

## Part II

# Declarative Programming with Constraints

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## 2 Declarative Programming with Constraints

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- Constraint Logic Programming (CLP)
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- Disjunctions in CLPFD
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## Block declarations

- A **block declaration** causes a goal to **suspend** when certain arguments are unbound
- Multiple block declarations mean disjunctive conditions
- Examples:

```
:- block p(-, ?, -, ?). suspends when 1st and 3rd arg is unbound.
```

```
:- block p(-, ?), p(?, -). suspends when 1st or 2nd arg is unbound.
```

- When blocking condition(s) hold no more, the call executes immediately.
- Example: safe append, with no infinite choice points:

```
:- block app(-, ?, -).
```

```
% app(L1, L2, L3): The concatenation of L1 and L2 is L3.
```

```
% Blocks if *both* L1 and L3 are unbound variables.
```

```
app([], L, L).
```

```
app([X|L1], L2, [X|L3]) :-      app(L1, L2, L3).
```

```
| ?- app(L1, L2, L3).            $\implies$    user:app(L1,L2,L3) ? ; no
```

```
| ?- app(L1, L2, L3), L3 = [1|_].
```

```
     $\implies$    L1 = [], L2 = [1|_A], L3 = [1|_A] ? ;
```

```
     $\implies$    L1 = [1|_A], L3 = [1|_B], user:app(_A,L2,_B) ? ; no
```

## Further coroutining predicates

- `freeze(X, Goal)`: `Goal` is true. Suspends `Goal` until `x` is instantiated.
- `dif(X, Y)`: `X` and `Y` are different. Suspends until this can be decided.
- `when(Condition, Goal)`: `Goal` is true. Suspends `Goal` until `Condition` is satisfied. Here `Condition` is a very simple Prolog goal:

```
Condition ::= nonvar(X) | ground(X) | ?=(X,Y) |
            Condition, Condition |
            Condition; Condition
```

- For example, `process/3` will execute only when `T` is ground and either `x` is not a variable, or the unifiability of `x` and `Y` can be decided:
 

```
| ?- when( (ground(T), (nonvar(X);?=(X,Y))),
           process(X,Y,T)).
```
- `frozen(X, Goals)`: `Goals` are the goals suspended because of variable `x`.
- `call_residue_vars(Goal, Vars)`: `Vars` is the list of variables because of which goals were suspended during the execution of `Goal`.

## The N-queens problem

- Place  $N$  queens on a  $N \times N$  chessboard so that no two queens attack each other
- The Prolog list  $[Q_1, \dots, Q_N]$  represents the placement: row  $i$  contains a queen in column  $Q_i$ .
- The “generate and test” approach for solving N-queens

```
:- use_module(library(between)).
```

```
:- use_module(library(lists),[select/3]).
```

```
queens_gt(N, Qs):-
```

```
    findall(I, between(1, N, I), L),      % L = [1,2,...N]
```

```
    permutation(L, Qs),
```

```
    safe(Qs). % Placement Qs has no queens attacking each other
```

```
% permutation(L, P): P is a permutation of L.
```

```
permutation([], P) :- !, P = [].
```

```
permutation(L0, [X|P]) :-
```

```
    select(X, L0, L1), % select the 1st elem of permutation
```

```
    permutation(L1, P). % permute the rest
```

## Safe placement of N-queens

- The code to check if a placement is safe

```

% safe(Qs): Placement Q is safe from queens attacking each other
safe([]).
safe([Q|Qs]):-
    no_attack(Qs, Q, 1), safe(Qs).

% no_attack(Qs, Q, I): Q is the placement of the queen in row n
% Qs are placements of queens in rows n+I, n+I+1, ...
% Queen in row n does not attack any of the queens described by Qs.
no_attack([], _, _).
no_attack([X|Xs], Y, I):-
    no_threat(X, Y, I),
    J is I+1, no_attack(Xs, Y, J).

% Queens placed in column X of row n, and in column Y of row n+I
% do not attack each other
no_threat(X, Y, I) :-
    /* X =\= Y, */
    Y =\= X-I, Y =\= X+I.

