \setminus V(F_1')$. However, such a separation would contradict the minimality of the choice of S_i . Thus the conditions of Lemma 4.2 hold, and the w_i -bounded δ -folio of G_2^i is generic with respect to S_i .

We use Proposition 2.7 to compute the w_i -bounded δ -folio of G with respect to $R_i \cup S_i$; by Proposition 2.3(2), this can be used to compute the w_i -bounded δ -folio of G with respect to R_i . As $|V(G_1^i)| < L$, the extended δ -folio of G_1^i with respect to $R_i \cup S_i$ can be determined by brute force in time depending only on L. We can determine the (unbounded) extended $(\delta - 1)$ -folio of G_2^i with respect to S_i by calling FINDFOLIO (recall that we assume in this section that Lemma 3.2 holds for $\delta - 1$ and $|S_i| \le 4\delta^2 \le 16(\delta - 1)^2$, satisfying the conditions of Lemma 3.2). We have shown above that the extended w_i -bounded δ -folio of G_2^i with respect to S_i is generic. Thus we have all the information required by Prop. 2.7 at our disposal to compute the w_i -bounded δ -folio of G with respect to $R_i \cup S_i$.

4.2 Case 2: Few high-degree vertices

Let *U* be the set of all vertices in *G'* with degree at least *L*; we suppose in this case that |U| < h. To determine the extended δ -folio of *G*, for every graph *X* on *R*(*G*), we need to determine the δ -folio of G + X. Fixing such an *X*, we set G' = G + X and proceed the following way.

We define a graph *F* on vertex set $V(G') \setminus U$, where two vertices are adjacent if their distance in $G' \setminus U$ is at most 2*L*. As the maximum degree of $G' \setminus U$ is at most L' = L + |R(G)|, the maximum degree of *F* is at most $(L')^{2L'+1}$. We say that a subset $C \subseteq V(G') \setminus U$ of vertices is a *cluster* if F[C] is connected. The maximum number of clusters of size at most *x* that contain a vertex $v \in V(G') \setminus U$ can be bounded by a function of the maximum degree of *F* and *x*. Therefore, assuming δ , |R(G)|, and *L* are fixed constants, the total number of clusters of size at most 2δ is linear in |V(G')|. Let C_1 , ..., C_t be an enumeration of the clusters of size at most 2δ .

For every $1 \le i \le t$, let w_i be a weight function on $V(G') \setminus U$ defined as $w_i(v) = \delta$ for $v \in C_i$ and $w_i(v) = 1$ otherwise. For ev-

ery $1 \leq i \leq t$, let us choose a separation (G_1^i, G_2^i) of $G' \setminus U$ such that $C_i \subseteq V(G_1^i)$, there is a branch set B_b with $B_b \subseteq V(G_2^i) \setminus V(G_1^i)$, and $w_i(V(G_1^i) \cap V(G_2^i))$ is minimum possible. It is easy to see that we can choose the separation such that every connected component of G_1^i contains a vertex of C_i . Let $D_i = V(G_1^i)$ and $S_i = V(G_1^i) \cap V(G_2^i)$. The separation $(G'[C_i], G' \setminus E(G'[C_i]))$ and the minimality of $w_i(S_i)$ shows that $w_i(S_i) \leq w_i(C_i) \leq 2\delta \cdot \delta$ and hence $|S_i| \leq w_i(S_i) \leq 2\delta^2$. Every branch set of the clique intersects $V(G_2^i)$, which means that $|V(G_2^i)| \geq L$. If $|V(G_1^i)| \geq L$ also holds, then G' has a small separation (G_1, G_2) with $V(G_1) = V(G_1^i) \cup u, V(G_2) = V(G_2^i) \cup U$, and $|V(G_1) \cap V(G_2)| = |V(G_1^i) \cap V(G_2^i)| + |U| \leq s$, which we can return. Thus in the following, we can assume that $|D_i| < L$.

We say that two clusters C_{i_1} and C_{i_2} are *independent* if there is no edge between C_{i_1} and C_{i_2} in *F*.