```

## Using coroutining for fusing generate and test

- Add blocking conditions to the test for `no_threat`:

```
:- block no_threat_b(-,?,?), no_threat_b(?,-?,?).
```

```
% Queens placed in column X of row n, and in column Y of row n+I  
% do not attack each other. Wakes up when all args are instantiated.
```

```
no_threat_b(X, Y, I) :-
```

```
    /* X =\= Y, */ Y =\= X-I, Y =\= X+I.
```

- `no_attack_b` is the same as `no_attack`, but using `no_threat_b`,  
`safe_b` is the same as `safe`, but using `no_attack_b`
- “First” test, then generate:

```
queens_tg(N, Qs):-
```

```
    length(Qs, N),           Qs is a list of N vars
```

```
    safe_b(Qs),             set up blocked no_threat checks
```

```
    findall(I, between(1, N, I), L),
```

```
    permutation(L, Qs). When Qsi is bound, it is checked  
                        immediately against queens placed earlier
```

- The ratio of runtimes of `gt` and `tg` variants

```
N → ratio: 8 → 4, 9 → 8, 10 → 16, 11 → 32, 12 → 69, 13 → 154
```

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## About CLP in general

- The CLP( $\mathcal{X}$ ) schema

Prolog or some other prog. language, e.g. C++

+

“strong” reasoning capabilities on a restricted domain  $\mathcal{X}$  involving specific constraint (relation) and function symbols.

- Examples for the domain  $\mathcal{X}$ :

- $\mathcal{X} = \mathbb{Q}$  or  $\mathbb{R}$  (rationals or reals) – cf. SICStus libraries `clpq`, `clpr`  
**constraints**: linear equalities and inequalities  
**reasoning techniques**: Gauß elimination and the simplex method
- $\mathcal{X} = \text{FD}$  ( Finite Domains, e.g. of integers) – `library(clpfd)`  
**constraints**: various arithmetic, logic, and combinatorial relationships  
**reasoning techniques**: methods developed for solving Constraint Satisfaction Problems (CSPs), a branch of Artificial Intelligence (AI)
- $\mathcal{X} = \text{B}$  (Boole values `true` and `false`, or 1 and 0) – `library(clpb)`  
**constraints**: relations of propositional calculus (negation, conj., etc.)  
**reasoning techniques**: AI methods developed for solving SAT (propositional satisfiability) problems, e.g. binary Decision Diagrams.

# Constraint Satisfaction Problems

- A CSP task is a triple  $(X, D, C)$ 
  - $X = \langle x_1, \dots, x_n \rangle$  – variables
  - $D = \langle D_1, \dots, D_n \rangle$  – domains, i.e. nonempty finite sets
  - variable  $x_i$  can take its values from the set  $D_i$ , called the domain of  $x_i$
  - $C$  is the set of constraints (primitive relations), with arguments from  $X$  (e.g.  $C \ni c = r(x_1, x_3)$ ,  $r \subseteq D_1 \times D_3$ )
- The solution of a CSP task: the assignment, to each  $x_i$ , of a value  $v_i \in D_i$  in such a way that all  $c \in C$  constraints are simultaneously satisfied.
- **Definition:** A value  $d_i \in D_i$  of a variable  $x_i$  is **infeasible** w.r.t. the constraint  $c = r(\dots, x_i, \dots)$ , if no assignment can be found for the remaining variables of  $c$ , which, taken with  $d_i$ , satisfies  $c$ .
- **Proposition:** removing an infeasible value (domain pruning) does not affect the set of solutions.
- **Definition:** A constraint is *arc-consistent*, if no variable domain contains an infeasible value. A CSP task is *arc-consistent*, if all constraints in it are arc-consistent. (A task with binary constraints only can be seen as a graph: var  $\Rightarrow$  node, relation  $\Rightarrow$  arc – hence the name arc-consistency.)
- Arc-consistency can be ensured by repeated domain pruning.

# The process of solving CSP (CLPFD) problems

- Modelling – transforming the problem to a CSP
  - defining the variables and their domains
  - identifying the constraints between the variables
- Implementation – the structure of the CSP program
  - Set up variable domains:  $N \text{ in } \{1,2,3\}$ ,  $\text{domain}([X,Y], 1, 5)$ .
  - Post constraints. Preferably, no choice points should be created.
  - Label the variables, i.e. systematically explore all variable settings.
- Optimisation, e.g. **redundant** constraints, labeling heuristics, constructive disjunction, shaving.
- Generate-and-test (G&T) vs. the CSP (constrain-and-generate) approach (4-queens example)
  - G&T:  $?- \text{between}(1,4,A), \text{between}(1,4,B), \text{between}(1,4,C), \dots$   
 $A \neq B, A \neq B+1, A \neq B-1, A \neq C+2, \dots$
  - CSP:  $?- L=[A,B,C,D], \text{domain}(L,1,4),$   
 $A \neq B, A \neq B+1, A \neq B-1, A \neq C+2, \dots, \text{labeling}([ff],L)$ .

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## library(clpfd) – an overview

- **Domain:** a finite set of integers (allowing the restricted use of infinite intervals for convenience)
- **Constraints:**
  - membership, e.g. `X in 1..5`  $(1 \leq X \leq 5)$
  - arithmetic, e.g. `X #< Y+1`  $(X < Y + 1)$
  - reified, e.g. `X#<Y+5 #<=> B` (B is the truth value of  $X < Y + 5$ )
  - propositional, e.g. `B1 #\ / B2`  
(at least one of the two Boolean values B1 and B2 is true)
  - combinatorial, e.g. `all_distinct([V1,V2,...])`  
(variables [V1,V2,...] are pairwise different)
  - user-defined, e.g. indexicals and global constraints



## Some important constraints

- Arithmetic formula constraints:  $Expr \text{ Relop } Expr$  where

$Expr ::= \langle \text{integer} \rangle \mid \langle \text{variable} \rangle$   
 $\mid - Expr \mid Expr + Expr \mid Expr - Expr \mid Expr * Expr$   
 $\mid Expr / Expr \quad \quad \quad \% \text{ integer division}$   
 $\mid Expr \text{ mod } Expr \mid Expr \text{ rem } Expr \quad \% \text{ differ only for ints } < 0$   
 $\mid \min(Expr, Expr) \mid \max(Expr, Expr) \mid \text{abs}(Expr)$

$RelOp ::= \# = \mid \# \backslash = \mid \# < \mid \# = < \mid \# > \mid \# > =$

- Global arithmetic constraints (global = having arbitrary number of args):

- $\text{sum}(+Xs, +RelOp, ?Value): \sum Xs \text{ Relop } Value.$
- $\text{scalar\_product}(+Coeffs, +Xs, +RelOp, ?Value[, +Options])$   
(last arg. optional):  $\sum (Coeffs * Xs) \text{ Relop } Value.$
- $\text{minimum}(?V, +Xs), \text{maximum}(?V, +Xs): V$  is the min/max of  $Xs$ .

- Some combinatorial (global) constraints:

- $\text{all\_different}([X_1, \dots, X_n]):$  same as  $X_i \# \backslash = X_j$  for all  $0 < i < j \leq n$ .
- $\text{all\_distinct}([X_1, \dots, X_n]):$  same as  $\text{all\_different}$ , but guarantees **arc-consistency** between the  $n$  variables.

$\mid ?- L=[A,B,C], \text{domain}(L, 1, 2), \text{all\_different}(L). \implies A \text{ in } 1..2, \dots$

$\mid ?- L=[A,B,C], \text{domain}(L, 1, 2), \text{all\_distinct}(L). \implies \text{no}$

# Labeling

- Labeling: search by systematic assignment of feasible values to vars.
- `indomain(?Var)`: `Var` is assigned feasible values in ascending order.
- `labeling(+Options, +Vars)`: assigns all `Vars`. Some useful options:
  - **Variable selection**: Select for assignment ...
    - `leftmost` (default) – the leftmost unbound variable;
    - `ff` (first-fail) – the leftmost variable with the smallest domain;
    - `ffc` – the leftmost variable with the smallest domain which participates in most constraints;
    - `min/max` – the leftmost variable with the smallest lower bound/largest upper bound;
    - `variable(SEL)` – the var. prescribed by the user through `SEL`.
  - **Direction**: `up`(default)/`down` – assign in ascending/descending order.
  - **Value selection**: Create a choice-point distinguishing between ...
    - `step` (default) – the lower/upper bound and the rest (2-way);
    - `enum` – all values in the domain ( $n$ -way,  $n$  is the domain size);
    - `bisect` (domain splitting) – the two halves of the domain (2-way);
    - `value(ENUM)` – as prescribed by the user through `ENUM`.