PROPOSITION 4.3. If clusters C_{i_1} and C_{i_2} are independent, then $D_{i_1} \cap D_{i_2} = \emptyset$.

PROOF. Let us choose a vertex $v \in D_{i_1} \cap D_{i_2}$. As $|D_{i_1}| < L$ and the component of $G_1^{i_1}$ containing v contains a vertex of C_{i_1} , vertex vis at distance at most L from some vertex of C_{i_1} in $G_1^{i_1}$, and therefore in $G' \setminus U$. Similarly, v is at distance at most L from some vertex of C_{i_2} in $G' \setminus U$. Thus there is an edge in F between a vertex of C_{i_1} and a vertex of C_{i_2} , a contradiction. \Box

DEFINITION 4.4. We say that clusters C_{i_1} and C_{i_2} are equivalent if there is a rooted isomorphism between the graphs $G[D_{i_1} \cup U]$ and $G[D_{i_2} \cup U]$ that is the identity on U, maps S_{i_1} to S_{i_2} , and maps C_{i_1} to C_{i_2} .

The following proposition is easy to prove:

PROPOSITION 4.5. The number of equivalence classes of the clusters can be bounded by a function of δ and L.

As we shall see, the topological minor is realized by a small number of clusters and paths connecting them. The following definition tries to capture which paths are inside a cluster and which paths are between clusters.

DEFINITION 4.6. Let *H* be a rooted graph. A scheme of *H* is a pair (H', H'_*) of rooted graphs, where

- (1) H' is a subdivision of H (the new vertices are not roots),
- (2) H'_* is a subgraph of H', and
- (3) every vertex of $V(H'_*) \setminus V(H)$ has degree at most 1 in H'_* .

For every *r*-tuple $C = (C_{i_1}, \ldots, C_{i_r})$ of clusters, we define $C^C = \bigcup_{i=1}^r C_{i_j}, D^C = \bigcup_{i=1}^r D_{i_j}$, and $S^C = \bigcup_{i=1}^r S_{i_j}$. We define two graphs: $G_1^C = G'[U \cup D^C]$ and $G_2^C = G' \setminus (D^C \setminus S^C)$. Note that (G_1^C, G_2^C) is a separation of *G*. We also define a weight function w^C on V(G)that is δ on every vertex of $U \cup C^C$ and 1 on every other vertex.

DEFINITION 4.7. Let *H* be a rooted graph and let (H', H'_*) be a scheme of *H*. Let $C = (C_{i_1}, \ldots, C_{i_r})$ be an *r*-tuple of clusters. We say that this tuple realizes the scheme (H', H'_*) if $H' \setminus E(H'_*)$ has a model ϕ in G_1^C such that

- (1) every vertex of V(H) is mapped to $U \cup C^{\mathcal{C}}$,
- (2) every vertex of $V(H'_*)$ is mapped to $U \cup S^{\mathcal{C}}$, and
- (3) for every $e \in E(H') \setminus E(H'_*)$, the internal vertices of $\phi(e)$ are not in $U \cup S^{\mathcal{C}}$.

Roughly speaking, what we want to show is that H is a topological minor of G if and only if there is a tuple of independent clusters that realizes a scheme of H (Lemmas 4.8 and 4.10). Therefore, deciding whether H is a topological minor essentially reduces to finding a tuple of independent clusters that realize a given scheme of H. As the clusters can be classified into a bounded number of equivalence classes, the main difficulty is to find independent clusters of given types, which can be solved using standard techniques.

We first prove that if a rooted graph H has a model in G', then H has a scheme that is realized by some tuple of clusters. We hope the proof sheds light on why schemes are defined this way.

LEMMA 4.8. Let H be a rooted graph in the δ -folio of G'. Then there is a scheme (H', H'_*) of H with $|V(H')| \leq 4\delta + 2\delta^2$ and a tuple $\mathcal{C} = (C_{i_1}, \ldots, C_{i_r})$ of pairwise independent clusters with $r \leq 2\delta$ that realizes (H', H'_*) .