## The implementation of CLPFD

- The main data structure: the **backtrackable constraint store** – maps variables to their domains.
- **Simple** constraints: e.g.  $X \text{ in } 1..10$  or  $X \#< 10$  just modify the store.
- **Composite** constraints are implemented as **daemons**, which keep removing **infeasible** values from argument domains, e.g., given the store  $X \text{ in } 1..6, Y \text{ in } \{1,6,7,8,9\}$  the daemon for  $X+5 \# = Y$  removes  $\implies 5, 6$  from  $X$ ;  $1$  from  $Y$ , producing:  $X \text{ in } 1..4, Y \text{ in } 6..9$ . (\*)
- Composite constraints can provide reasoning of different strengths:
  - **domain-consistency** ( $\equiv$  arc-cons.) – removes **all** infeasible values, e.g. after (\*),  $Y \# \neq 7$  removes  $\implies 2$  from  $X$ . (\*\*)  
(Cost: **exponential** in the number of variables.)
  - **bound-consistency** – (repeatedly) removes infeasible **bounds** only, i.e. *middle* elements, as in (\*\*), are not removed. E.g. after (\*),  $Y \#< 8 \implies$  remove  $4$  and then  $3$ , the upper bounds of  $X$ , so that all bounds become feasible. (Cost: **linear** in the # of vars)
- A daemon may **exit** (die), when the constraint it represents is **entailed** by (follows from) the constraint store; e.g.  $X \#< Y$  may exit if the store contains:  $X \text{ in } 1..5$  and  $Y \text{ in } 7..9$ .

## The implementation of CLPFD (contd.)

- To execute a constraint  $C$ :
  - Transform  $C$  (at compile time) to a series of primitive constraints, e.g.  $X*X \#> Y \Rightarrow X*X \# = Z, Z \#> Y$  (formula constraints only).
  - Post  $C$  (or each of the primitive constraints obtained from  $C$ ):
    - execute immediately (e.g.  $x \#< 3$ ); or
    - create a daemon for  $C$ :
      - tell the constraint engine when to wake me up (**activation conditions**)
      - prune** the domains
      - until** the **termination condition** becomes true **do**
      - go to sleep (wait for activation)
      - prune** the domains
      - enduntil**
- An **activation condition**: the domain of a variable  $x$  changes in SOME way: SOME = any; lower/upper bound change; instantiation; ...
- The **termination condition** is constraint specific; **earliest**: when the constraint is entailed; **latest**: when all its variables are instantiated.
- `| ?- assert(clpfd:full_answer).`  
makes SICStus Prolog show the non-terminated constraints.

## The implementation of some constraints

- $A \# \neq B$  (arc-consistent)
  - **Activation:** when  $A$  or  $B$  is instantiated.
  - **Pruning:** remove the value of the instantiated variable from the domain of the other.
  - **Termination:** when  $A$  or  $B$  is instantiated.
- $A \# < B$  (arc-consistent)
  - **Activation:** when  $\min(A)$  (the lower bound of  $A$ ) or  $\max(B)$  (the upper bound of  $B$ ) changes.
  - **Pruning:**  
remove from the domain of  $A$  all  $x$ 's such that  $x \geq \max(B)$ ,  
remove from the domain of  $B$  all  $y$ 's such that  $y \leq \min(A)$ .
  - **Termination:** if one of the variables  $A$  and  $B$  becomes instantiated (could be improved).

## The implementation of some constraints (contd.)

- $X+Y \#< T$  (bound-consistent)
  - **Activation:** when the lower or upper bound changes for any of the variables  $X$ ,  $Y$ ,  $T$ .
  - **Pruning:**  
narrow the domain of  $T$  to  $(\min(X)+\min(Y))..(\max(X)+\max(Y))$ ;  
narrow the domain of  $X$  to  $(\min(T)-\max(Y))..(\max(T)-\min(Y))$ ;  
narrow the domain of  $Y$  to  $(\min(T)-\max(X))..(\max(T)-\min(X))$ .
  - **Termination:** if all three variables are instantiated.
- $\text{all\_distinct}([A_1, \dots])$  (arc-consistent)
  - **Activation:** at any domain change of any variable.
  - **Pruning:** remove all infeasible values from the domains of all variables (using an algorithm based on maximal paths in bipartite graphs).
  - **Termination:** when at most one of the variables is uninstantiated.