PROOF. Let ϕ be a model of H in G'. Let $C = \{\phi(v) \mid v \in V(H)\} \setminus U$. Each connected component of F[C] is a cluster; let $C = (C_{i_1}, \ldots, C_{i_r})$ be these connected components. Clearly, these clusters are pairwise independent and $r \leq |V(H)| \leq 2\delta$. Due to a minor technical detail, we need to handle some vertices of $S^C \cup U$ in a special way. We define X to contain a vertex $v \in S^C \cup U$ if v is an internal vertex of $\phi(e)$ for some $e \in E(H)$ and both neighbors of v in $\phi(e)$ are in $V(G_2^C)$.

If for some $e \in V(H)$, the path $\phi(e)$ contains *m* internal vertices in $(S^{\mathcal{C}} \cup U) \setminus X$, then let us subdivide *e* with *m* new (nonroot) vertices; let *H'* be the rooted graph obtained this way. As $|S^{\mathcal{C}} \cup U| \leq 2\delta^2 + 2\delta$, we have $|V(H')| \leq 4\delta + 2\delta^2$. The model ϕ gives a model ϕ' of *H* in *G* the obvious way (every new vertex of the subdivision is mapped to a vertex in $(S^{\mathcal{C}} \cup U) \setminus X$). Let H'_* be the subgraph of *H'* that contains those vertices *v* for which $\phi'(v) \in (S^{\mathcal{C}} \cup U) \setminus X$ and those edges *e* for which $\phi'(e)$ is fully contained in $G_2^{\mathcal{C}}$.

We claim that (H', H'_*) is a scheme of H and C realizes this scheme. Conditions 1 and 2 of Definition 4.6 are easy to verify. To check condition 3, suppose that vertex $v \in V(H'_*) \setminus V(H)$ has degree more than 1. Since vertex v was obtained as the subdivision of an edge $e \in E(H)$, vertex v has degree exactly 2 in H'_* and $\phi'(v) \in (S^C \cup U) \setminus X$. Let e_1 and e_2 be the two edges incident to vin H'_* . By definition of $H'_*, \phi'(e_1)$ and $\phi'(e_2)$ are fully contained in G_2^C . Thus the two neighbors of $\phi(v)$ in $\phi(e)$ are both in $V(G_2^C)$, implying that $\phi(v) \in X$, a contradiction.

Finally, we show that ϕ' defines a model of $H' \setminus E(H'_*)$ in $G_1^{\mathcal{C}}$ satisfying the conditions of Definition 4.7. Let us verify that the images of the vertices and edges are indeed in $G_1^{\mathcal{C}}$. It is clear that $\phi'(v) \in V(G_1^{\mathcal{C}})$ for every $v \in V(H')$. Let us prove that $\phi'(e)$ is fully contained in $V(G_1^{\mathcal{C}})$ for every $e \in E(H') \setminus E(H'_*)$. In fact, we show that $\phi'(e)$ has no internal vertex in $V(G_2^{\mathcal{C}})$. Suppose that $\phi'(e)$ has an internal vertex $u_2 \in V(G_2^{\mathcal{C}})$. As $e \notin E(H'_*)$, path $\phi'(e)$ contains a vertex $u_1 \in V(G_1^{\mathcal{C}}) \setminus V(G_2^{\mathcal{C}})$ (u_1 can be an endpoint of $\phi'(e)$). Going from u_1 to u_2 on $\phi'(e)$, let u be the first vertex of $V(G_2^{\mathcal{C}})$; clearly, $u \in S \cup U$ and $u \neq u_1$. Now u is an internal vertex of $\phi'(e)$, and the vertex preceding u is not in $V(G_2^{\mathcal{C}})$. Thus $u \in (S^{\mathcal{C}} \cup U) \setminus X$, which means that u should be the image of a vertex of H' in ϕ' , a contradiction. Therefore, $\phi'(e)$ has no internal vertex in $V(G_2^{\mathcal{C}})$ and in particular $\phi'(e)$ is fully contained in $V(G_1^{\mathcal{C}})$ for every $e \in$ $E(H') \setminus E(H'_*)$. This means that ϕ' is indeed a model of $H' \setminus E(H'_*)$ in $G_1^{\mathcal{C}}$ and we also verified condition 3 of Definition 4.7. Conditions 1 and 2 are straightforward to check. \Box

We prove now the converse of Lemma 4.8. We show first that the w_i -bounded folio of G_2^C is rooted-generic (Lemma 4.9). Then

we use this fact to route the edges of H'_* when constructing a model of H' in G' (Lemma 4.10).

LEMMA 4.9. Let $C = (C_{i_1}, \ldots, C_{i_r})$ be a tuple of pairwise independent clusters. Either the w^C -bounded $w^C(S^C)$ -folio of G_2^C with respect to $U \cup S^C$ is rooted-generic (and we can find a model of every graph in the folio), or we can find a separation (G'_1, G'_2) of G' with $|V(G'_1)|, |V(G'_2)| \ge L$ and $|V(G'_1) \cap V(G'_2)| \le s$.

PROOF. If the conditions of Lemma 4.2 hold for $G_2^{\mathcal{C}}$, $w^{\mathcal{C}}$, and set of roots $U \cup S^{\mathcal{C}}$, then we are done. Suppose therefore that there is a separation (F_1, F_2) of $G_2^{\mathcal{C}}$ violating the conditions of Lemma 4.2. There is a corresponding separation (G_1', G_2') of G' with $V(F_1) \cap$ $V(F_2) = V(G_1') \cap V(G_2')$, $V(G_1') \subseteq V(F_1)$, and $V(G_2') = V(F_2)$. Let $S' = V(F_1) \cap V(F_2) = V(G_1') \cap V(G_2')$, it is clear that $|S'| \leq$ $w^{\mathcal{C}}(U \cup S^{\mathcal{C}}) \leq s$. As $B_b \subseteq V(G_2')$, we also have $|V(G_2')| \geq L$. If $|V(G_1')| \geq L$, then we can return the small separation (G_1', G_2') . Thus in the following, we can assume that $|V(G_1')| \leq L$. In particular, this means that $U \subseteq S'$: if $u \in V(G_1') \setminus V(G_2')$ for some $u \in U$, then every neighbor of u is in $V(G_1')$ and $|V(G_1')| \geq L$ follows.

Let S'_{i_j} be the set of those vertices of $S' \setminus U$ that can be reached from $S_{i_j} \subseteq V(G'_1) \setminus U$ by a path in $G'_1 \setminus U$. We claim that these sets are pairwise disjoint for j = 1, ..., r. Suppose without loss of generality that there is a vertex $v \in S'_{i_1} \cap S'_{i_2}$. This means that there is a vertex $v_1 \in S_{i_1}$ and a vertex $v_2 \in S_{i_2}$ that are in the same connected component K of $G'_1 \setminus U$ as v. Note that D_{i_1} and D_{i_2} are fully contained in $G'_1 \setminus U$, thus there is a vertex $c_1 \in C_{i_1}$ and a vertex $c_2 \in C_{i_2}$ in this connected component K. As clusters C_{i_1} and C_{i_2} are independent by assumption, the distance of c_1 and c_2 is at least 2Lin $G'_1 \setminus U$, which means that $|V(G'_1)| \ge 2L$, a contradiction.