## Consistency levels guaranteed by SICStus Prolog

- Membership constraints (trivially) ensure arc-consistency.
- Linear arithmetic constraints ensure at least bound-consistency.
- Nonlinear arith. constraints do not guarantee bound-consistency.
- For all constraints, when all the variables of the constraint are bound, the constraint is guaranteed to deliver the correct result (success or failure).

```
| ?- X in {4,9}, Y in {2,3}, Z #= X-Y.    => Z in 1..7 ?
                                         => Bound consistent
| ?- X in {4,9}, Z #= X-2.                => Z in {2}\/{7} ?
                                         => Domain consistent
| ?- X in {4,9}, Y in {2,3},
    scalar_product([1,-1], [X,Y], #=, Z, [consistency(domain)]).
                                         => Z in (1..2)\/(6..7) ?
                                         => Domain consistent
| ?- domain([X,Y], -9,9), X*X+2*X+1 #= Y. => X in -4..4, Y in -7..9 ?
                                         => Not even bound consistent
| ?- domain([X,Y], -9,9), (X+1)*(X+1)#=Y. => X in -4..2, Y in 0..9 ?
                                         => Bound consistent
```

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## Reified constraints – an introduction

- A **speculative** solution for counting the positive members of a list:

```
% pcount0(L, N): L has N positive elements.
pcount0([X|L], N) :- ( X #> 0, N1 #= N-1, pcount0(L, N1)
                      ; X #=< 0, pcount0(L, N)
                      ).
pcount0([], 0).
```

```
| ?- pcount0([A,B], 0). => A in inf..0, B in inf..0 ? ; no
| ?- pcount0([A,B], 1). => A in 1..sup, B in inf..0 ? ;
                        => B in 1..sup, A in inf..0 ? ; no
```

- **Speculative disjunction**: ChPs made while posting constraints.

```
| ?- length(L, 20), pcount0(L, 0).      takes ~ 15 sec!
```

- With **reification** a non-speculative solution is possible (no ChPs):

```
% pcount1(L, N): L has N positive elements.
pcount1([X|Xs], N) :-
    (X #> 0) #<=> B,          % (X > 0) iff (B = 1)
    N1 #= N-B, pcount1(Xs, N1).
pcount1([], 0).
```

## Reification – obtaining the truth value of a constraint

- The reification of an  $n$ -ary constraint  $C = r(x_1, \dots, x_n)$ 
  - is a constraint  $r_{reif}(x_1, \dots, x_n, b)$  defined as  $r(x_1, \dots, x_n) \Leftrightarrow b = 1$ , where  $b$  is a Boolean (0-1) variable;
  - denoted by  $C \# \Leftrightarrow B$
  - this means that  $B \text{ in } 0..1$  and  $B$  is 1 iff  $C$  is true.
- A reified constraint is very much like an arithmetic constraint, and sometimes can be replaced by an arithmetic one, e.g.
  - $(X \# > 0) \# \Leftrightarrow B$  means:  $B$  is the truth value of  $x > 0$ .
  - If  $x$  has the domain  $0..9$ , then  $B \# = (X+9)/10$  is the **very same** constraint, just implemented differently
- Which constraints can be reified?
  - Arithmetic formula constraints ( $\# =$ ,  $\# <$ , etc.)
  - Membership constraints ( $\text{in}$ )
- Global constraints (e.g. `all_distinct/1`, `sum/3`) cannot be reified.

## Executing reified constraints

- The execution of  $C \# \Leftarrow B$  requires the following actions:
  - When  $B$  is **instantiated**:
    - if  $B=1$ , **post**  $C$ , if  $B=0$ , **post**  $\neg C$ ,
  - When  $C$  is **entailed** (i.e. the store implies  $C$ ), **set**  $B$  to 1.
  - When  $C$  is **disentailed** (i.e.  $\neg C$  is entailed), **set**  $B$  to 0.
- The above three action types are delegated to three daemons.
- Detecting entailment can be done with different levels of precision:
  - A reified membership constraint  $C$  detects **domain-entailment**, i.e.  $B$  is set as soon as  $C$  is a consequence of the store
  - A linear arithmetic constraint  $C$  is guaranteed to detect **bound-entailment**, i.e.  $B$  is set as soon as  $C$  is a consequence of the interval closure of the store. (The interval closure is obtained by removing the holes in the domains.) E.g. the store below implies the constraint  $X+Y \neq Z$  (odd+even  $\neq$  even), but its interval closure does not:
 

| ?- X in{1,3}, Y in{2,4}, Z in{2,4}, X+Y#=\Z#<=>B.  $\implies$  B in 0..1,...
- When a constraint becomes ground, its (dis)entailment is detected

## Propositional constraints

- Propositional connectives allowed by SICStus Prolog CLPFD:

#\ Q	negation	op(710, fy, #\ ).
P #/\ Q	conjunction	op(720, yfx, #/\ ).
P #\ Q	exclusive or	op(730, yfx, #\ ).
P #\/ Q	disjunction	op(740, yfx, #\/ ).
P #=> Q	implication	op(750, xfy, #=> ).
Q #<= P	implication	op(750, yfx, #<= ).
P #<=> Q	equivalence	op(760, yfx, #<=> ).

- The operand of a propositional constraint can be
  - a variable B, whose domain automatically becomes 0..1; or
  - an integer (0 or 1); or
  - a reifiable constraint; or, recursively
  - a propositional constraint.
- The propositional constraints are
  - built from vars, ints and reifiable constraints using above operators;
  - executed by transforming them to arith. and reified constraints, e.g.
 
$$(X\#>0) \#\/ (Y\#<5). \iff (X\#>0)\#<=>B1, (Y\#<5)\#<=>B2, B1+B2\#>0.$$

## N-queens – a CLPFD variant

- Recall: the Prolog list  $[Q_1, \dots, Q_N]$  represents the placement: row  $i$  contains a queen in column  $Q_i$ .

```
% queens(+Lab, +N, ?Q): Q is a safe placement i.e. no two queens
% attack each other, obtained using the labeling options Lab
```

```
queens(Lab, N, Qs) :-
    length(Qs, N), domain(Qs, 1, N),
    safe(Qs), labeling(Lab, Qs).
```

```
% safe(Qs): List Qs describes a safe placement of queens.
```

```
safe([]).
safe([Q|Qs]):- no_attack(Qs, Q, 1), safe(Qs).
```

```
% no_attack(Qs, Q, I): Q is the placement of the queen in row n
```

```
% Qs are placements of queens in rows n+I, n+I+1, ...
```

```
% Queen in row n does not attack any of the queens described by Qs.
```

```
no_attack([],_,_).
```

```
no_attack([X|Xs], Y, I):-
```

```
    no_threat(X, Y, I), J is I+1, no_attack(Xs, Y, J).
```

```
% Queens in row n, col X and in row n+I, col Y do not attack each other.
```

```
no_threat(X, Y, I) :- Y #\= X, Y #\= X-I, Y #\= X+I.
```

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## User-defined constraints

- What should be specified when defining a new constraint:
  - Activation conditions: when should it wake up
  - Pruning: how should it prune the domains of its variables
  - Termination conditions: when should it exit
- Additional issues for reifiable constraints:
  - How should its negation be posted?
  - How to decide its entailment?
  - How to decide its disentanglement (the entailment of its negation)?

## Possibilities for defining constraints

- Global constraints
  - Arbitrary number of arguments (variable lists as arguments)
  - Activation, pruning, termination is specified by arbitrary Prolog code.
  - No specific support for reification
- FD predicates
  - Fixed number of arguments
  - Support for reification
  - Pruning and entailment is specified by so called indexicals (Pascal van Hentenryck), using a set-valued functional language.
  - Activation and termination conditions deduced automatically from the indexicals.