As $U, S'_{i_1}, \ldots, S'_{i_r}$ are pairwise disjoint and $U \subseteq S$, the only way $w^{\mathcal{C}}(S') < w^{\mathcal{C}}(S)$ is possible if $w^{\mathcal{C}}(S'_{i_j}) < w^{\mathcal{C}}(S_{i_j})$ for some $1 \le j \le r$. However, in this case there is a separation $(G_1^{i_j}, G_2^{i_j})$ of $G' \setminus U$ with $V(G_1^{i_j}) \cap V(G_2^{i_j}) = S'_{i_j}, D_{i_j} \subseteq V(G_1^{i_j})$, and $B_b \subseteq V(G_2^{i_j}) \setminus V(G_1^{i_j})$ for some branch set B_b . This contradicts the minimality of the choice of S_{i_j} . \Box

LEMMA 4.10. Let *H* be a rooted graph and (H', H'_*) be a scheme of *H*. Let $C = (C_{i_1}, \ldots, C_{i_r})$ be an *r*-tuple of pairwise independent clusters that realizes (H', H'_*) . Then we can find either a model of *H* in *G'* or a separation (G'_1, G'_2) of *G'* with $|V(G'_1)|, |V(G'_2)| \ge L$ and $|V(G'_1) \cap V(G'_2)| \le s$.

PROOF. Let ϕ be a model of $H' \setminus E(H'_*)$ in $G_1^{\mathcal{C}}$, as in Definition 4.7. Since $G_1^{\mathcal{C}}$ is a subgraph of G', ϕ can be considered as a model of $H' \setminus E(H'_*)$ in G'. We try to extend ϕ to a model of H' in G' by assigning values to $\phi(e)$ for every $e \in E(H'_*)$. In order to do this, let us make every vertex of $U \cup S^{\mathcal{C}}$ a root $G_2^{\mathcal{C}}$, and let H_*'' be obtained from H_*' by making every vertex v a root with the same root number as $\psi(v)$. We try to find a $w^{\mathcal{C}}$ -bounded model ψ of H'_* in $G_2^{\mathcal{C}}$. Note that Definition 4.7 ensures that such a ψ respects the degree condition: for every $v \in V(H'_*) \cap V(H)$, we have $\psi(v) \in U \cup S^{\mathcal{C}}$ and hence $w^{\mathcal{C}}(\psi(v)) = \delta$, while the degree of every $v \in V(H'_*) \setminus V(H)$ is at most 1 in H'_* . We use Lemma 4.9 to find either a small separation (G'_1, G'_2) , or a model ψ of H''_* in $G_2^{\mathcal{C}}$ with $\psi(v) = \phi(v)$ for every $v \in V(\tilde{H})$. If Lemma 4.9 gives us a separation, then we are done. Otherwise, let us set $\phi(e) = \psi(e)$ for every $e \in E(H'_*)$. The paths $\phi(e)$ for $e \in E(H'_*)$ are pairwise internally disjoint: this follows from the fact that if $e \in E(H'_*)$, then the internal vertices of $\phi(e) = \psi(e)$ are in $V(G_2^{\mathcal{C}})$, while for every $e \in E(H') \setminus E(H'_*)$, the internal vertices of $\phi(e)$ are not in $V(G_2^{\mathcal{C}})$ (by Definition 4.7(3)). Thus ϕ is indeed a model of H'.

Having established the correspondence between topological minors and tuples of clusters realizing a scheme, we concentrate on finding such a tuple. We observe that only the equivalence types of the clusters matter:

PROPOSITION 4.11. Let *H* be a rooted graph and (H', H'_*) be a scheme of *H*. Let $(C_{i_1}, \ldots, C_{i_r})$ and $(C_{i'_1}, \ldots, C_{i'_r})$ be two *r*-tuple of clusters such that $(C_{i_1}, \ldots, C_{i_r})$ realizes (H', H'_*) and for every $1 \le j \le r$, clusters C_{i_j} and $C_{i'_j}$ are equivalent. Then $(C_{i'_1}, \ldots, C_{i'_r})$ also realizes (H', H'_*) .

The following lemma is standard: it shows that finding small fixed-size "colorful" independent sets in bounded-degree graphs can be done in linear time.

LEMMA 4.12. Let W be a graph with maximum degree d where the vertices are labeled with k different labels. We can find in time $f(d,k) \cdot (|V(W)| + |E(W)|)$ an independent set of size k where every vertex has a different label (or correctly state that there is no such set).