## FD predicates – a simple example

An FD predicate ' $x < y$ ' (X,Y), implementing the constraint  $x \# < Y$

- FD clause with neck +: – the prunings for the constraint itself:

```
'x=<y' (X,Y) +:
    X in inf..max(Y),      % intersect X with inf..max(Y)
    Y in min(X)..sup.     % intersect Y with min(X)..sup
```

- FD clause with neck -: – the prunings for the *negated* constraint:

```
'x=<y' (X,Y) -:
    X in (min(Y)+1)..sup,
    Y in inf..(max(X)-1).
```

- FD clause with neck +? – the entailment condition:

```
'x=<y' (X,Y) +?          % X<Y is entailed if the domain of X
    X in inf..min(Y).    % becomes a subset of inf..min(Y)
```

- FD clause with neck -? – the entailment condition for the negation:

```
'x=<y' (X,Y) -?          % Negation X > Y is entailed when X's
    X in (max(Y)+1)..sup. % domain is a subset of (max(Y)+1)..sup
```

## Defining global constraints

- The constraint is written as two pieces of Prolog code
  - The start-up code
    - an ordinary predicate with arbitrary arguments
    - should call `fd_global/3` to set up the constraint
  - The wake-up code
    - written as a clause (of a hook predicate) to be called by SICStus at activation
    - should return the domain prunings
    - should decide whether the constraint can exit (with success or failure) or should fall asleep and keep pruning later

## Global constraints – a simple example

Defining the constraint  $x \#=< Y$  as a global constraint

- The start-up code

```
lseq(X, Y) :-
    fd_global(lseq(X,Y), void, [min(X),max(Y)]).
    %           ~~~~~
    %           ~~~~~
    %           ~~~~~
```

constraint name  
initial state  
wake-up conditions

- The wake-up code

```
:- multifile clpfd:dispatch_global/4.
:- discontinuous clpfd:dispatch_global/4.
clpfd:dispatch_global(lseq(X,Y), St, St, Actions) :-
    dispatch_lseq(X, Y, Actions).

dispatch_lseq(X, Y, Actions) :-
    fd_min(X, MinX), fd_max(X, MaxX), % get min of X in MinX, etc.
    fd_min(Y, MinY), fd_max(Y, MaxY),
    ( number(MaxX), number(MinY), MaxX =< MinY
    -> Actions = [exit]
    ;   Actions = [X in inf..MaxY, Y in MinX..sup]
    ).
```

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## Shaving – a special case of constructive disjunction

- Base idea: remove  $v$  from  $X$  if setting  $X = v$  fails immediately, i.e. without labeling
- Shaving a single value  $v$  off the domain of  $x$  is similar to a constructive disjunction  $(X = v) \vee (X \neq v)$  w.r.t.  $X$

```
shave_value(V, X) :-
    \+ X = V, !, X in \{V}.
shave_value(_, _).
```

- Shaving all values in  $X$ 's domain  $\{v_1, \dots, v_n\}$  is the same as performing a constructive disjunction for  $(X = v_1) \vee \dots \vee (X = v_n)$  w.r.t.  $X$

```
shave_all(X) :-
    fd_set(X, FD), fdset_to_list(FD, L),
    findall(X, member(X,L), Vs),
    list_to_fdset(Vs, FD1), X in_set FD1.
```

- Shaving may be applied repeatedly, until a fixpoint (may not pay off)
- Shaving is normally done during labeling. To reduce its costs, one may:
  - limit it to variables with small enough domain (e.g. of size 2)
  - perform it only after each  $n^{\text{th}}$  labelling step (requires global variables)

## An example for shaving, from a kakuro puzzle

- Kakuro puzzle: like a crossword, but with distinct digits 1–9 instead of letters; sums of digits are given as clues.
 

```
% L is a list of N distinct digits 1..9 with a sum Sum.
kakuro(N, L, Sum) :-
    length(L, N), domain(L, 1, 9), all_distinct(L), sum(L,#=,Sum).
```
- Example: a 4 letter “word” [A,B,C,D], the sum is 23, domains:
 

```
sample_domains(L) :- L = [A,_,C,D], A in {5,9}, C in {6,8,9}, D=4.
```
- Only B gets pruned: 4, because of all\_distinct, 9 because of sum
 

```
| ?- L=[A,B,C,D], kakuro(4, L, 23), sample_domains(L).
    => A in{5}\/{9}, B in(1..3)\/(5..8), C in{6}\/(8..9) ?
```
- Shaving 9 off c shows the value 9 for c is infeasible:
 

```
| ?- L=[A,B,C,D], kakuro(4, L, 23), sample_domains(L),
    shave_value(9,C). => ..., C in{6}\/{8} ?
```
- Shaving off the whole domain of B leaves just three values:
 

```
| ?- L=[A,B,C,D], kakuro(4, L, 23), sample_domains(L), shave_all(B).
    => ..., B in{2}\/{6}\/{8}, ... ?
```
- These two shaving operations happen to achieve domain consistency:
 

```
| ?- kakuro(4, L, 23), sample_domains(L), labeling([], L).
    => L = [5,6,8,4] ? ; L = [5,8,6,4] ? ; L = [9,2,8,4] ? ; no
```