LEMMA 4.13. Given a scheme (H',H'_*) with $|V(H')| \le 4\delta + 2\delta^2$, in time $f(\delta,L)|V(G)|$ (for some function $f(\delta)$) we can find a tuple $C = (C_{i_1}, \ldots, C_{i_r})$ of clusters with $r \le 2\delta$ that realizes (H', H'_*) (if such a tuple exists).

PROOF. Let us enumerate all clusters and sort them into equivalence classes (where equivalence is understood according to Definition 4.4). Let t be the number of equivalence classes and let us assign an integer $\tau(C_i) \in [t]$ to each cluster C_i based on which class it belongs to. For every subset $T \subseteq [t]$ of size at most 2δ , we test whether there is a tuple $(C_{i_1}, \ldots, C_{i_{|T|}})$ of pairwise independent clusters with $\{\tau(C_{i_1}), \ldots, \tau(C_{i_{|T|}})\} = T$. In order to do this, we build a graph W_T by introducing a vertex with label $\tau(C_i)$ corresponding to every cluster C_i with $\tau(C_i) \in T$. Two vertices of W_T are adjacent if the corresponding clusters are *not* independent. We claim that the maximum degree of W_T can be bounded by a function of δ and L. To see this, recall that the maximum degree of $G \setminus U$ is at most L and that the maximum distance in $G \setminus U$ between two vertices of a cluster C_i is $O(\delta L)$ (as C_i induces a connected subgraph of F). Thus if C_i and C_i are not independent, then C_i is fully contained in the $O(\delta L)$ -neighborhood of every vertex of C_i ; the number of such sets can be bounded by a function of δ and L. This means that if we use Lemma 4.12 to find a colorful independent set in W_T , then the running time is linear in the number of clusters (for fixed δ and L). If Lemma 4.12 returns an independent set, then we test if the corresponding pairwise independent tuple $C = (C_{i_1}, \dots, C_{i_{|T|}})$ of clusters realizes (H',H'_*) (as the size of $G_1^{\mathcal{C}}$ is bounded by a function of δ and L, this can be done by brute force). If after trying every $T \subseteq [t]$ of size at most 2δ , no tuple realizing (H', H'_*) is found, then by Proposition 4.11 we know that there is no tuple realizing (H', H'_*) .

In Case 2 (|U| < h), our algorithm for FINDIRRELEVANTORSEP-ARATION determines the δ -folio of G' = G + X the following way. For every candidate H in the δ -folio, we enumerate every scheme (H', H'_*) of H with $|V(H)| \le 4\delta + 2\delta^2$ (the number of such schemes is clearly bounded by a function of δ). For each scheme, we use Lemma 4.13 to check if there is a tuple of clusters that realizes this scheme. If there is such a tuple, then by Lemma 4.10, we can obtain a model of H in G' or a small separation; if there is no such tuple, then the (contrapositive) of Lemma 4.8 shows that H' is not a topological minor of G'. It is easy to verify that for fixed δ and L, the running time is $O(|V(G)|^2)$.

5. Immersion

Let G, H be graphs. An *immersion* of H in G is a function α with domain $V(H) \cup E(H)$, such that:

- $\alpha(v) \in V(G)$ for all $v \in V(H)$, and $\alpha(u) \neq \alpha(v)$ for all distinct $u, v \in V(H)$,
- for each edge e of H, if e has distinct ends u, v then α(e) is a path of G with ends α(u), α(v), and
- for all distinct $e, f \in E(H), E(\alpha(e) \cap \alpha(f)) = \emptyset$.

In the definition of *strong immersion*, we impose on another condition, that

• for all $v \in V(H)$ and $e \in E(H)$, if *e* is not incident with *v* in *H* then $\alpha(v) \notin V(\alpha(e))$.

In this section, we show that our main theorem, Theorem 1.1 implies that both versions of the immersion containment problem are fixed-parameter tractable parameterized by the order of |E(H)|.

THEOREM 5.1. For every fixed graph H, there is a $O(|V(G)|^3)$ time algorithm that decides if H is an immersion in G.

PROOF. Let k = |E(H)| + |V(H)|. We construct a new graph G' from G by subdividing each edge and replacing each original vertex by k duplicates. Formally, for each $e \in E(G)$, there is a vertex e' in G'; for each vertex $v \in V(G)$, there are k vertices v_1, \ldots, v_k in G', and if $v \in V(G)$ is an endpoint of $e \in E(G)$, then vertex $e' \in V(G')$ is adjacent to v_1, \ldots, v_k in G'. Note that the degree of e' is 2k.

Let $\ell = 2k|V(H)| + 2$ and let us use the algorithm of Theorem 1.1 to find a K_{ℓ} topological minor in G'. We claim that if there is such a topological minor model $\phi : V(K_{\ell}) \to V(G')$, then *H* has an immersion in G. To see this, observe first that $\phi(v)$ is a vertex with degree at least $\ell - 1 > 2k$, thus $\phi(v) = u_i$ for some $u \in V(G)$; let us define $\alpha(v) = u$ in this case. It is clear that α maps at most k vertices of K_{ℓ} to the same vertex of G. As $\ell/k > |V(H)|$ holds, one can select vertices $x_1, \ldots, x_{|V(H)|}$ whose images in ϕ are all distinct. For any $1 \le i, j \le |V(H)|$, the path $\phi(x_i x_j)$ between $\phi(x_i)$ and $\phi(x_i)$ in G' gives a path $\alpha(x_i x_i)$ between $\alpha(x_i)$ and $\alpha(x_i)$ in a natural way. As the paths $\phi(x_i x_j)$ are pairwise internally vertex disjoint in G', the paths $\alpha(x_i x_j)$ are pairwise edge disjoint in G: a vertex $e' \in E(G')$ can be used by at most one of the paths $\phi(x_i x_j)$. Therefore, ϕ shows that $K_{|V(H)|}$ has an immersion in G, which immediately implies that H has an immersion in G. This means that we are done in the case when K_{ℓ} is a topological minor of G'.

Suppose now that K_{ℓ} is not a topological minor of G'. We modify G' to obtain a new graph G'' as follows. For every $v \in V(G)$, we introduce a new copy of K_{ℓ} and identify v_1 with a vertex of K_{ℓ} . Thus the number of vertices of G'' is $|V(G')| + |V(G)|(\ell-1)$. Similarly, we obtain H'' from H by introducing for each $u \in V(H)$ a new copy of K_{ℓ} and identifying u and a vertex of K_{ℓ} (so $|V(H'')| = \ell|V(H)|$).

We claim that H'' is a topological minor of G'' if and only if H has an immersion in G. For the if part, suppose that α is an immersion of H in G. In this case, it is easy to construct a model ϕ of H'' in G'': if $\alpha(u) = v$ for some $u \in V(H)$ and $v \in V(G)$, then we set $\phi(u) = v_1$, map the clique attached to v in H'' to the clique attached to v_1 , and transform each path $\alpha(u_1u_2)$ in G into a corresponding path $\phi(u_1u_2)$ in G''. We can ensure that the paths in ϕ are internally vertex disjoint: the paths in α are edge disjoint (so we can ensure that each vertex $e' \in V(G'')$ is used at most once) and the k vertices v_1, \ldots, v_k in G'' are sufficient to accommodate the at most |E(H)| paths going through v in α .

For the only if part, suppose that ϕ is a model of H'' in G''. Consider a vertex u of H'' that also appears in H (i.e., it is not a vertex introduced by a new clique). The degree of u in H'' is more than $\ell - 1$ (assuming that *H* has no isolated vertices) and *u* is part of an ℓ -clique in *H*". Thus $\phi(u)$ is a vertex of *G*" having degree more than $\ell - 1$ and part of a topological minor model of a ℓ -clique. We claim that $\phi(u) = v_1$ for some $v \in V(G)$. Every model of an ℓ clique is fully contained in a biconnected component of *G*". As *G*' has no ℓ -clique topological minor, such a biconnected component must be one of the K_ℓ -cliques created in the construction of *G*". Furthermore, the new vertices of such a clique have degree exactly $\ell - 1$, thus $\phi(u)$ can be only a vertex v_1 for some $v \in V(G)$. Thus ϕ restricted to *H* is a topological minor model of *H* that does not go inside the cliques, which means that it is a topological minor model of *H* in *G*'. Arguing as in the first part of the proof, it follows that *H* has an immersion in *G*.