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## The domino puzzle

- Consider a rectangle of size  $(n + 1) \times (n + 2)$  covered by a full set of  $n$ -dominoes with no overlaps and no holes.
- The set has tiles of size  $1 \times 2$ , marked with  $\{\langle i, j \rangle | 0 \leq i \leq j \leq n\}$
- Input: a rectangle filled with integers  $0..n$  (domino boundaries removed)
- The task is to reconstruct the domino boundaries<sup>13</sup>

```

% A puzzle (n=3):      % The (only) solution:  % The solution matrix:
-----
1  3  0  1  2      | 1 | 3  0 | 1 | 2 |      n  w  e  n  n
|  |-----|  |  |
3  2  . 0  1  3    | 3 | 2  0 | 1 | 3 |      s  w  e  s  s
|-----|-----|----|
3  3  0  0  1      | 3  3 | 0  0 | 1 |      w  e  w  e  n
|-----|-----|  |
2  2  1  2  . 0    | 2  2 | 1  2 | 0 |      w  e  w  e  s
-----

```

- The input: a matrix of integers, the solution: a matrix of atoms `n`, `w`, `s`, `e` (the given position is a northern, western, ... part of a domino piece)

<sup>13</sup>Red dots show the 3 possible placements of the mid-line of domino  $\langle 0, 2 \rangle$

## Modelling the domino puzzle

### Selecting the variables<sup>14</sup>

- Option a: A matrix of solution variables, each having a value which encodes  $n$ ,  $w$ ,  $s$ ,  $e$  – difficult to ensure that each domino is used once
- Option b: for each domino in the set have variable(s) pointing to its place on the board – makes difficult to describe the non-overlap constraint
- Solution 1: use both sets of variables, with constraints linking them
- Solution 2: Map each gap between (horiz. or vert.) adjacent numbers to a 0-1 variable, whose value is 1, say, iff it is the mid-line of a domino

### Selecting the constraints (for Solution 2):

- Let  $S_{yx}$  and  $E_{yx}$  be the variables for the southern and eastern boundaries of the matrix element in row  $y$ , column  $x$ .
- Non overlap constraint: the four boundaries of a matrix element sum up to 1, e.g. for the element in row 2, column 4:  $\text{sum}([S14, E23, S24, E24], \# =, 1)$
- All dominoes used: Of all the possible placements of each domino exactly one is used. E.g. for the domino  $\langle 0, 2 \rangle$  (see red dots on the previous slide):  $\text{sum}([E22, S34, E44], \# =, 1)$

<sup>14</sup>SICStus library('clpfd/examples/dominoes') contains a solution using the `geost/2` constraint.

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## What else is there in (SICStus) Prolog?

- Prolog features
  - Definite clause grammars,  
e.g. `expr -> term, ( "+" | "-" ), expr | ""` ).
  - “Traditional” built-in predicates,  
e.g. sorting, input/output, exception handling, etc.
- Constraints
  - Further constraint libraries in SICStus:
    - CLPB – booleans
    - CLPQ/CLPR – linear (in/dis)equalities on rationals/reals
    - Constraint Handling Rules: generic constraints,  
this package is also available for other host-languages, e.g. Java.
- Numerous other libraries

## Some applications of (constraint) logic programming

- Boeing Corp.: Connector Assembly Specifications Expert (CASEy) – an expert system that guides shop floor personnel in the correct usage of electrical process specifications.
- Windows NT: `\WINNT\SYSTEM32\NETCFG.DLL` contains a small Prolog interpreter handling the rules for network configuration.
- Experian (one of the largest credit rating companies): Prolog for checking credit scores. Experian bought Prologia, the Marseille Prolog company.
- IBM bought ILOG, the developer of many constraint algorithms (e.g. that in `all_distinct`); ILOG develops a constraint programming / optimization framework embedded in C++.
- IBM uses Prolog in the Watson deep Question-Answer system for parsing and matching English text