Let us estimate the running time of the algorithm. First, we can assume that $|E(G)| \le c_H |V(G)|$ for some constant c_H depending only on H: by a classical result of Mader, if the average degree of G is sufficiently large, then G has a $K_{|V(H)|}$ topological minor, immediately implying that H has an immersion in G. Therefore, the number of vertices of G' is k|V(G)| + |E(G)| = O(|V(G)|) (for fixed H). The construction of G'' increases the number of vertices by a factor of ℓ , hence |V(G'')| = O(|V(G)|) also holds. Thus both invocations of Theorem 1.1 need $O(|V(G)|^3)$ time. \Box

A similar reduction works in the case of strong immersion:

THEOREM 5.2. For every fixed graph H, there is a $O(|V(G)|^3)$ time algorithm that decides if H is a strong immersion in G.

6. References

- S. Arnborg and A. Proskurowski. Linear time algorithms for NP-hard problems restricted to partial k-trees. *Discrete Applied Mathematics*, 23(1):11–24, 1989.
- [2] H. L. Bodlaender. A linear-time algorithm for finding tree-decompositions of small treewidth. SIAM J. Comput., 25(6):1305–1317, 1996.
- [3] R. G. Downey and M. R. Fellows. Fixed-parameter intractability. In Structure in Complexity Theory Conference, pages 36–49, 1992.
- [4] R. G. Downey and M. R. Fellows. *Parameterized Complexity*. Monographs in Computer Science. Springer, New York, 1999.
- [5] J. Flum and M. Grohe. Parameterized Complexity Theory. Springer, 2006.
- [6] S. Fortune, J. E. Hopcroft, and J. Wyllie. The directed subgraph homeomorphism problem. *Theor. Comput. Sci.*, 10:111–121, 1980.
- [7] M. R. Garey and D. S. Johnson. *Computers and Intractability*. W. H. Freeman and Co., San Francisco, Calif., 1979.
- [8] K. Kawarabayashi, Y. Kobayashi, and B. Reed. The disjoint paths problem in quaratic time. Submitted. Available at http://research.nii.ac.jp/~k_keniti/quaddp1.pdf.
- [9] K. Kawarabayashi and P. Wollan. A shorter proof of the graph minor algorithm: the unique linkage theorem. In STOC, pages 687–694, 2010. A full version vailable at http://research.nii.ac.jp/~k_keniti/uniquelink.pdf.
- [10] A. S. LaPaugh and R. L. Rivest. The subgraph homeomorphism problem. J. Comput. Syst. Sci., 20(2):133–149, 1980.
- [11] N. Robertson and P. D. Seymour. Graph minors. XIII. The disjoint paths problem. J. Combin. Theory Ser. B, 63(1):65–110, 1995.
- [12] N. Robertson and P. D. Seymour. Graph minors. XVI. Excluding a non-planar graph. J. Comb. Theory, Ser. B, 89(1):43–76, 2003.
- [13] N. Robertson and P. D. Seymour. Graph minors. XXI. Graphs with unique linkages. J. Comb. Theory, Ser. B, 99(3):583–616, 2009.
- [14] N. Robertson and P. D. Seymour. Graph minors XXIII. nash-williams' immersion conjecture. J. Comb. Theory, Ser. B, 100(2):181–205, 2010.
- [15] P. D. Seymour and R. Thomas. Graph searching and a min-max theorem for tree-width. J. Comb. Theory, Ser. B, 58(1):22–33, 1993.
- [16] J. Thatcher and J. Wright. Generalised finite automata theory with an application to a decision problem of second-order logic. *Mathematical Systems Theory*, 2:57–81, 1968.